



Deep Image Description

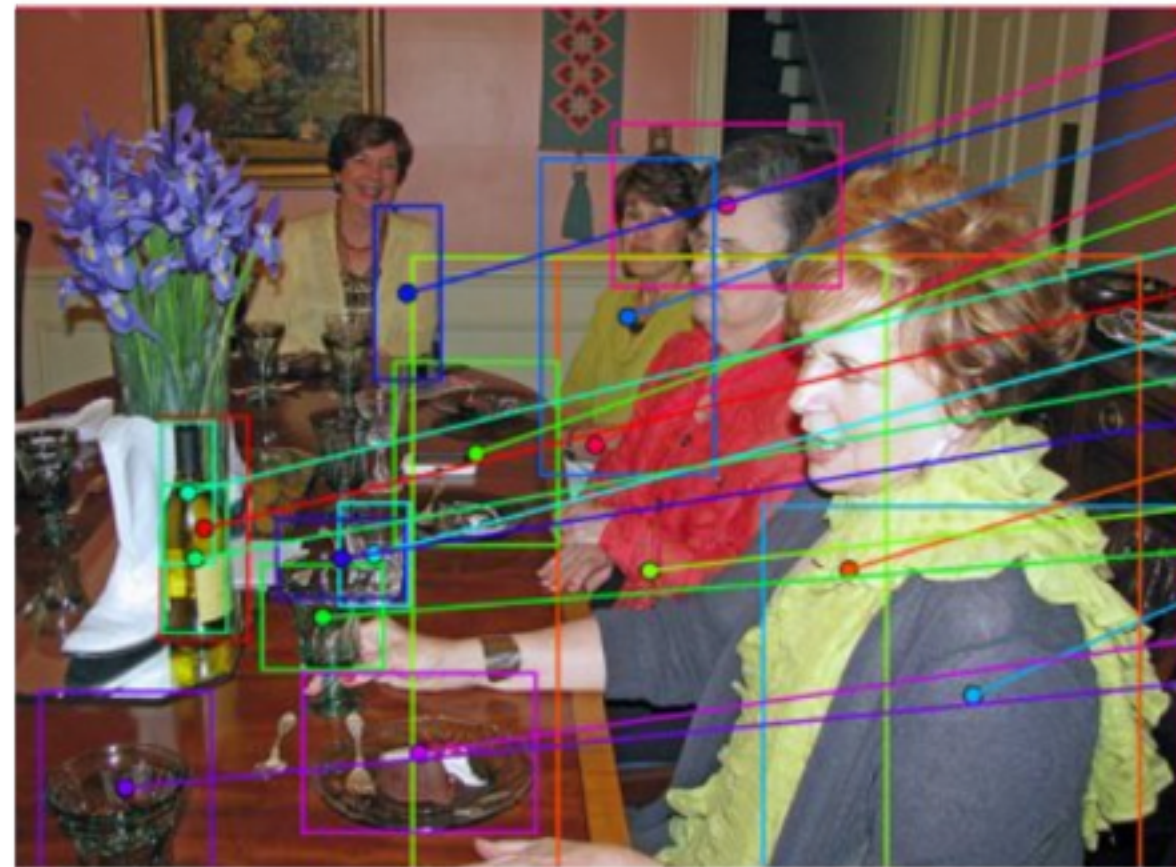
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Outline

- Generating descriptions for the **whole** images^{Vinyals2014, Karpathy2014}
- Generating descriptions for the **regional** images^{Karpathy2014}



guy sitting on chair tunes his guitar
orchestra conductor is conducting orchestra
man in black shirt is playing guitar



man
yellow
young man
group
kitchen
bottles of wine
wine bottles
glasses
bottle
table with wine glasses
woman
people
glass vases
these different types
chocolate cake
glass of wine

Generating descriptions for the **whole** images



"girl in pink dress is jumping in air."



"black and white dog jumps over bar."



"young girl in pink shirt is swinging on swing."



"man in blue wetsuit is surfing on wave."



"little girl is eating piece of cake."



"baseball player is throwing ball in game."

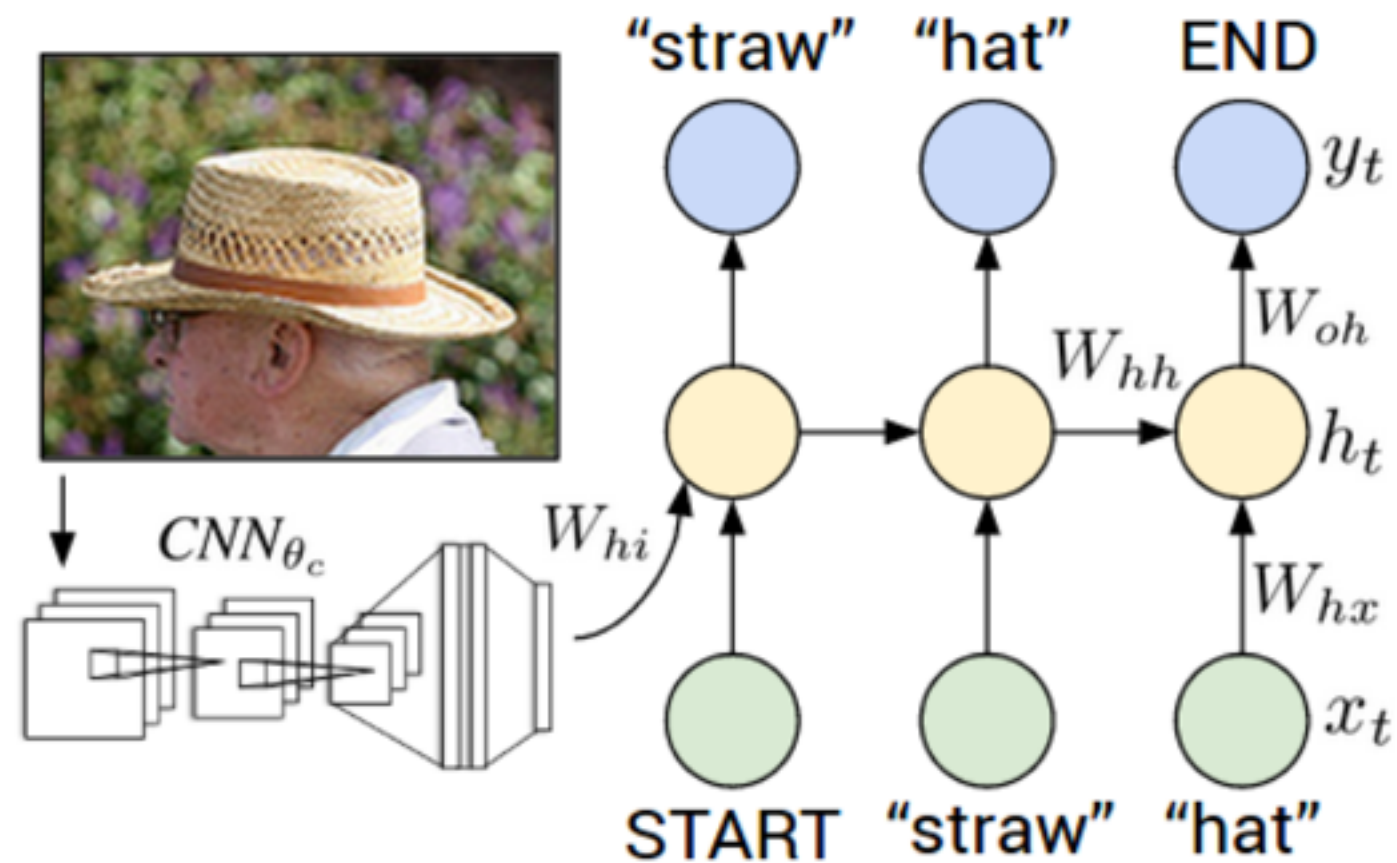


"woman is holding bunch of bananas."



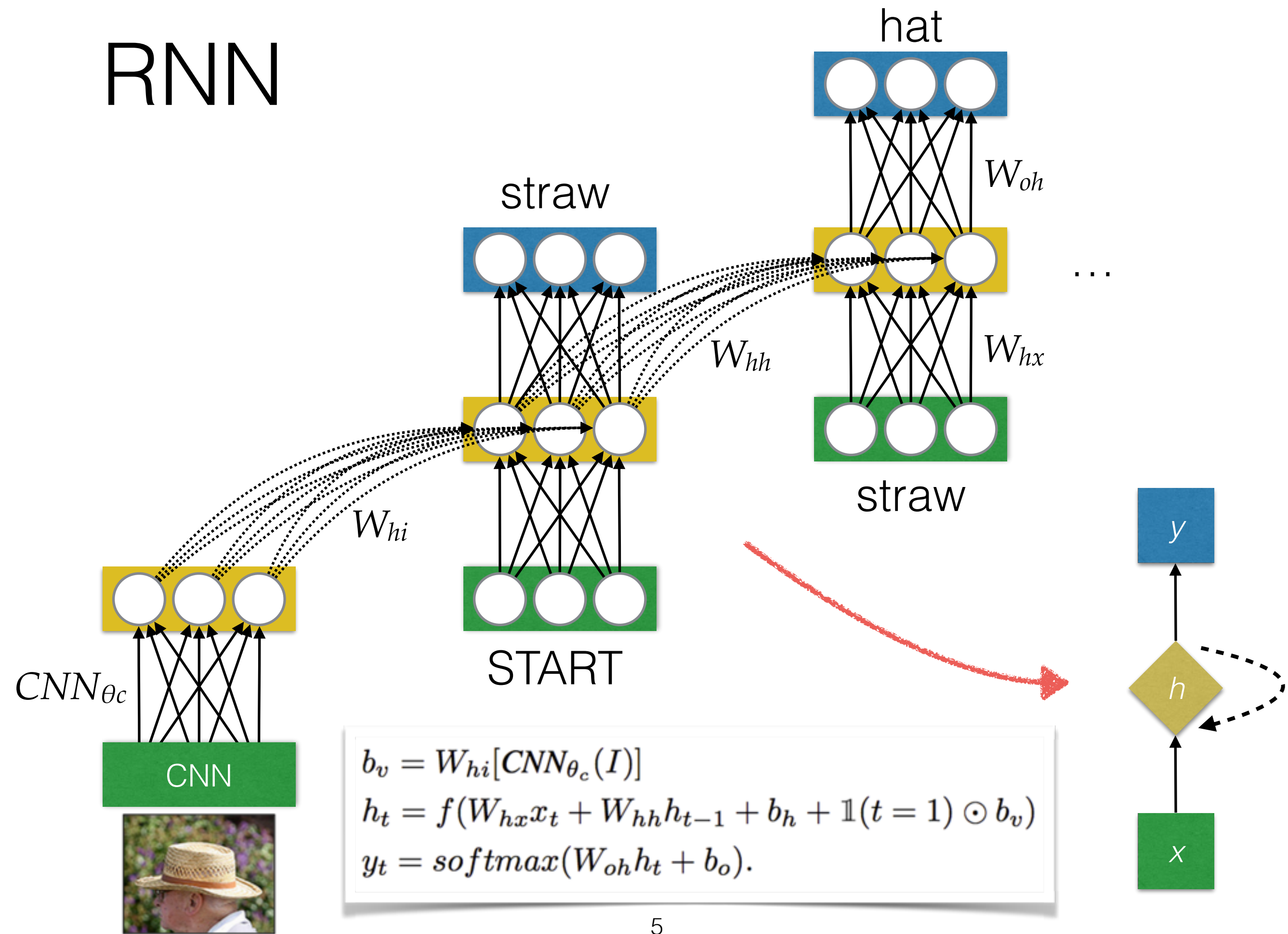
"black cat is sitting on top of suitcase."

Predictive Model

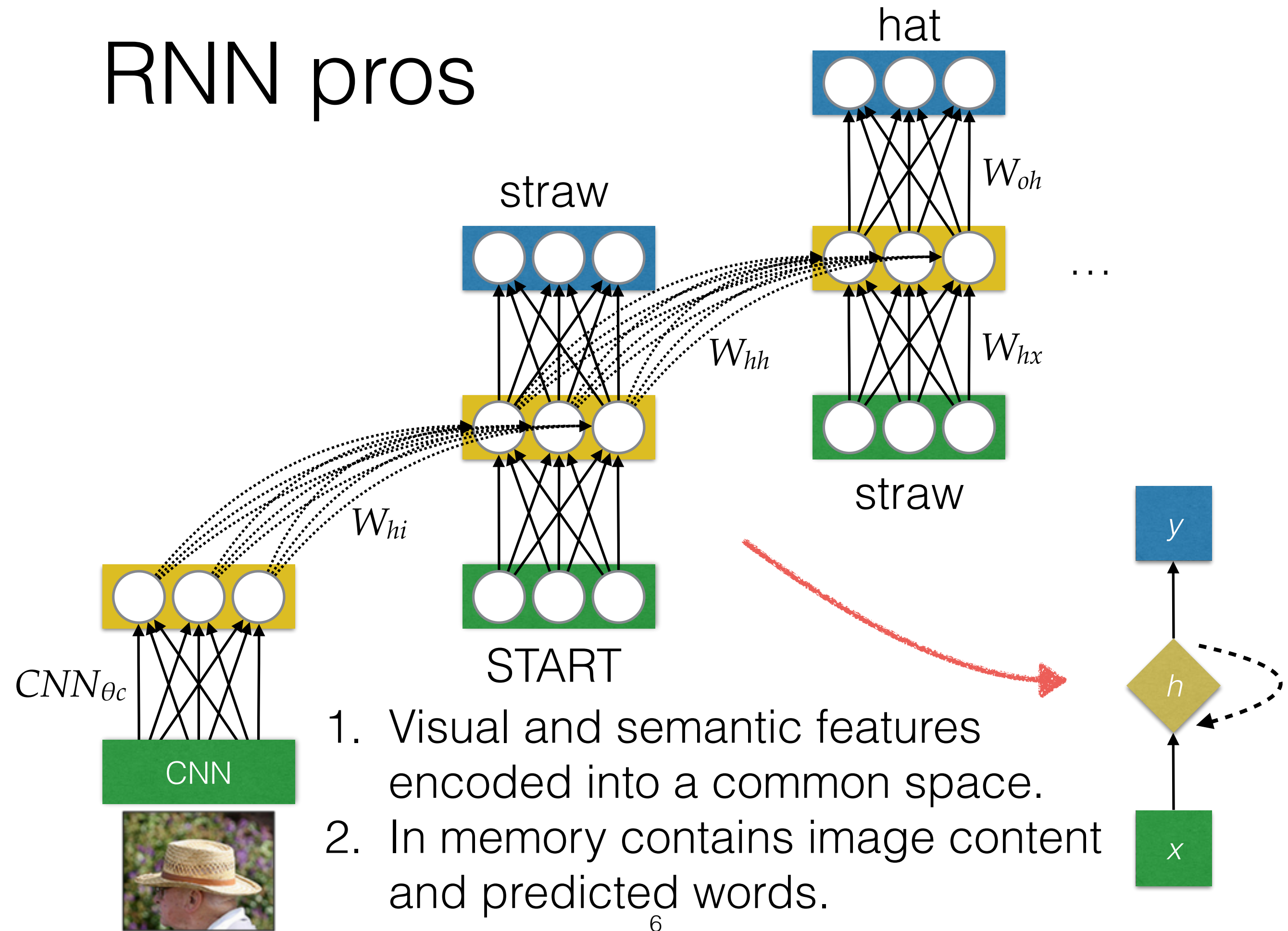


$$f(s | v; \Theta) = p(s_1 | v, s_0) p(s_2 | v, s_0, s_1) \cdots p(s_T | v, s_0, \dots, s_{T-1})$$

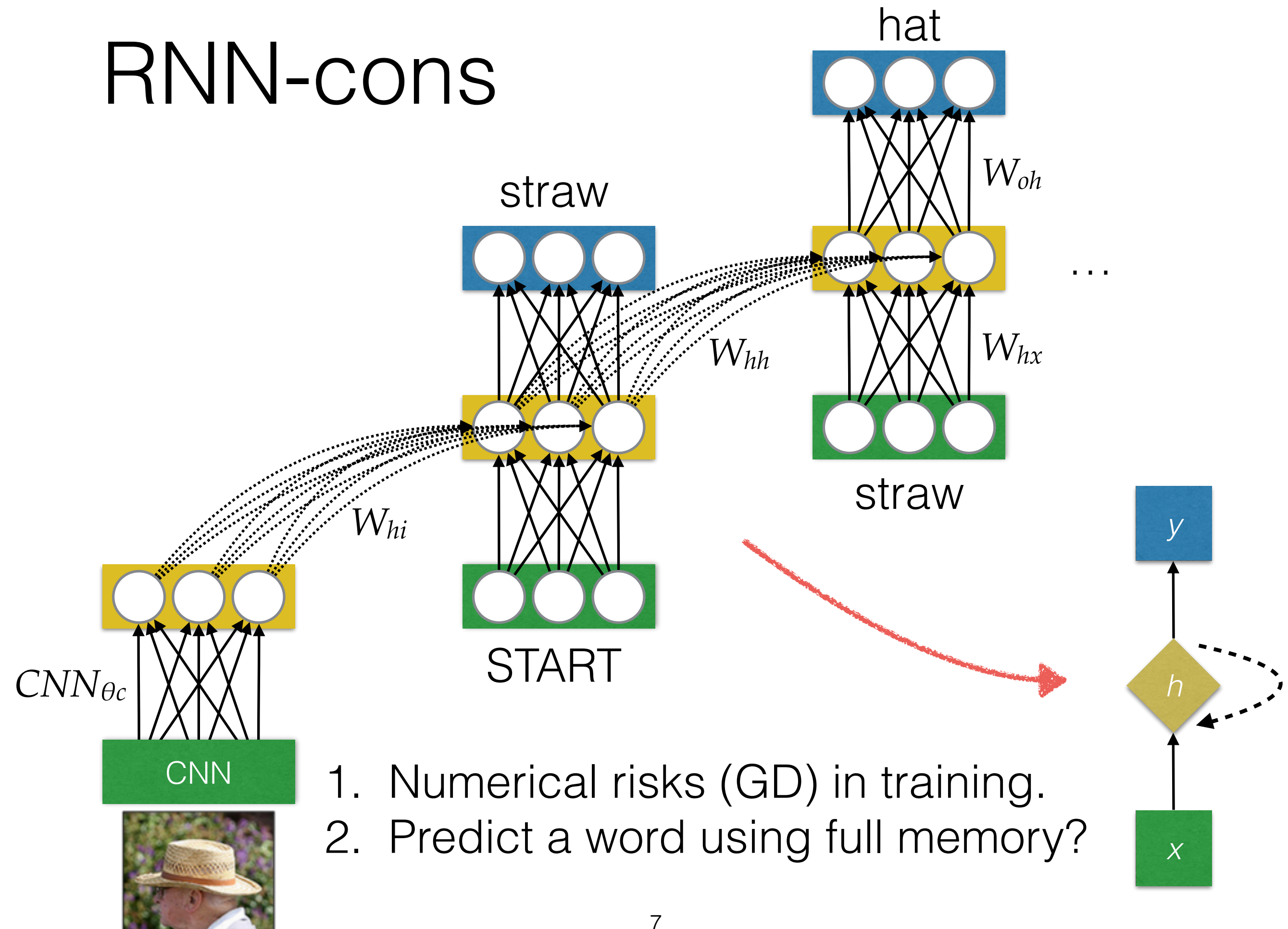
RNN



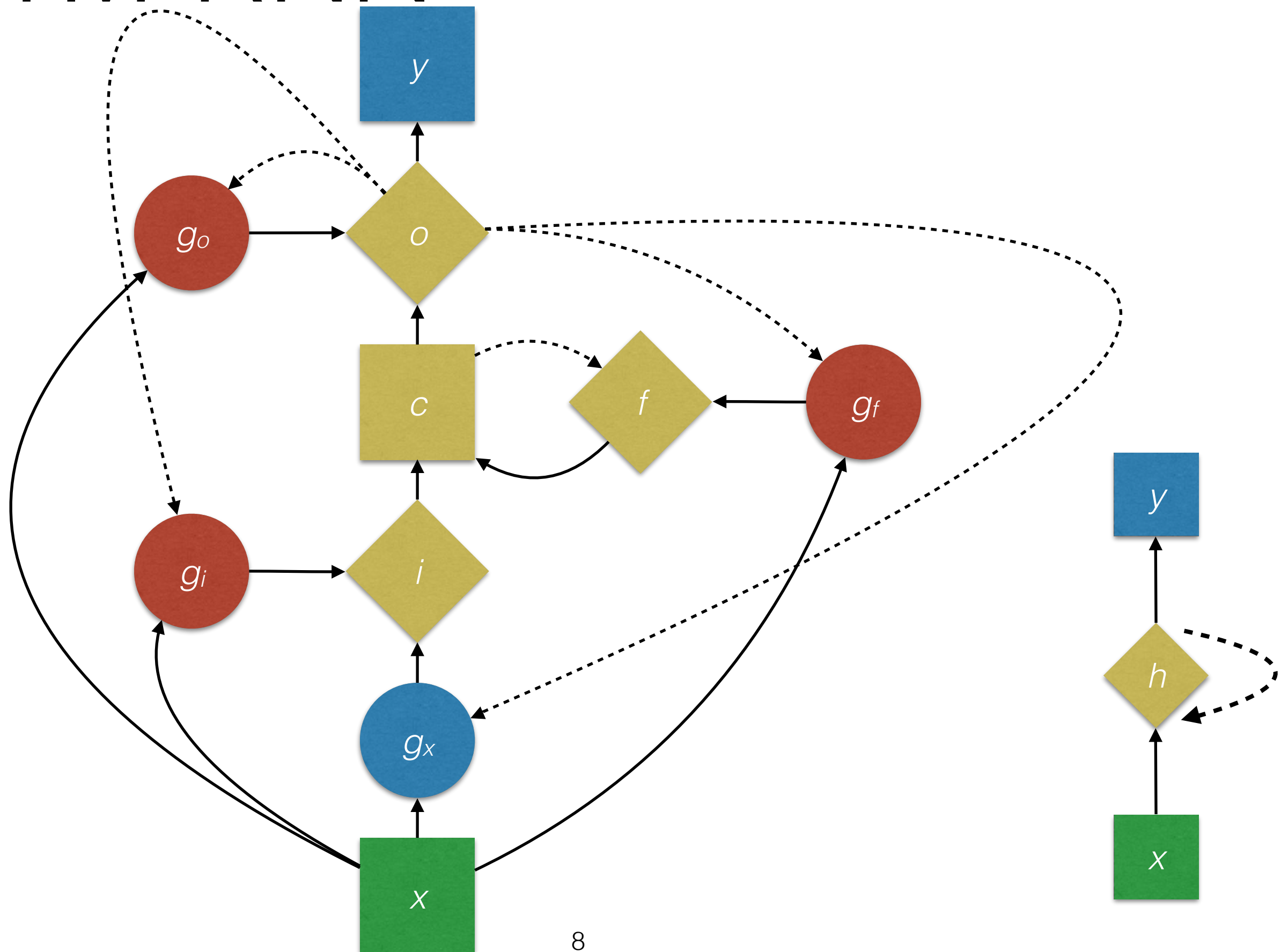
RNN pros



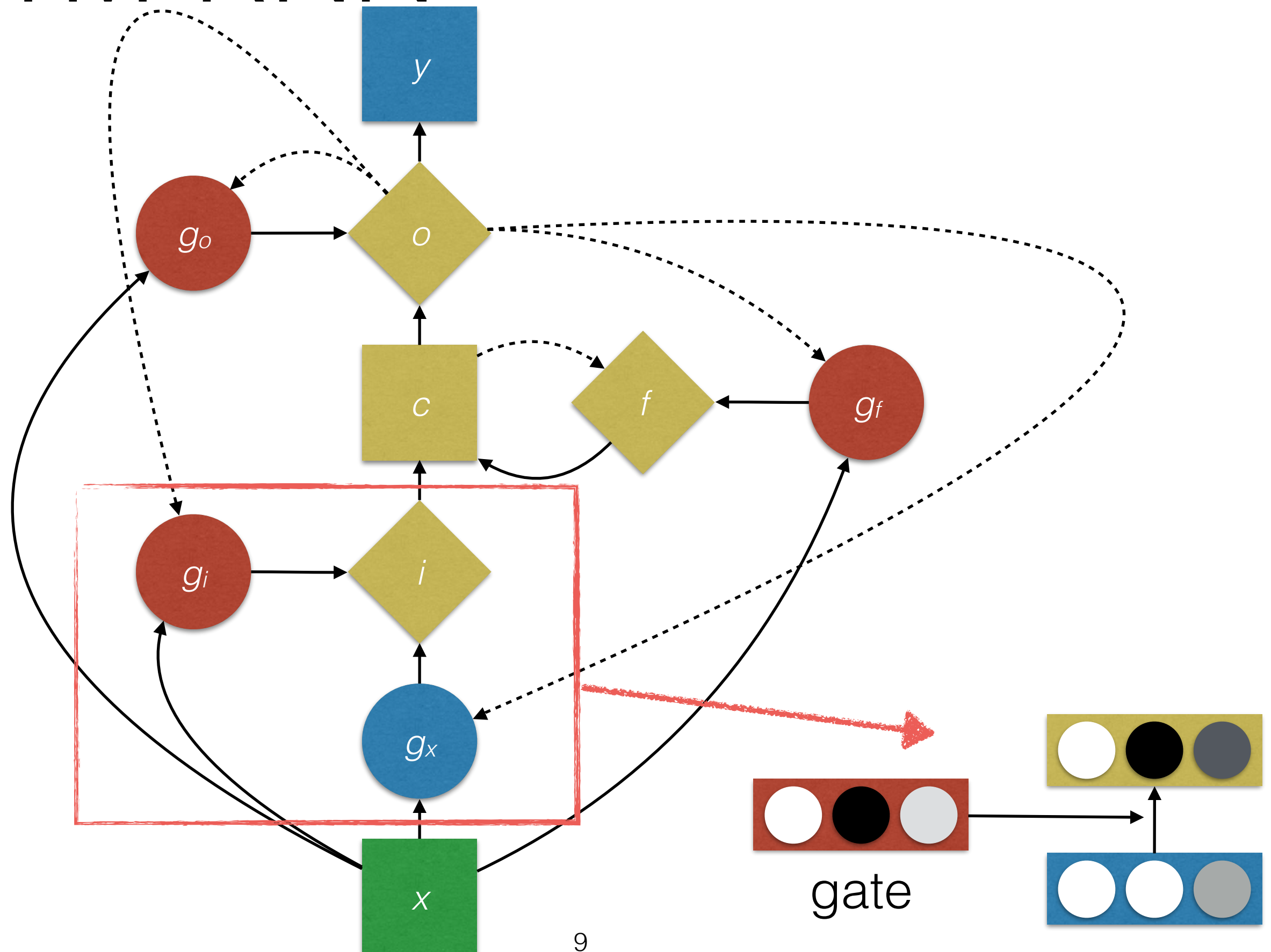
RNN-cons



LSTM-RNN



LSTM-RNN



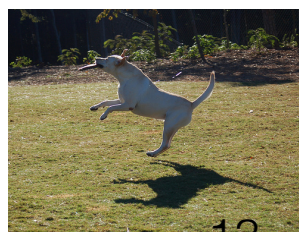
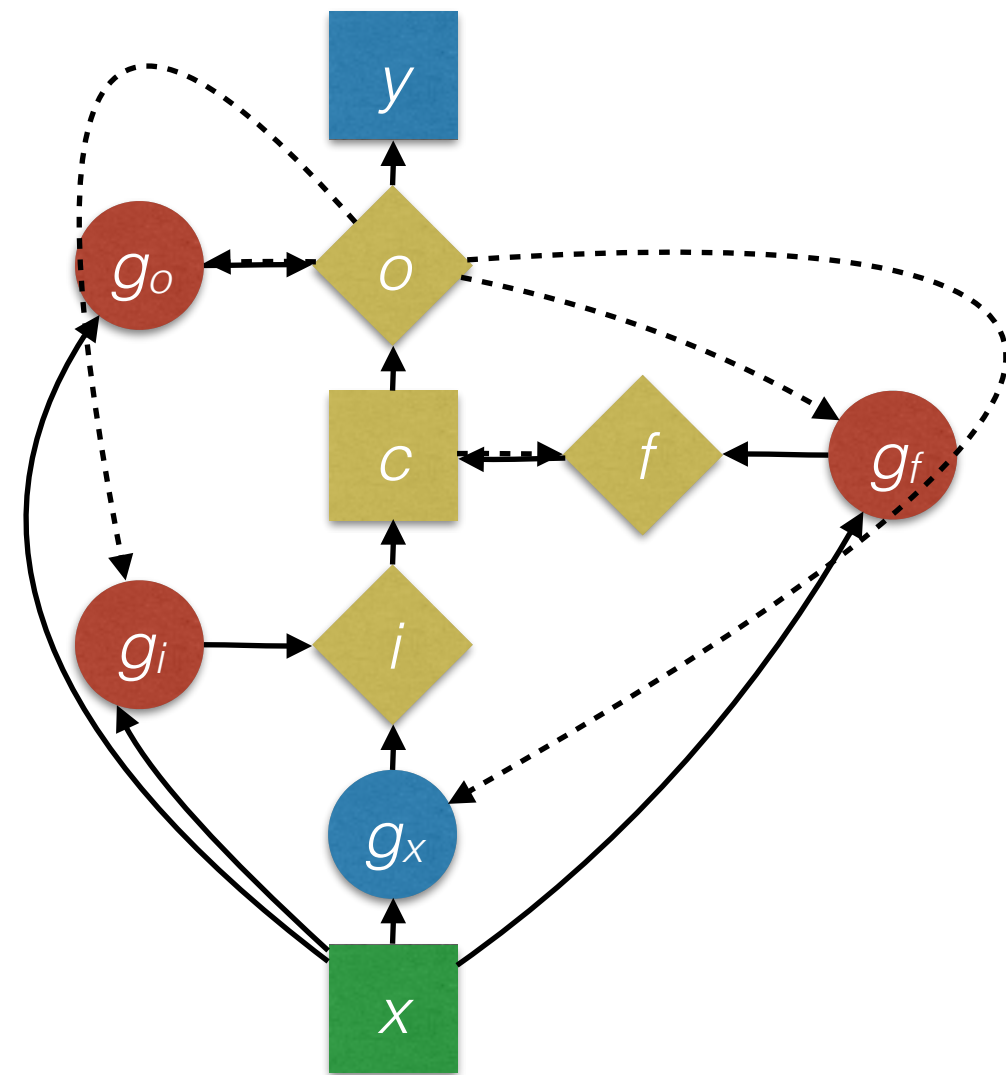
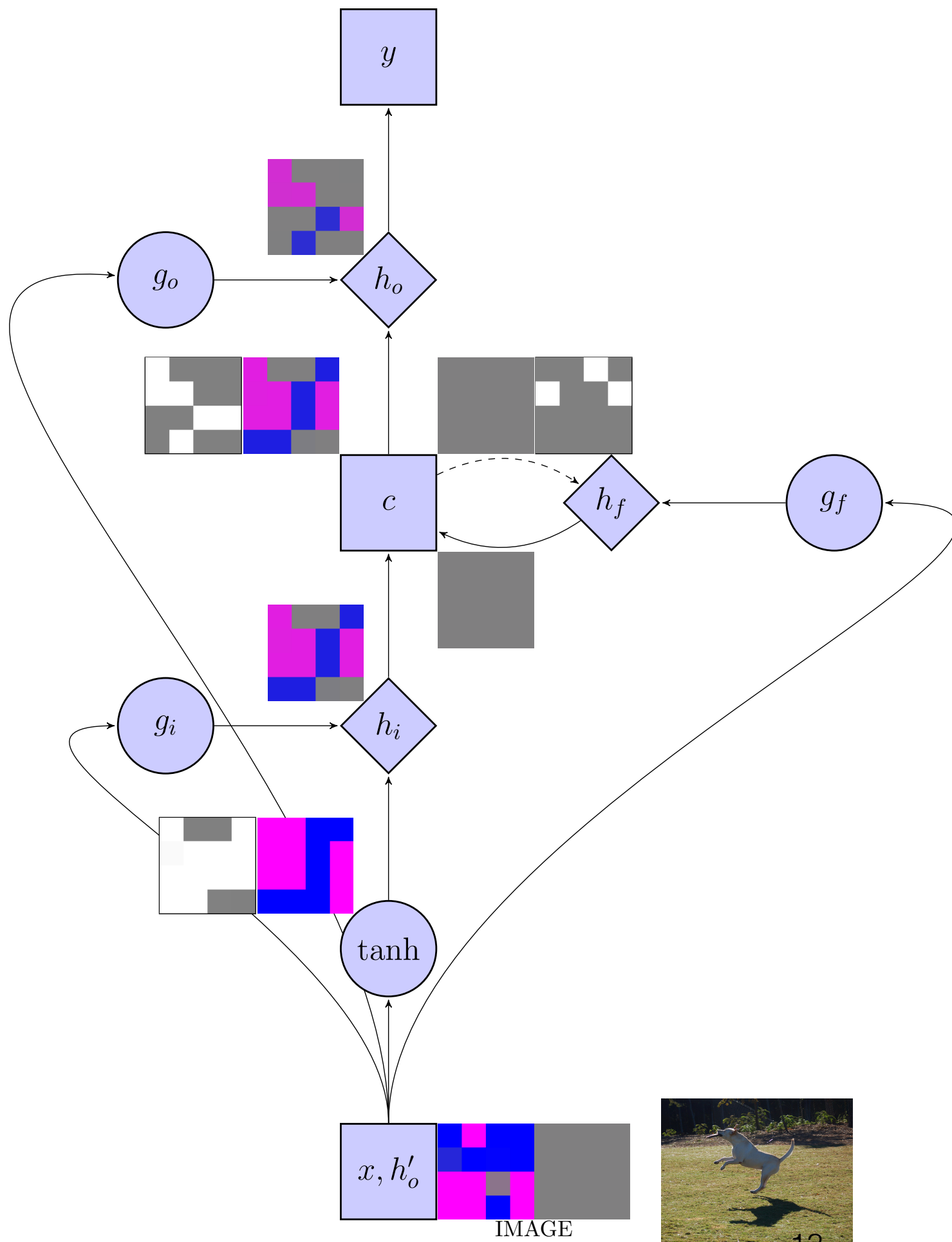
Toy Experiment

- Training set (407)
 - dog & frisbee: 59
 - man & ride: 324
 - kiss: 24

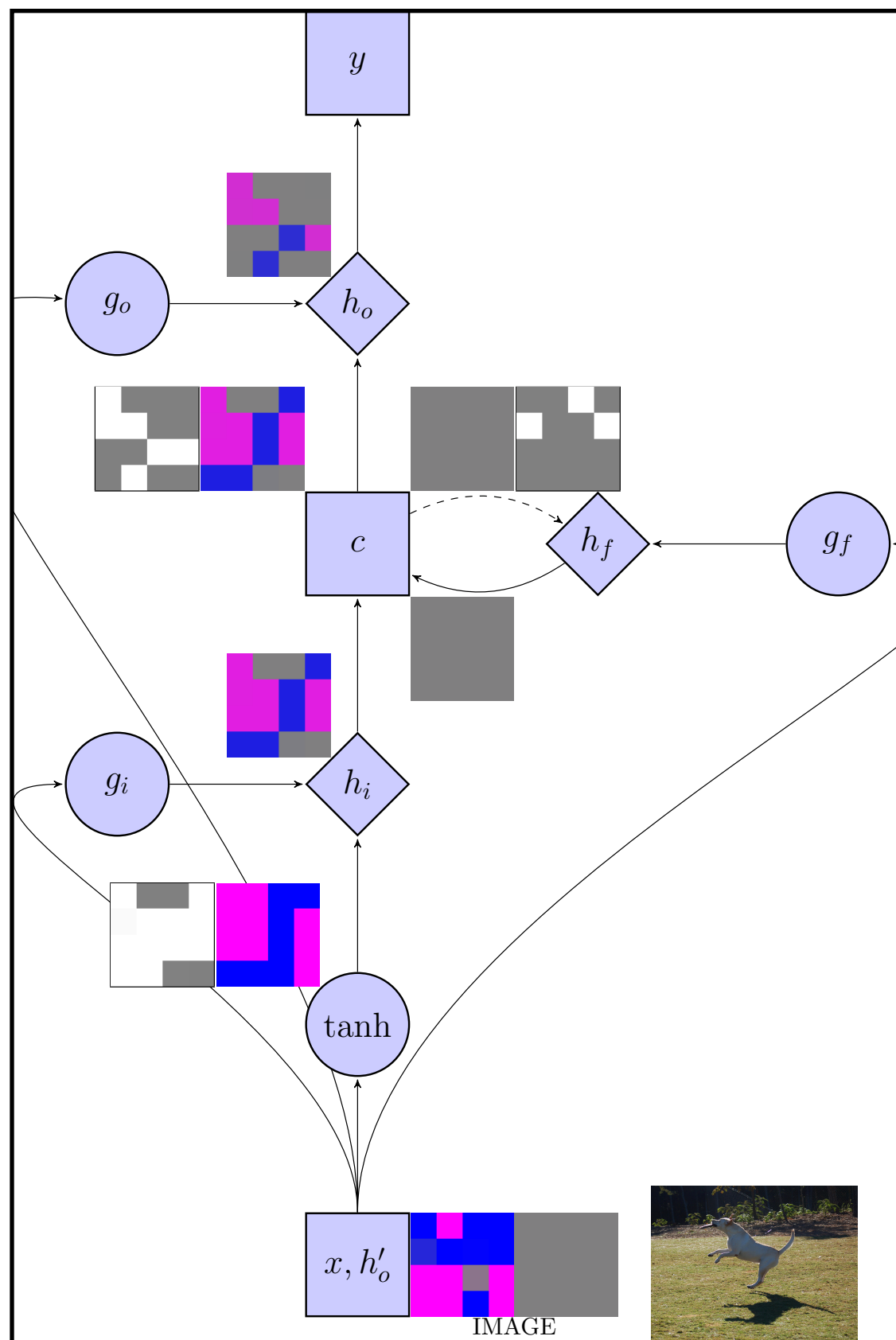


a dog jumps to catch a frisbee .

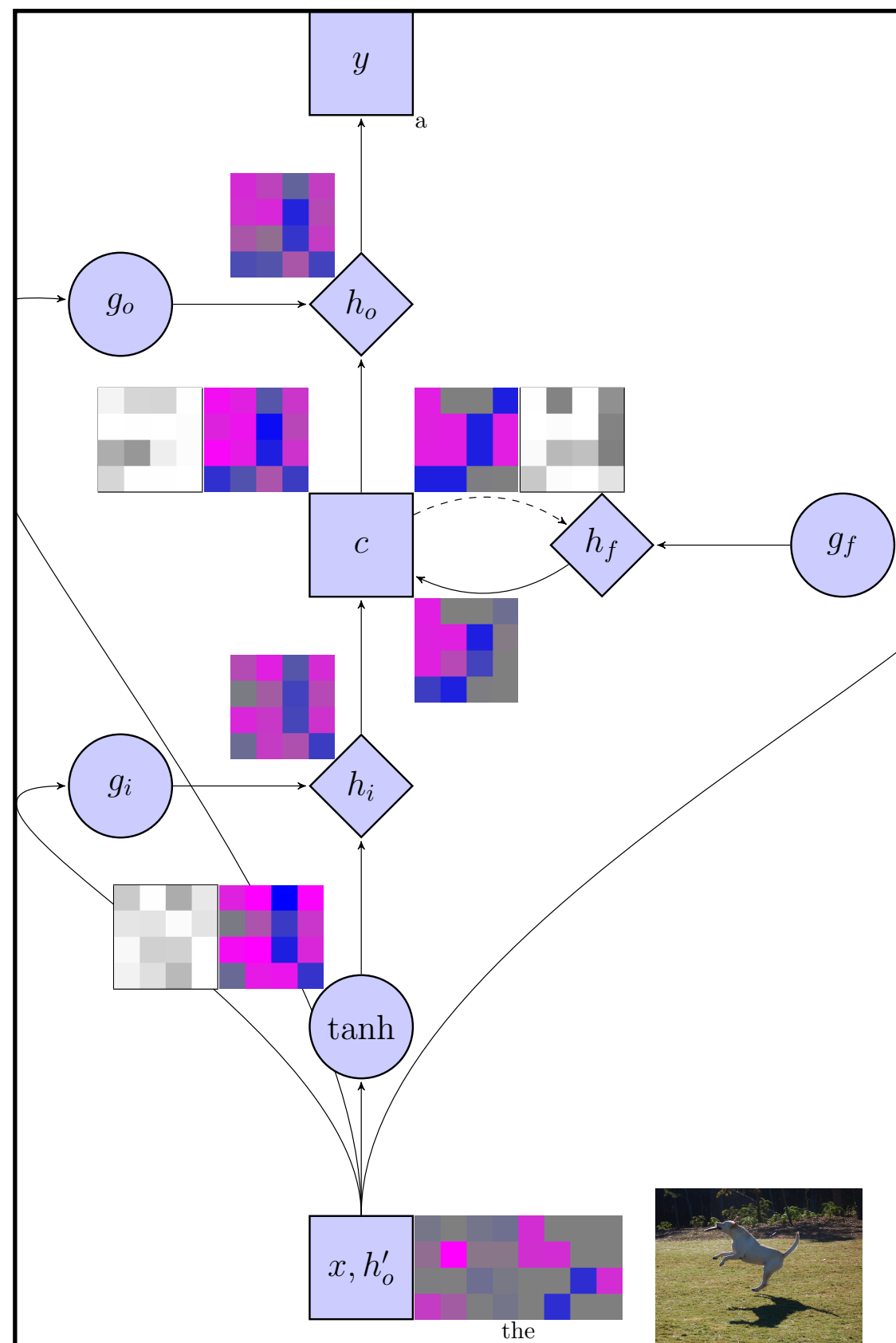
1674612291_7154c5ab61.jpg



a dog jumps to catch a frisbee .

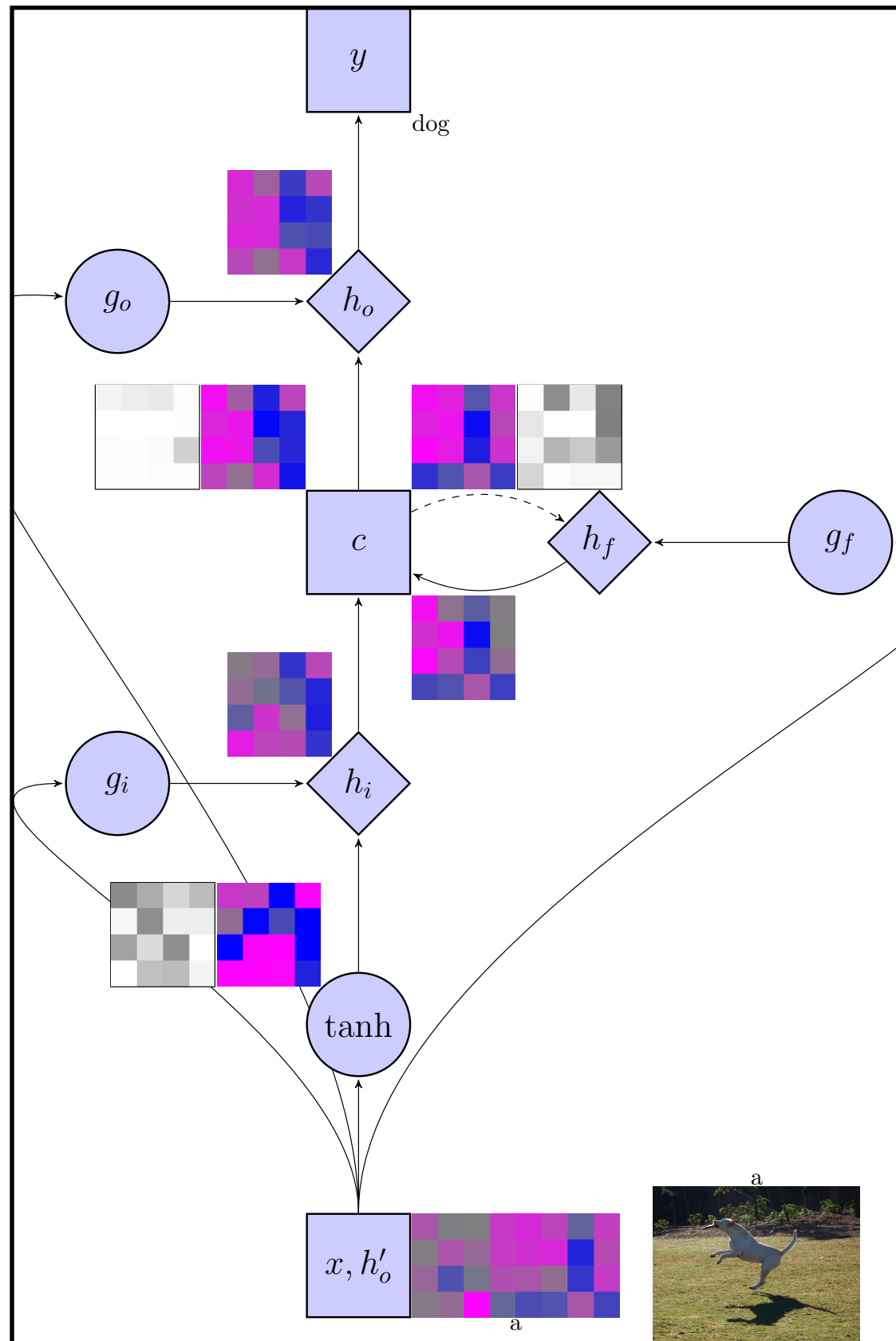


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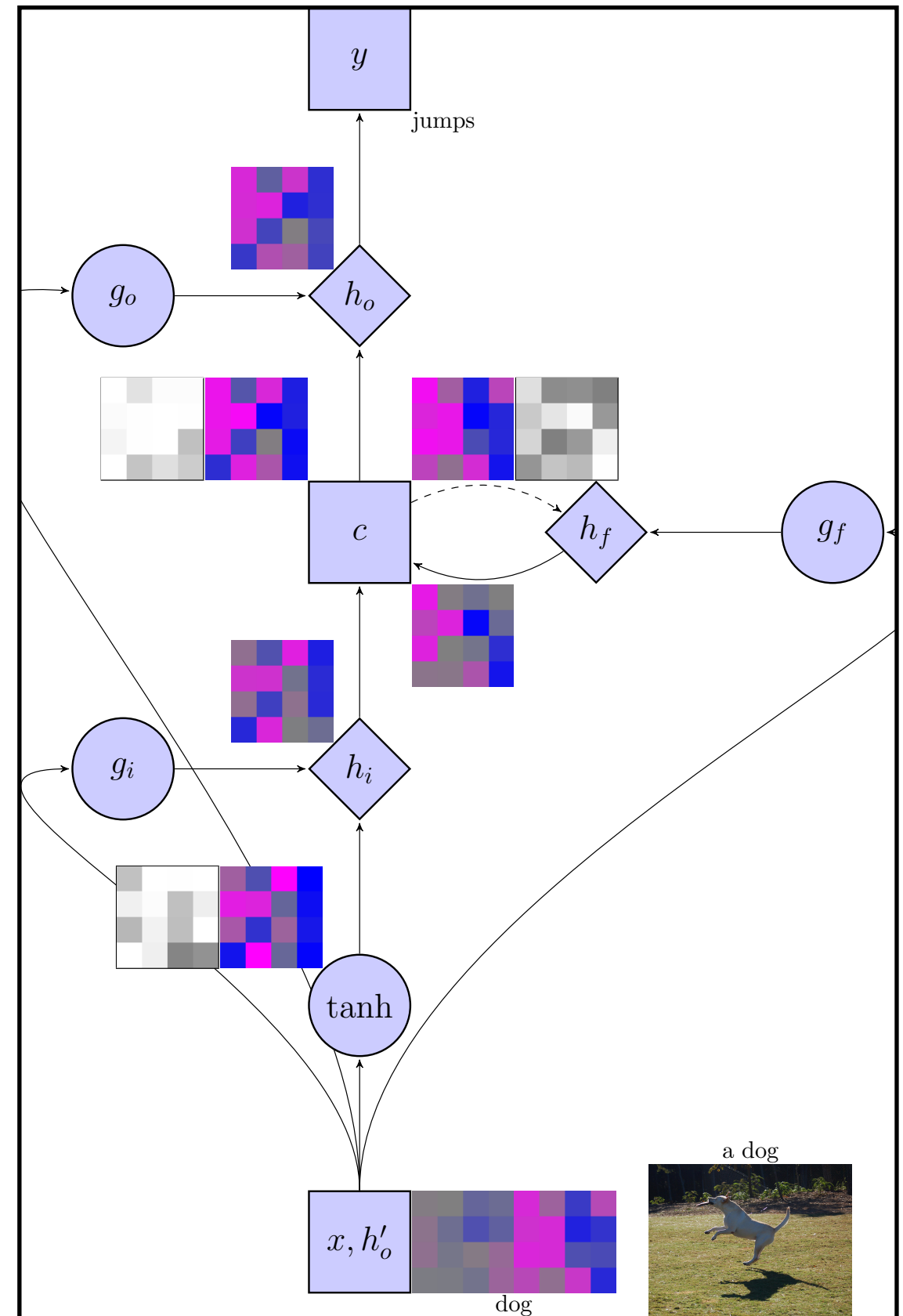


1

a dog jumps to catch a frisbee .

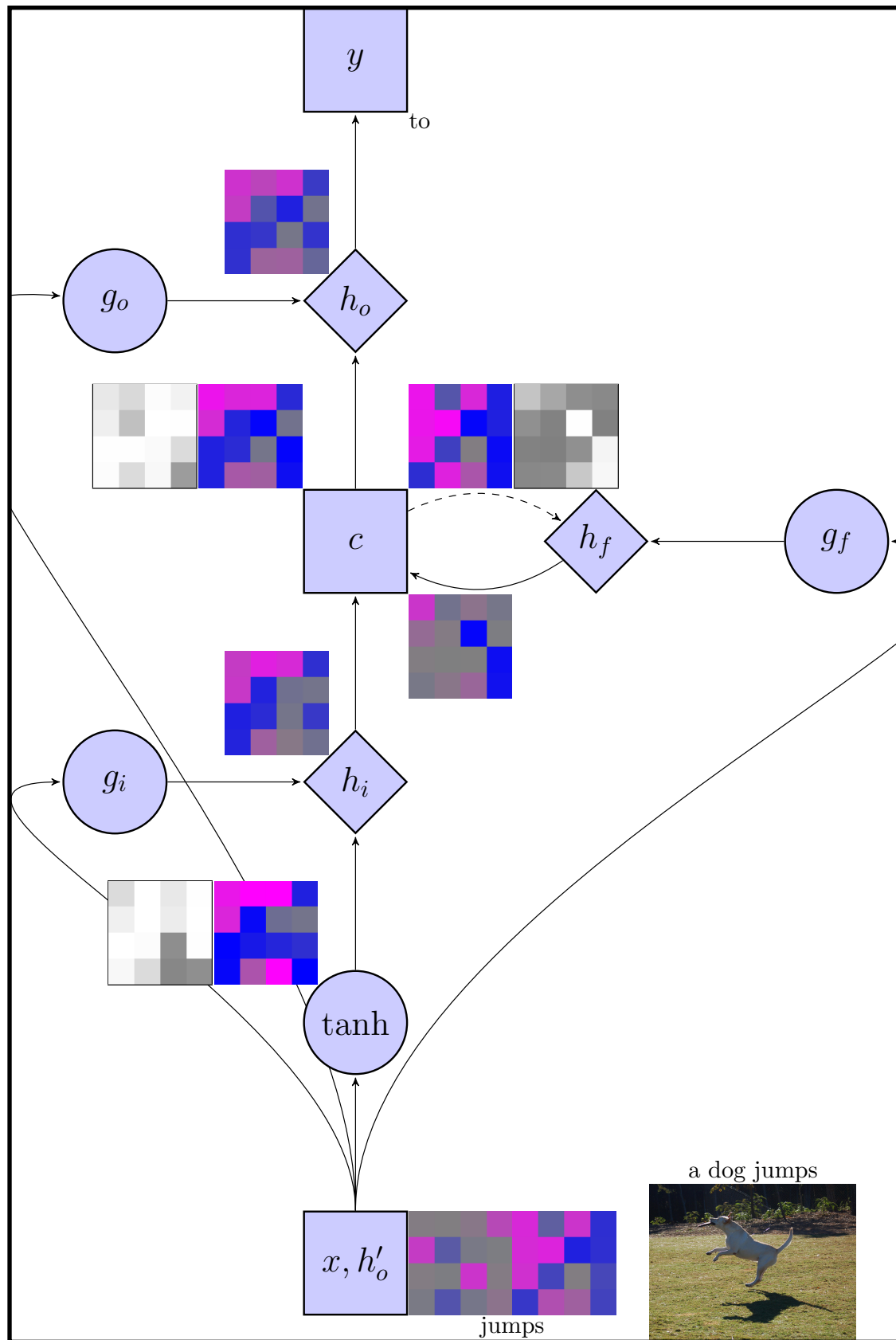


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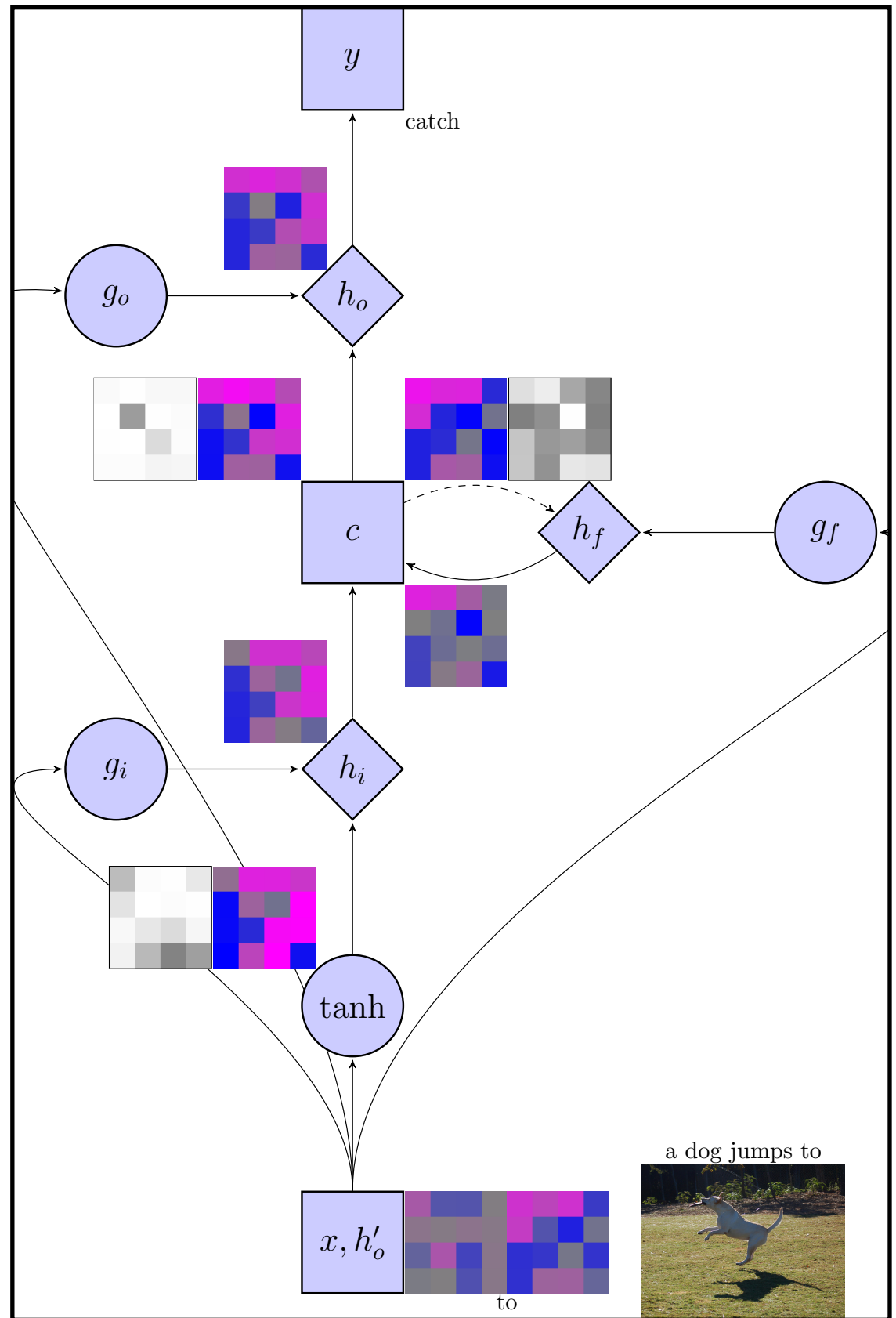


3

a dog jumps to catch a frisbee .

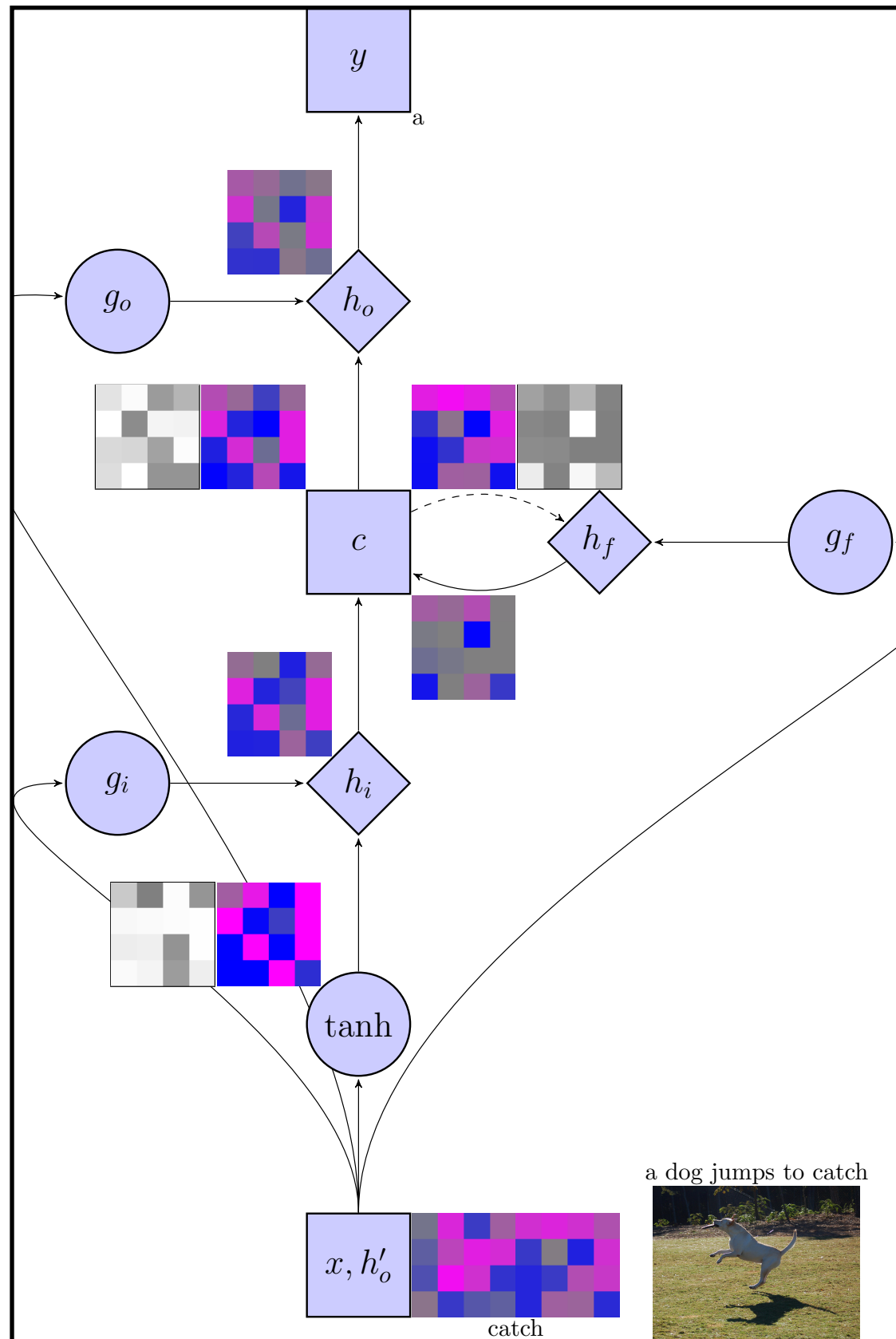


4

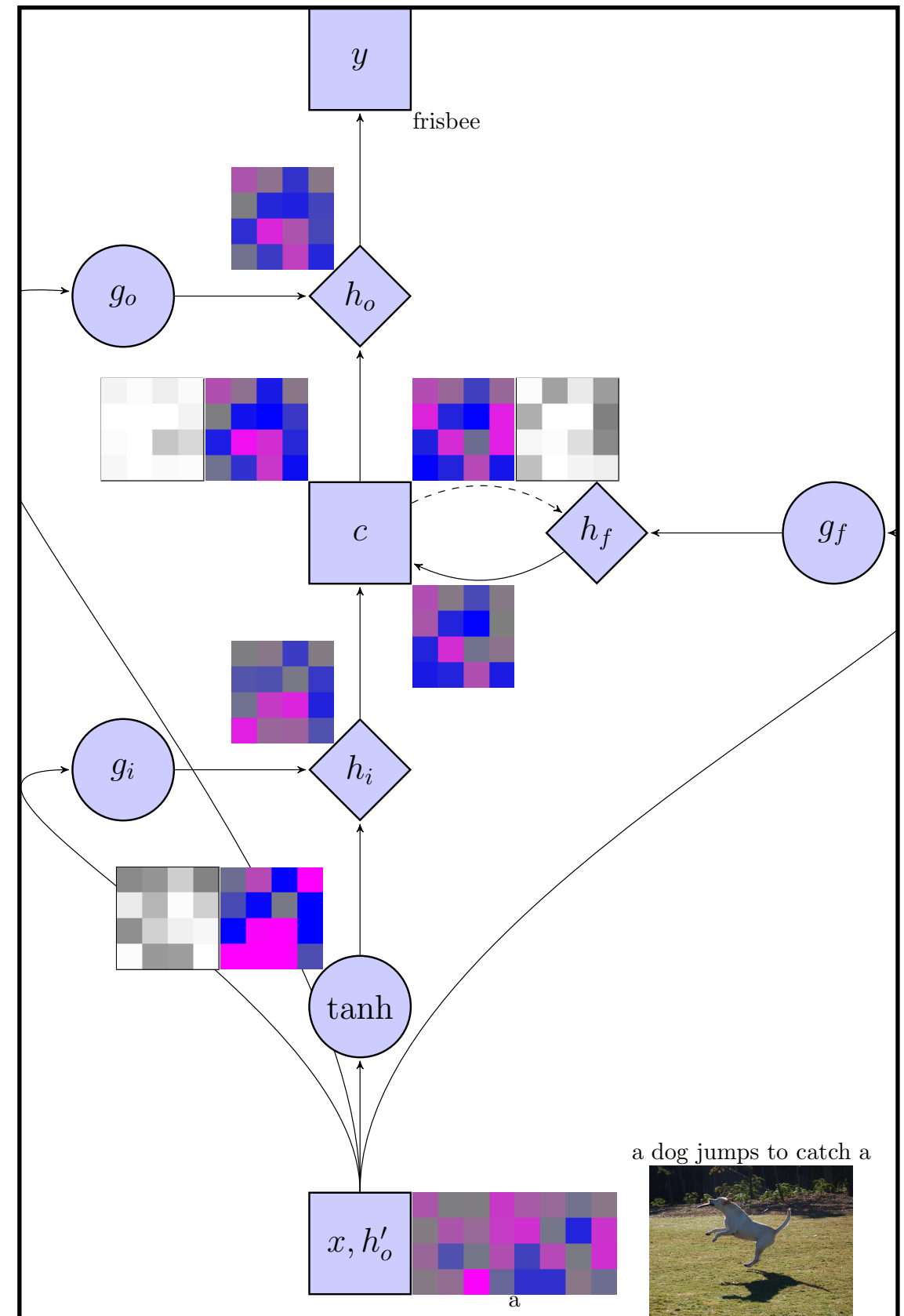


5

a dog jumps to catch a frisbee .

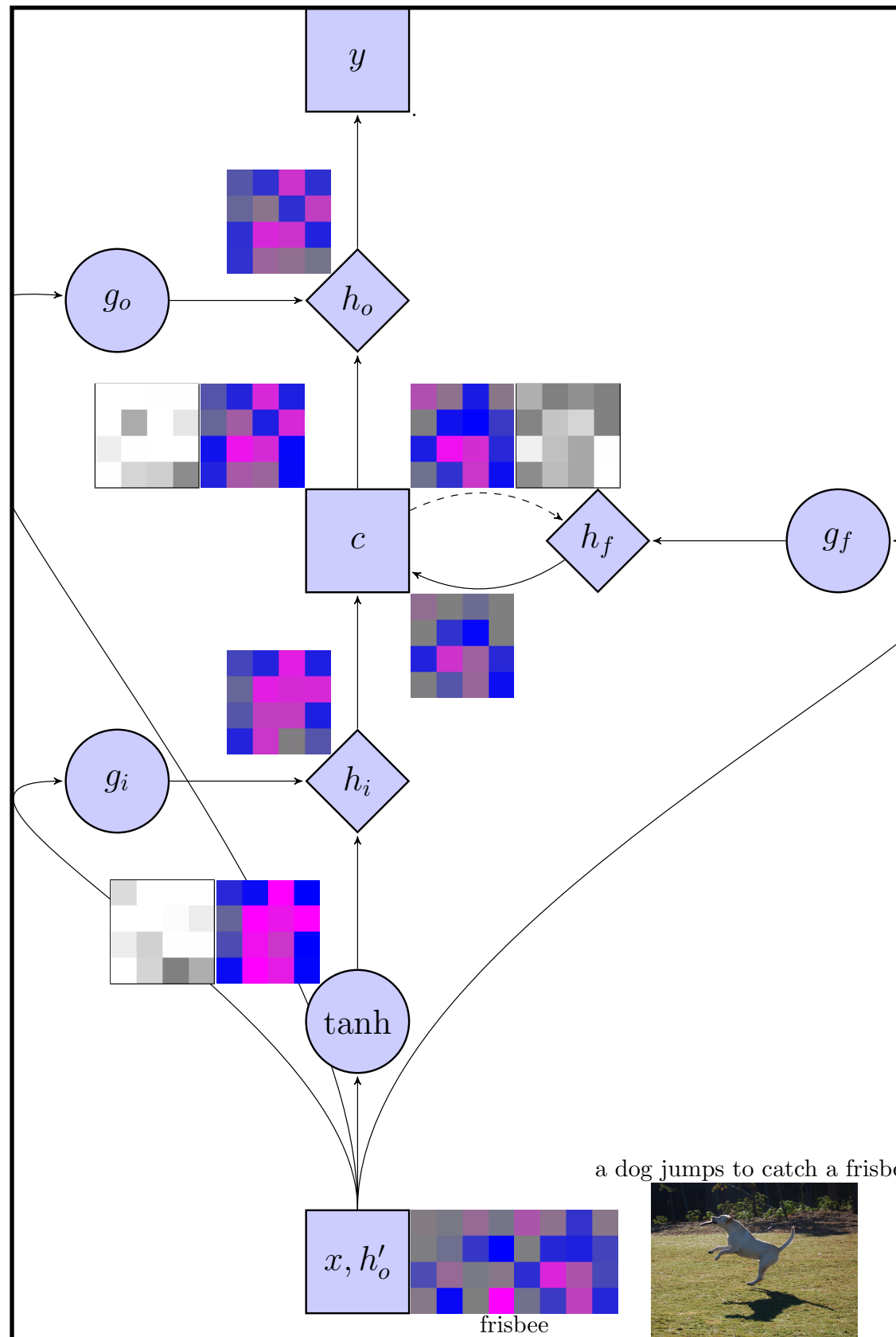


6



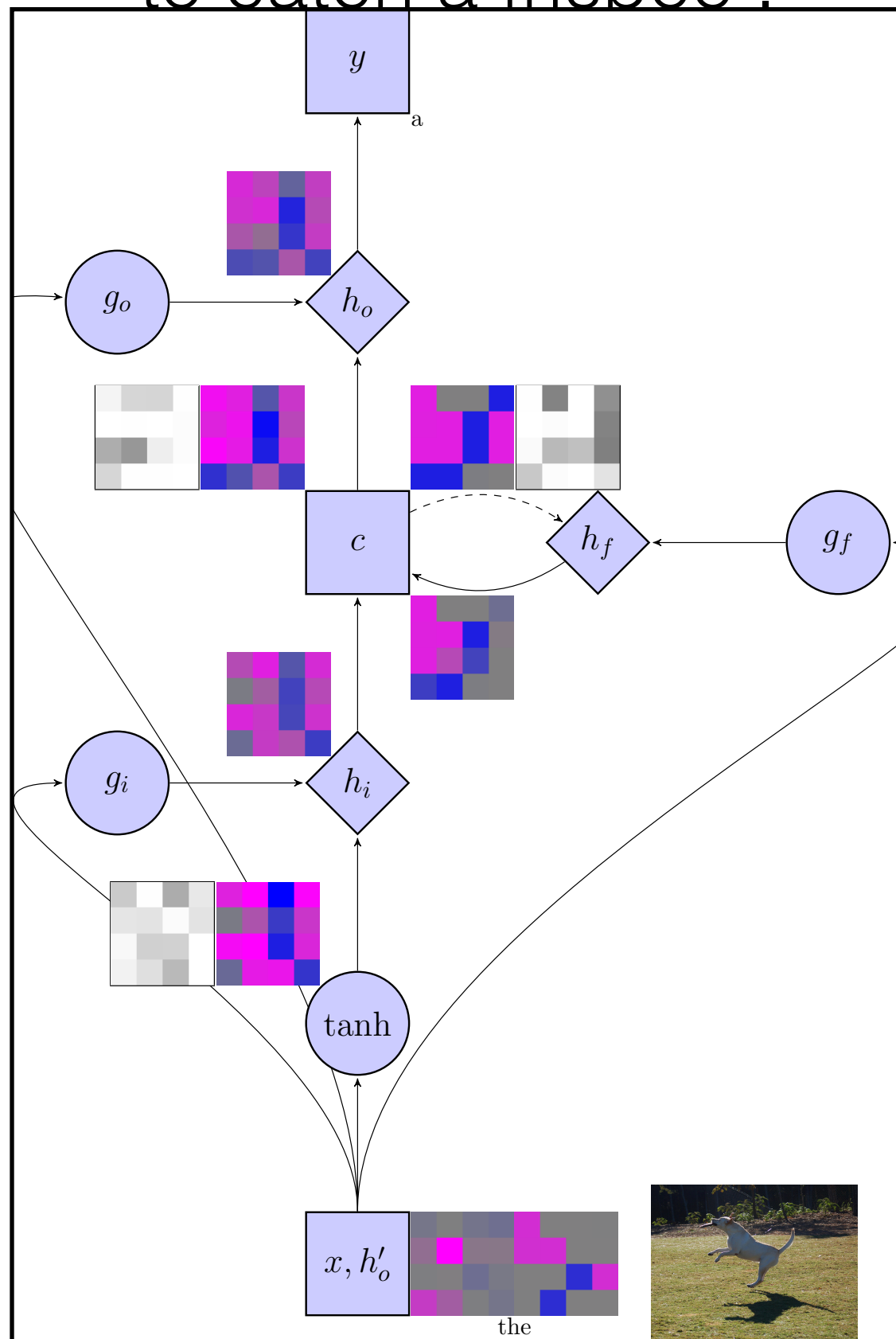
7

a dog jumps to catch a frisbee .



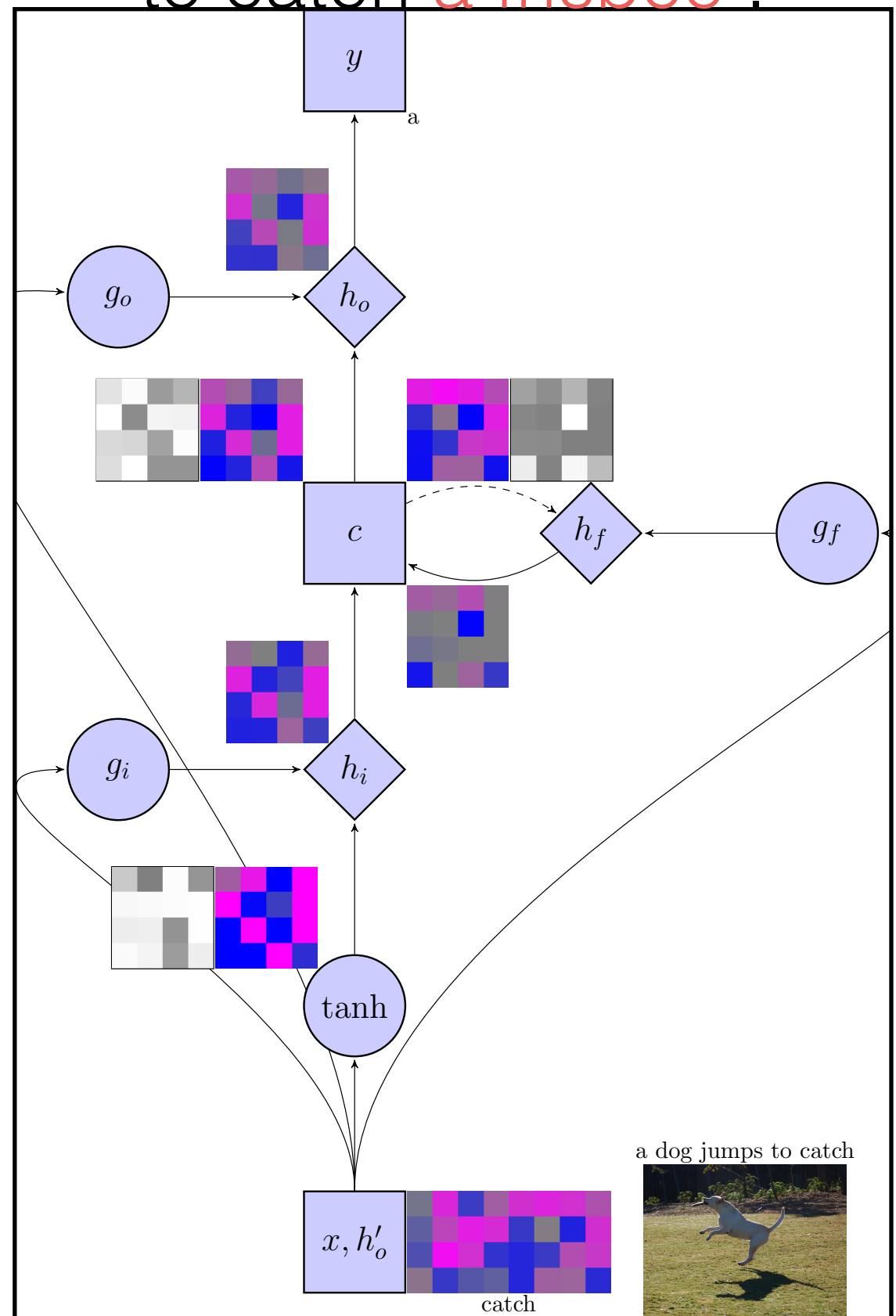
Inherit previous memory
Acknowledge previous word
Update current memory
Predict next word
Until all memory fades out

a dog jumps
to catch a frisbee .



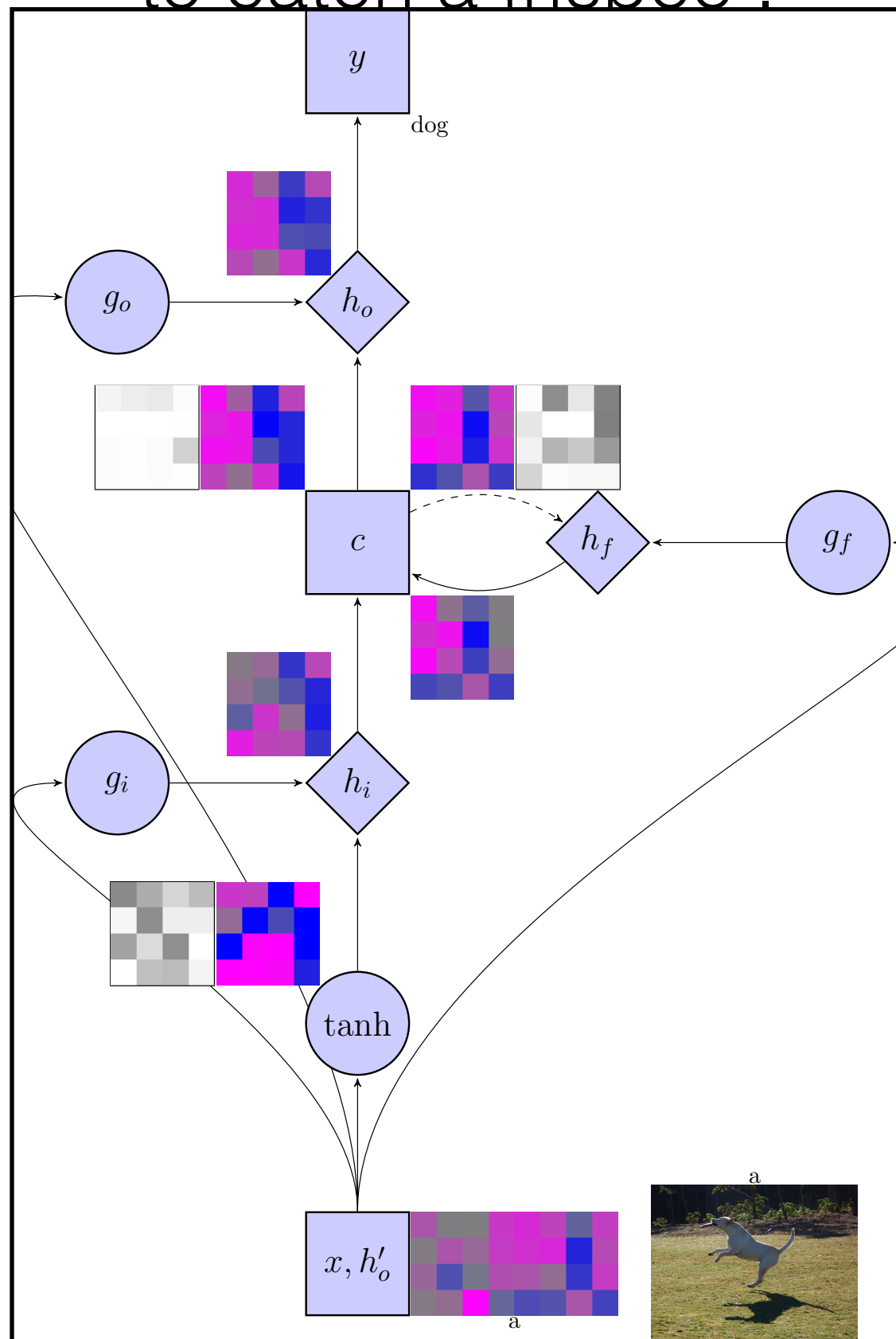
1

a dog jumps
to catch a frisbee .



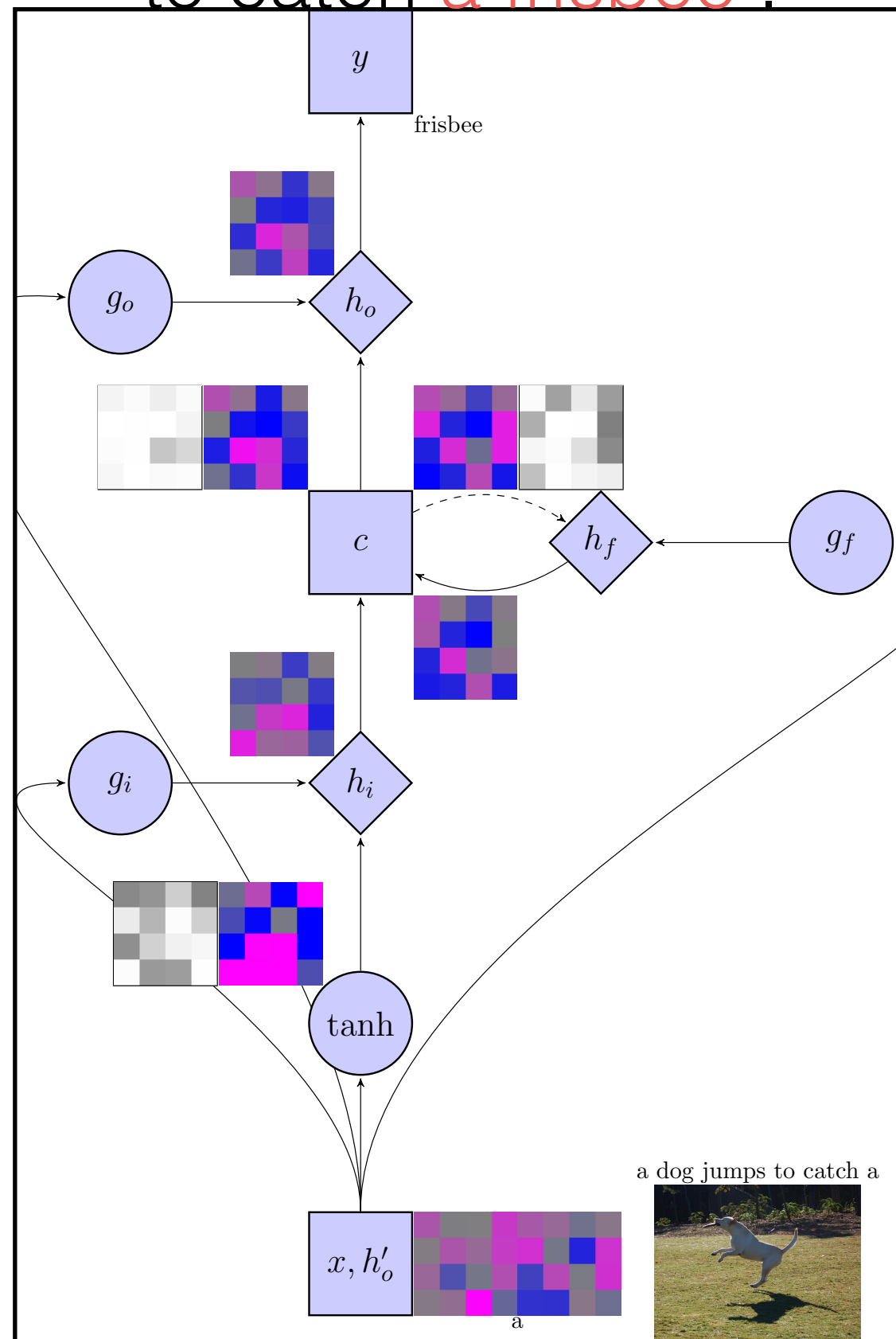
6

a dog jumps
to catch a frisbee .



2

a dog jumps
to catch a frisbee .



7

a dog **jumps** to
catch a frisbee .

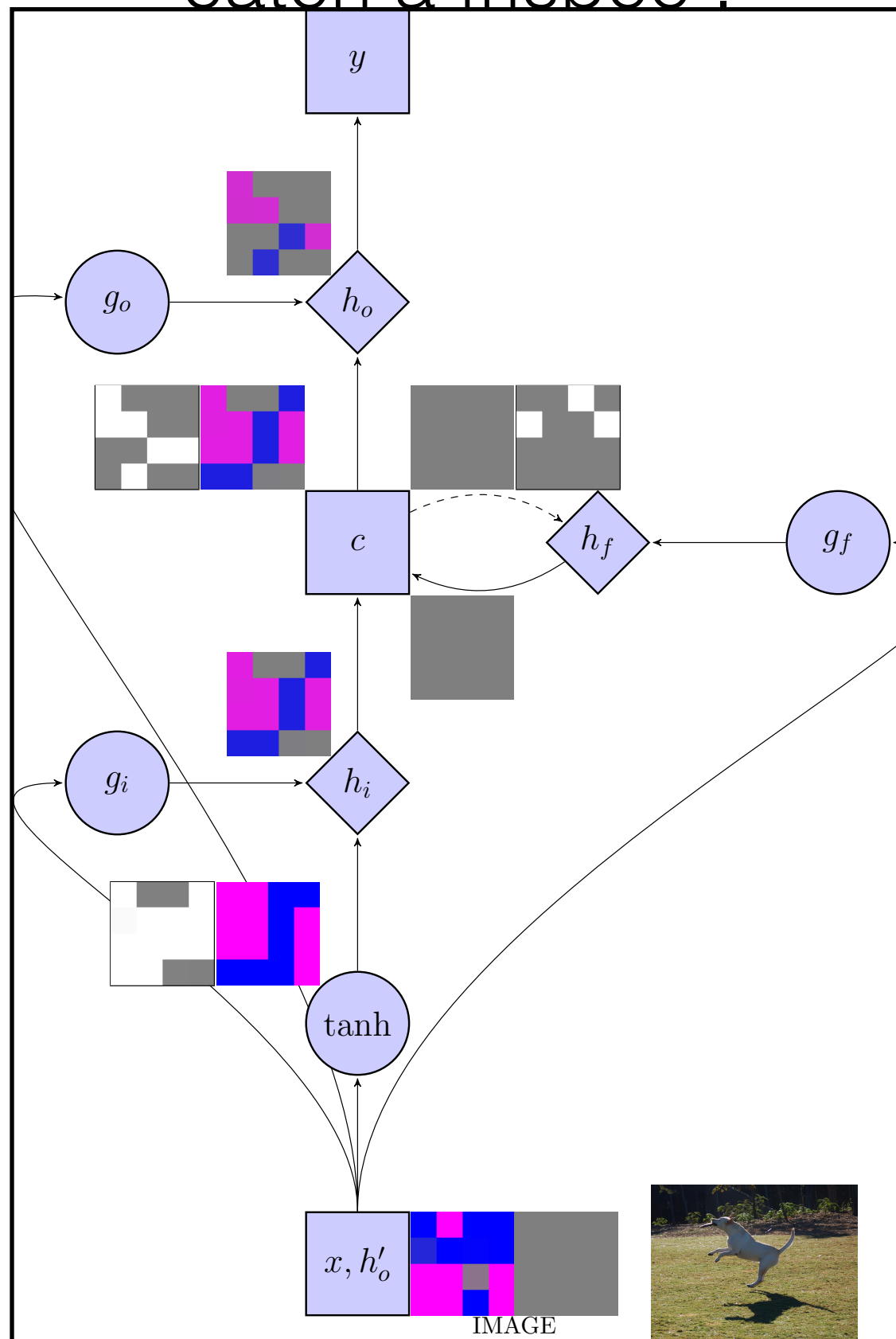


a dog **is jumping** to
catch a frisbee .



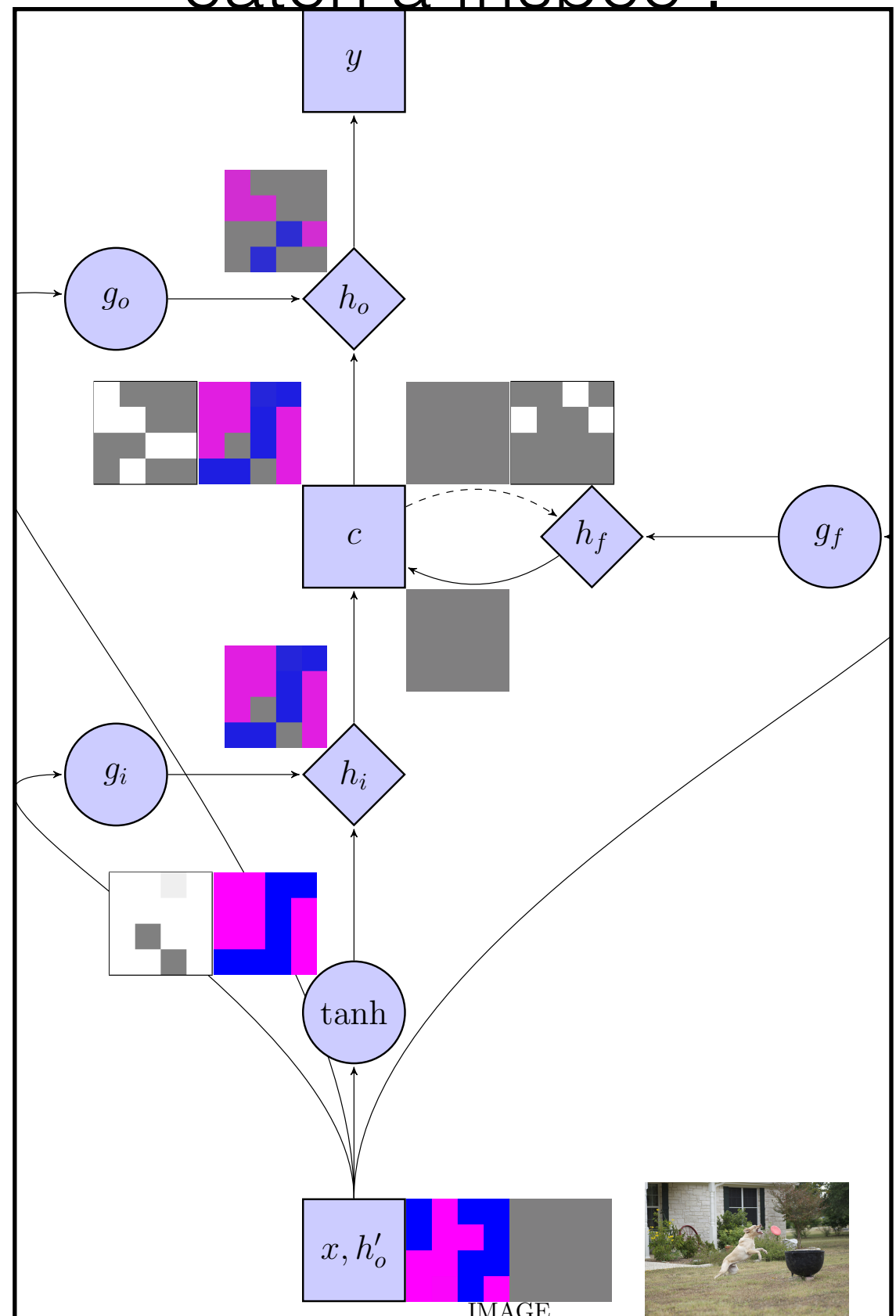
1674612291_7154c5ab61.jpg₂₁ 2945036454_280fa5b29f.jpg

a dog **jumps** to
catch a frisbee .



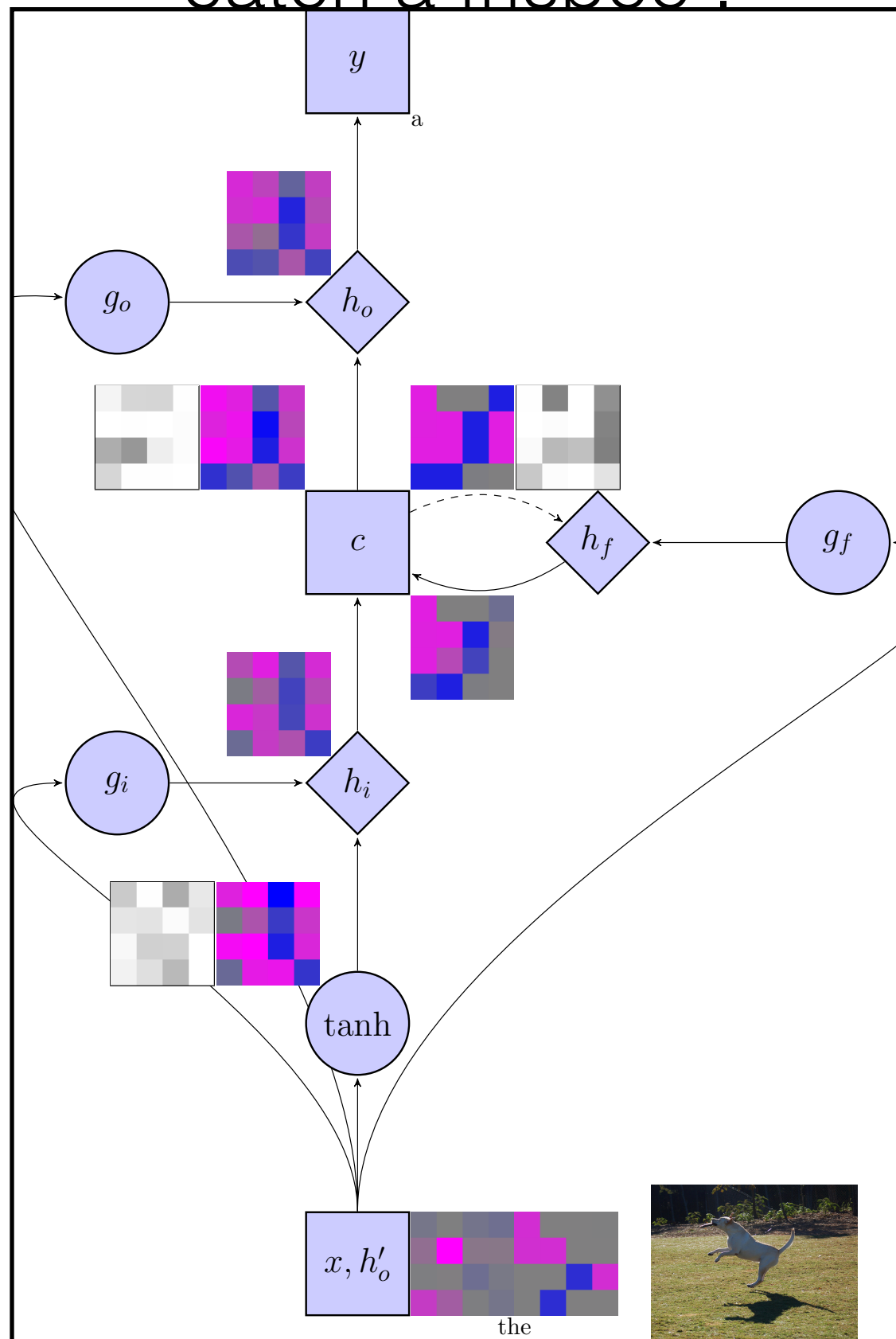
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a dog **is jumping** to
catch a frisbee .



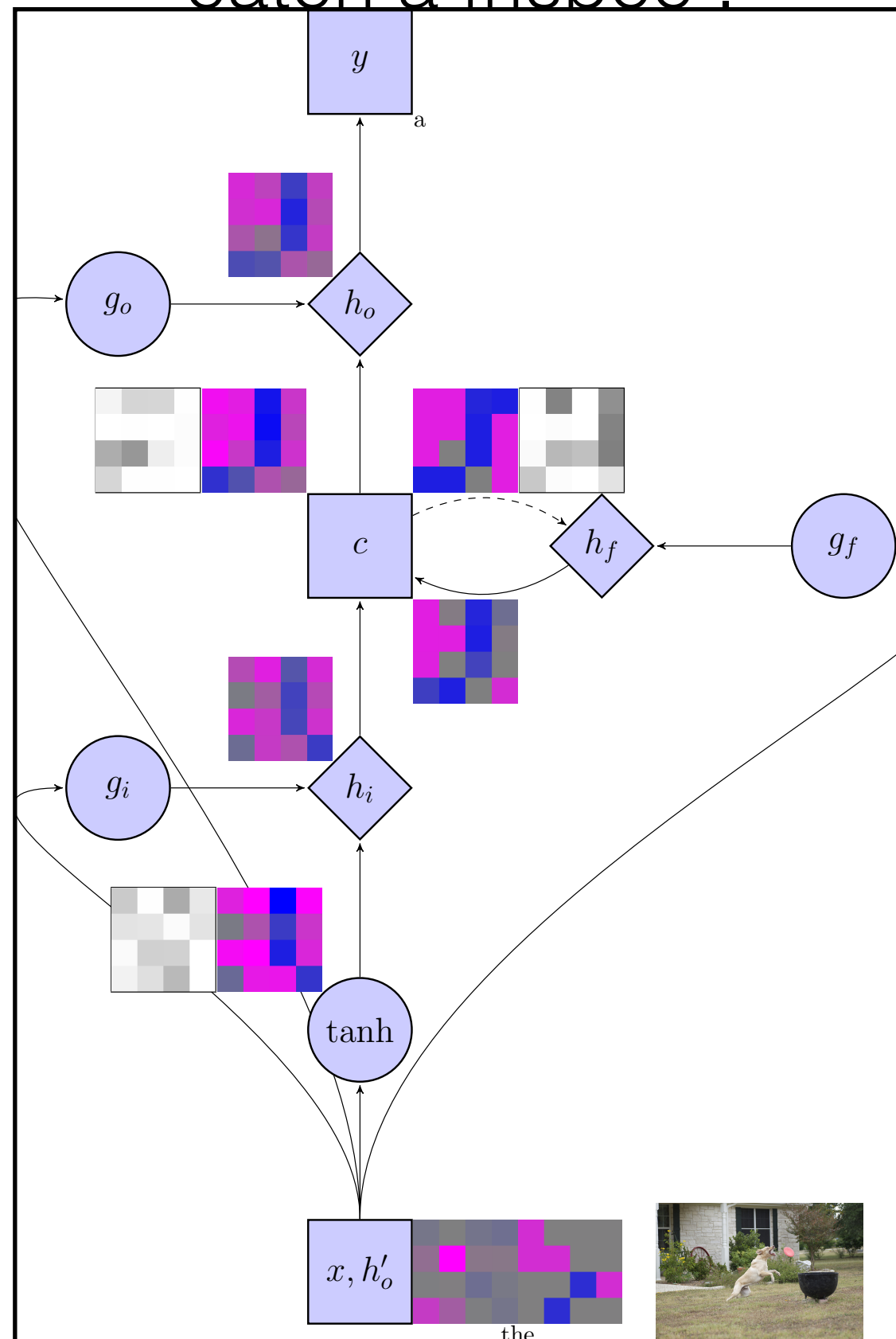
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a dog jumps to
catch a frisbee .



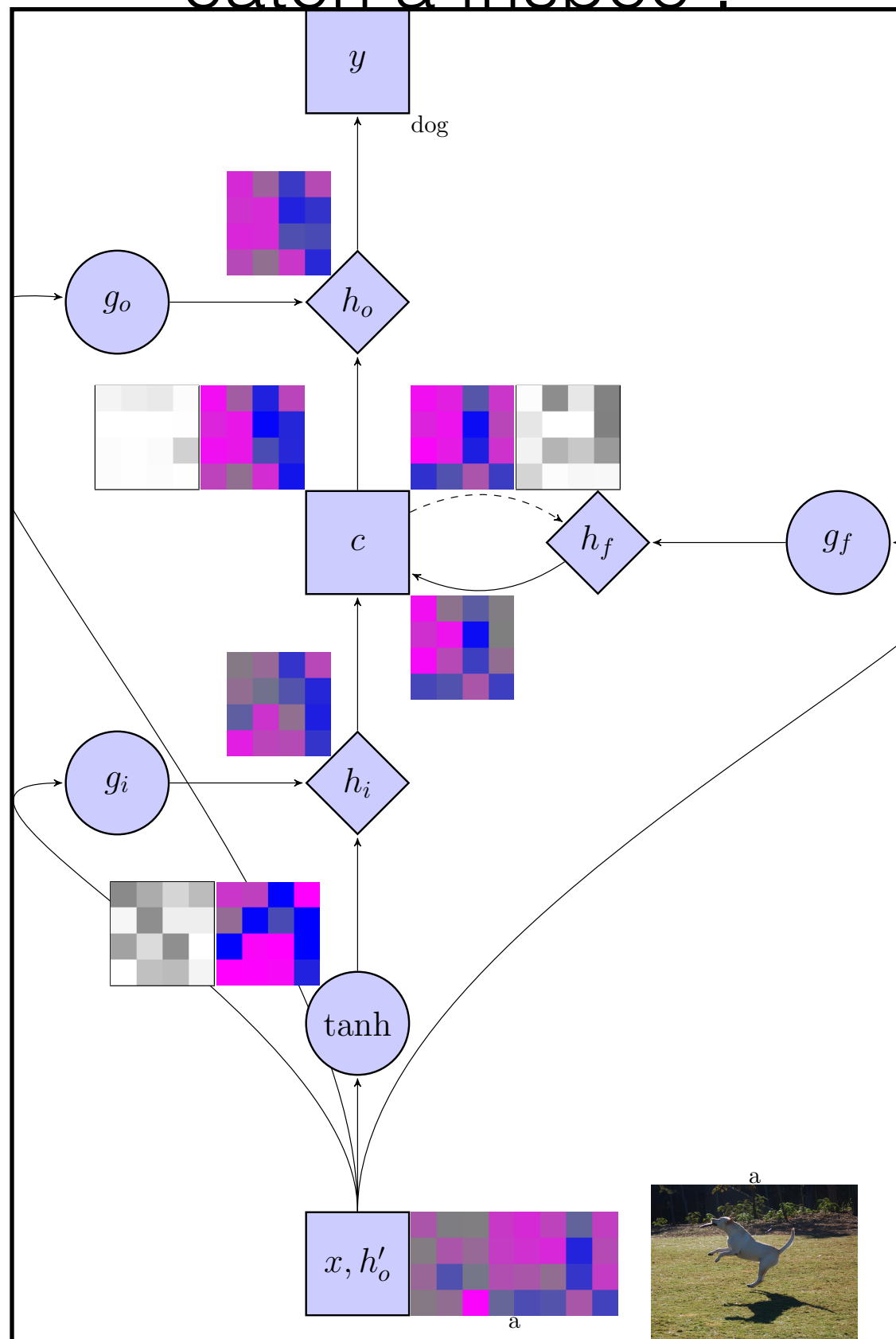
1

a dog is jumping to
catch a frisbee .



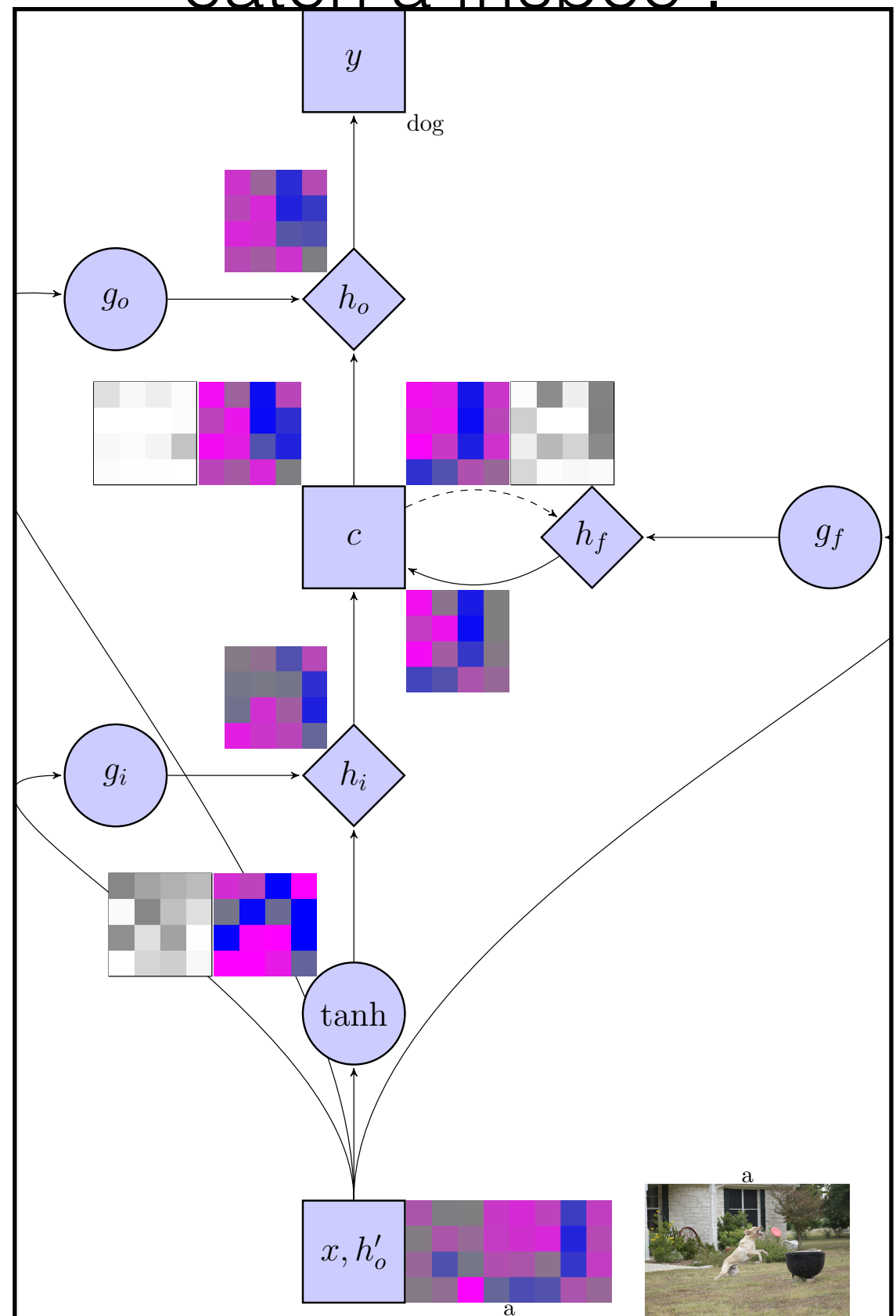
1

a dog jumps to
catch a frisbee .



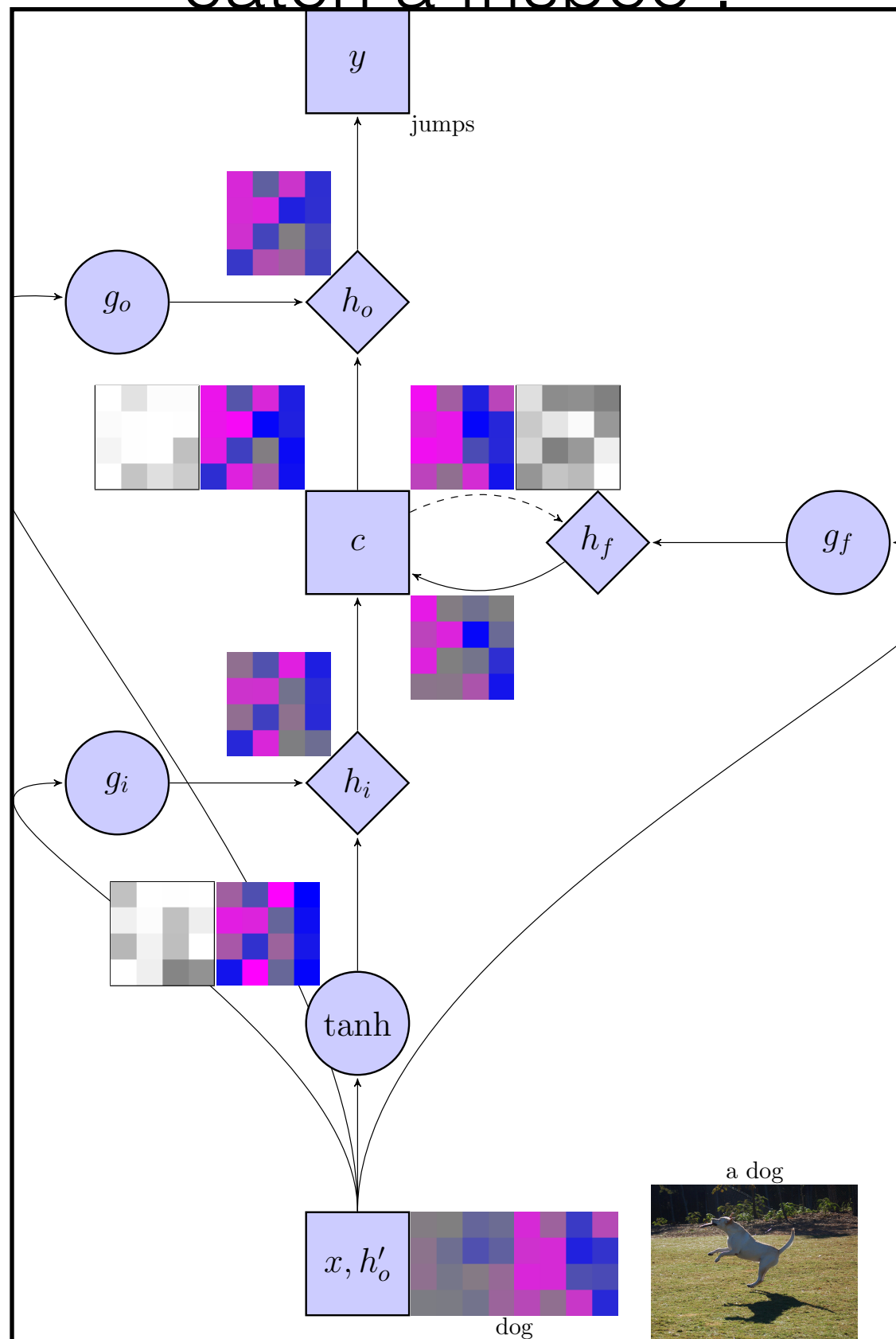
2

a dog is jumping to
catch a frisbee .



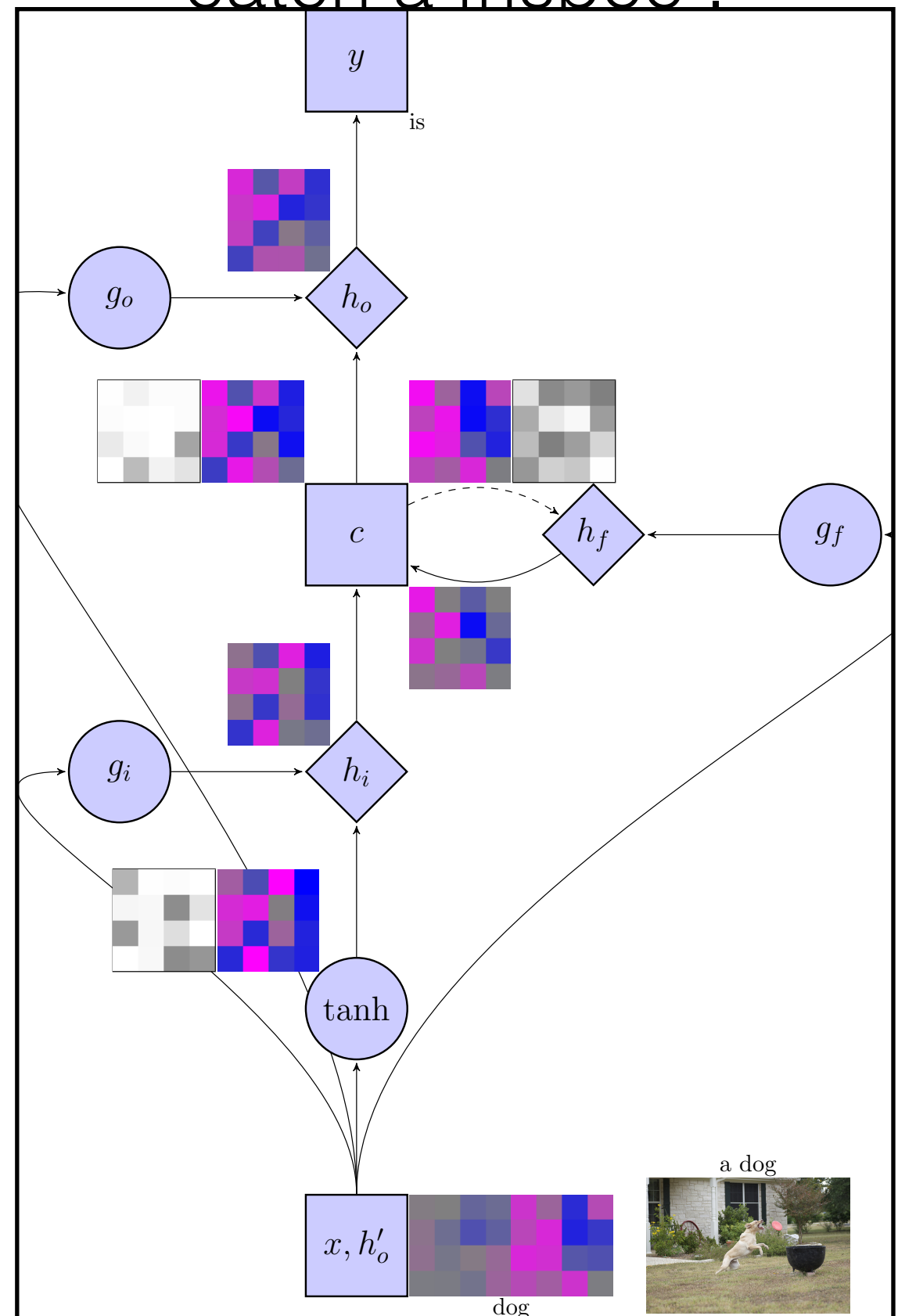
2

a dog **jumps** to
catch a frisbee .



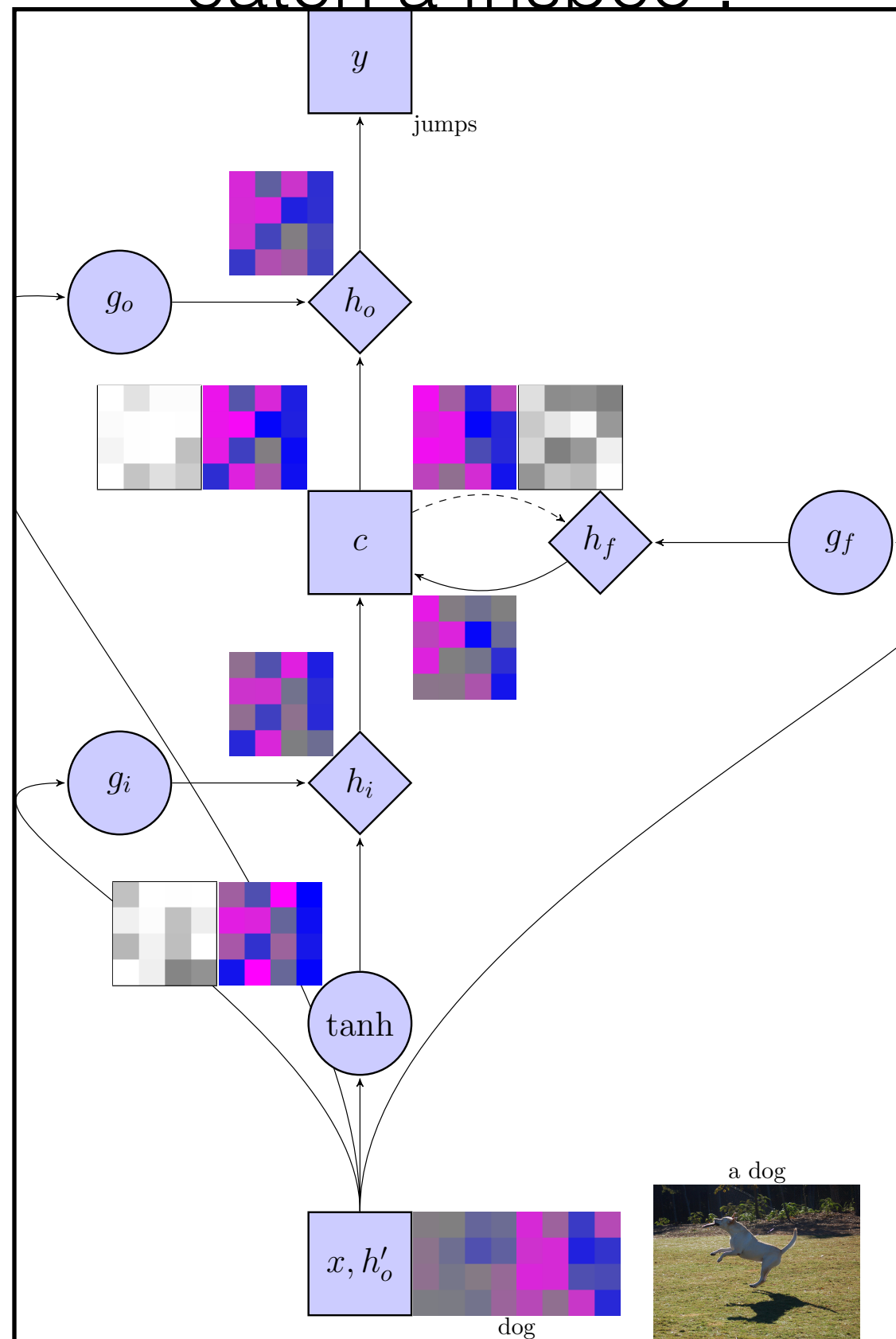
3

a dog **is jumping** to
catch a frisbee .



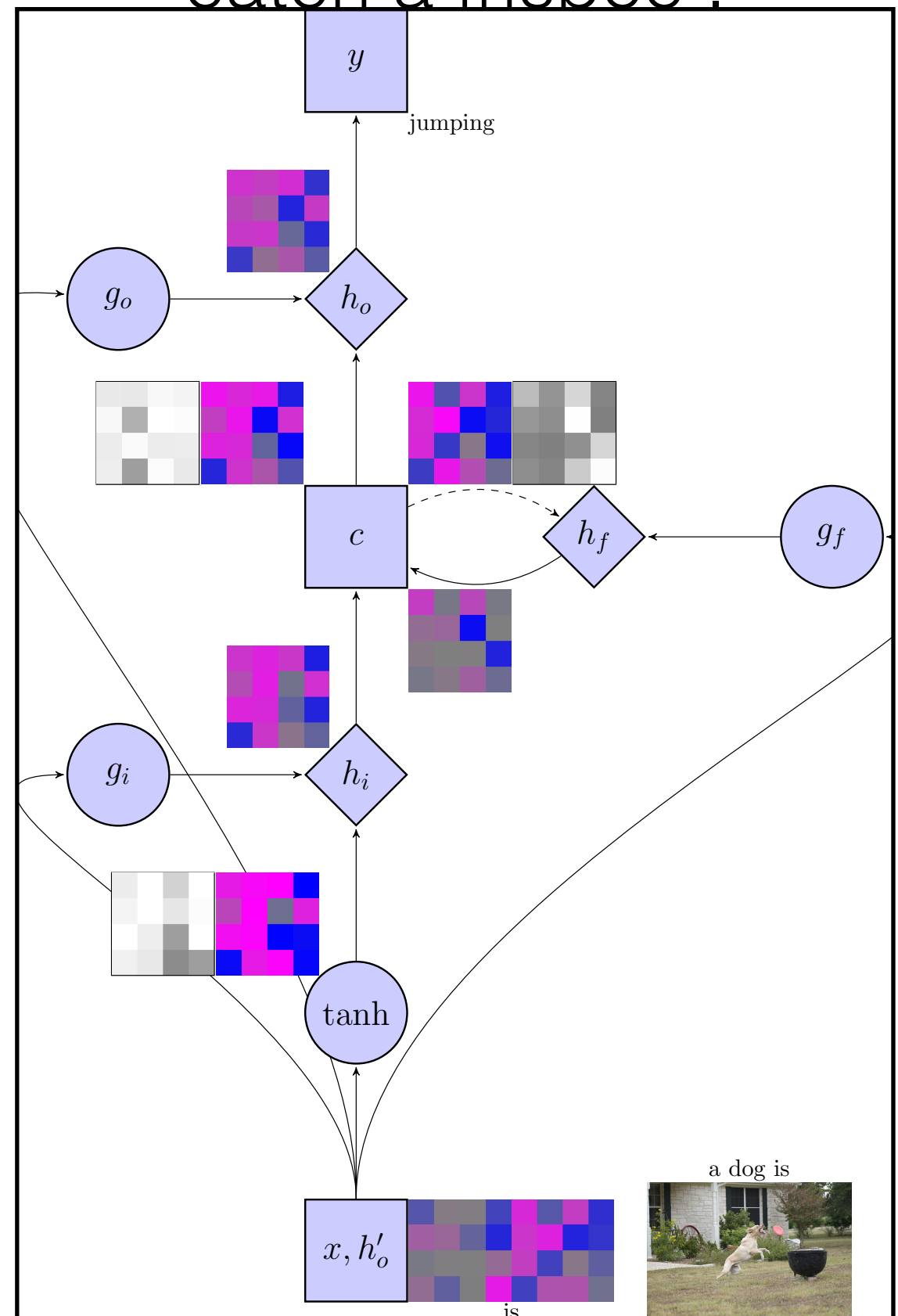
3

a dog **jumps** to
catch a frisbee .



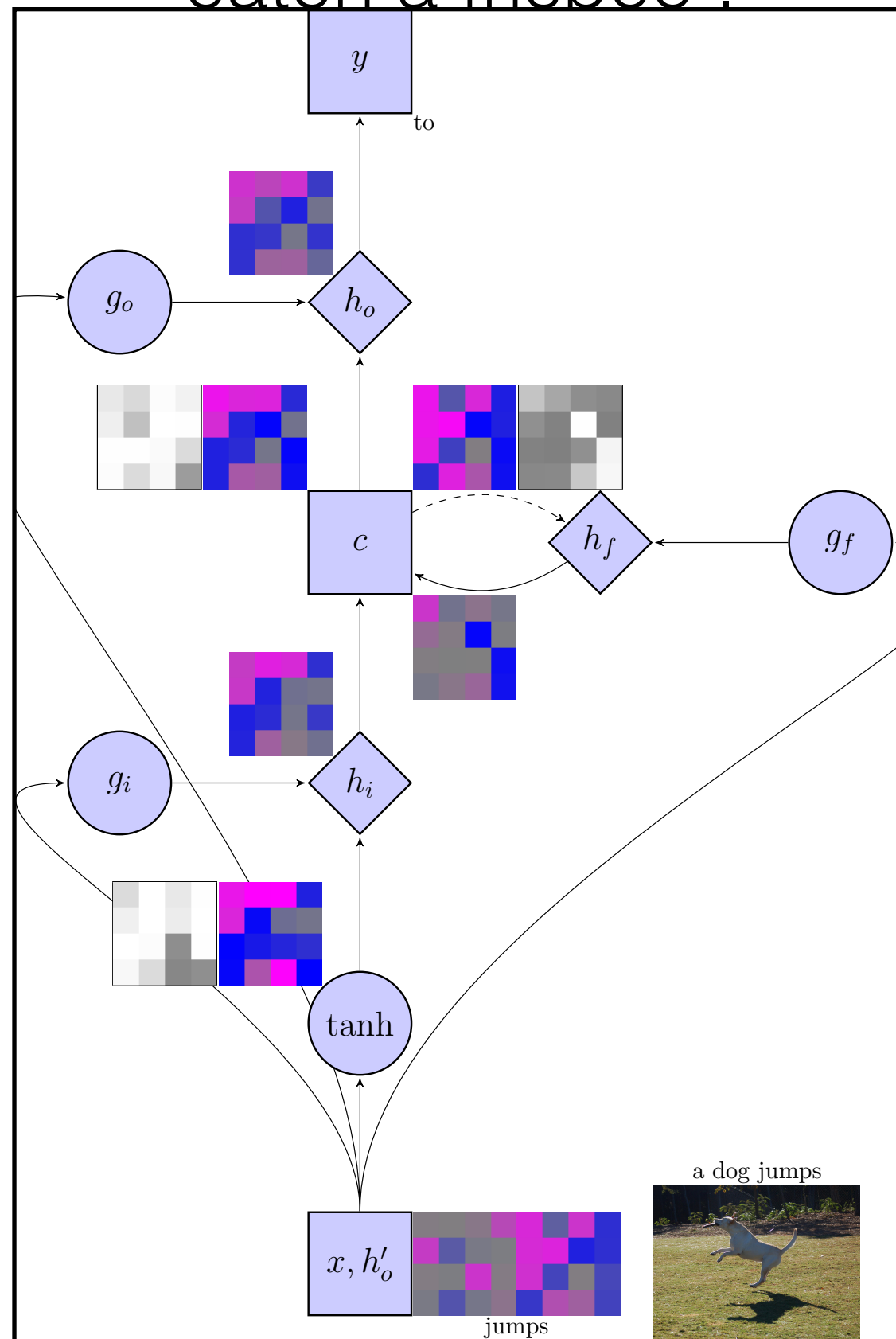
3

a dog **is jumping** to
catch a frisbee .



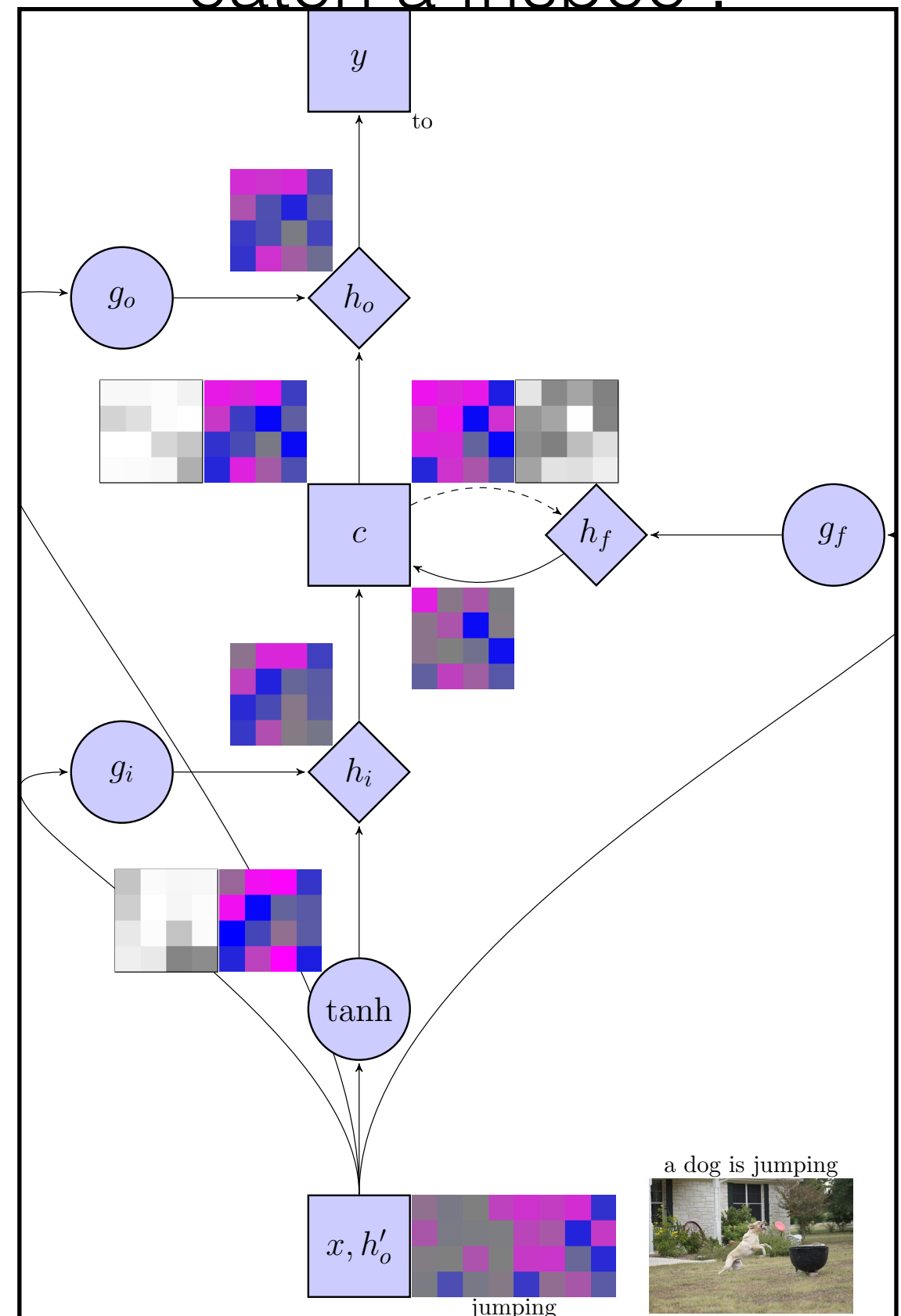
4

a dog **jumps** to
catch a frisbee .



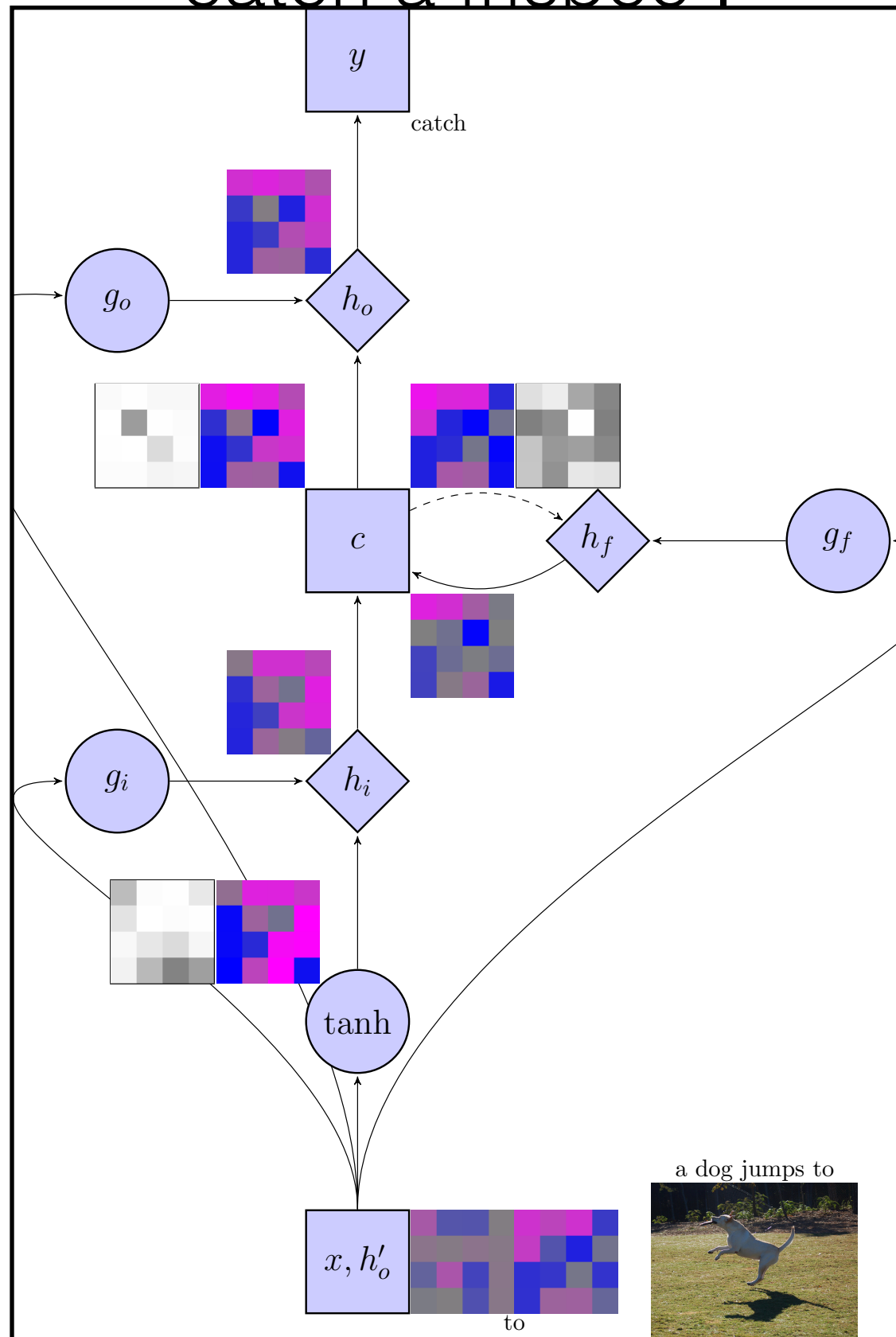
4

a dog **is jumping** to
catch a frisbee .



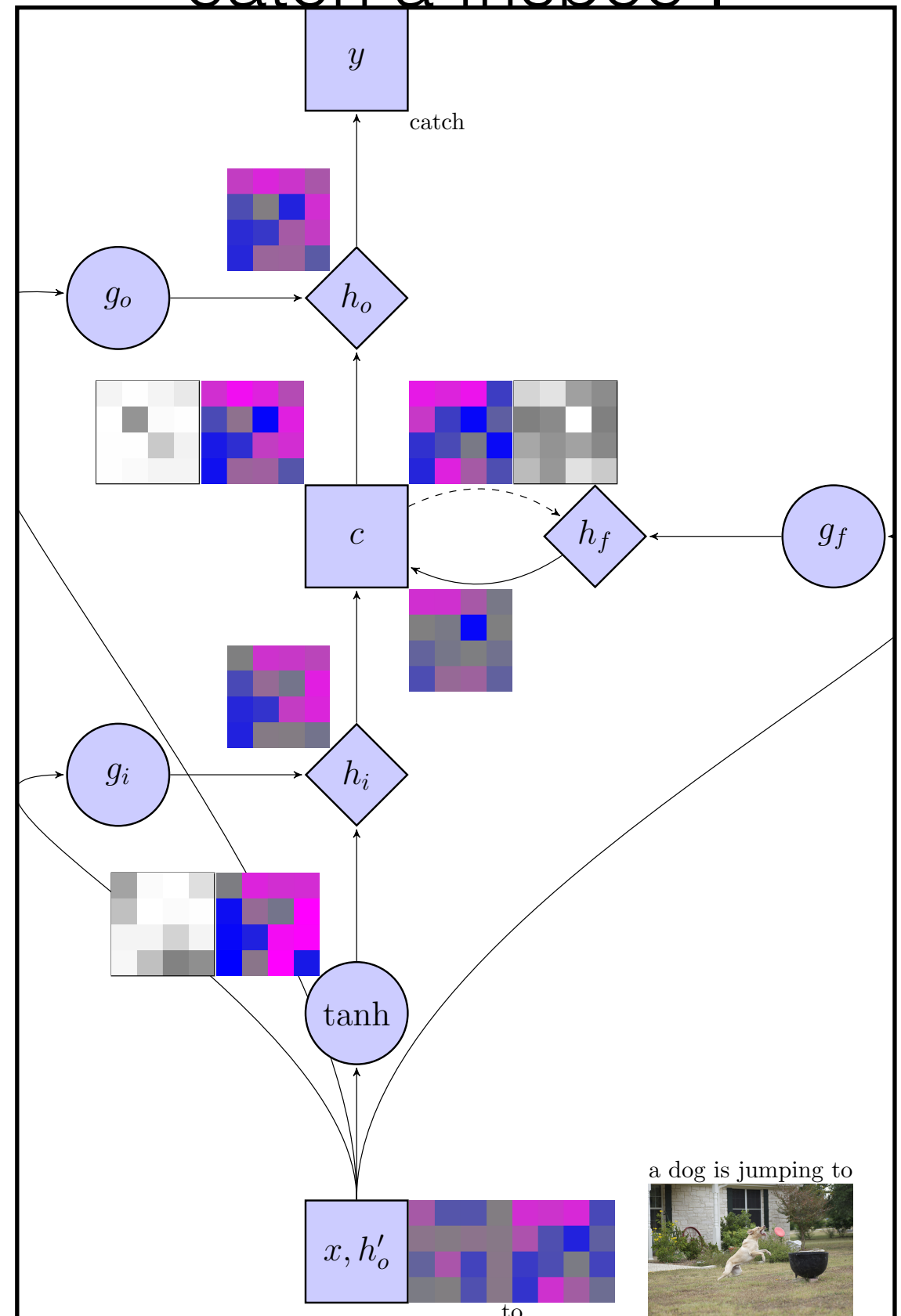
5

a dog **jumps** to
catch a frisbee .



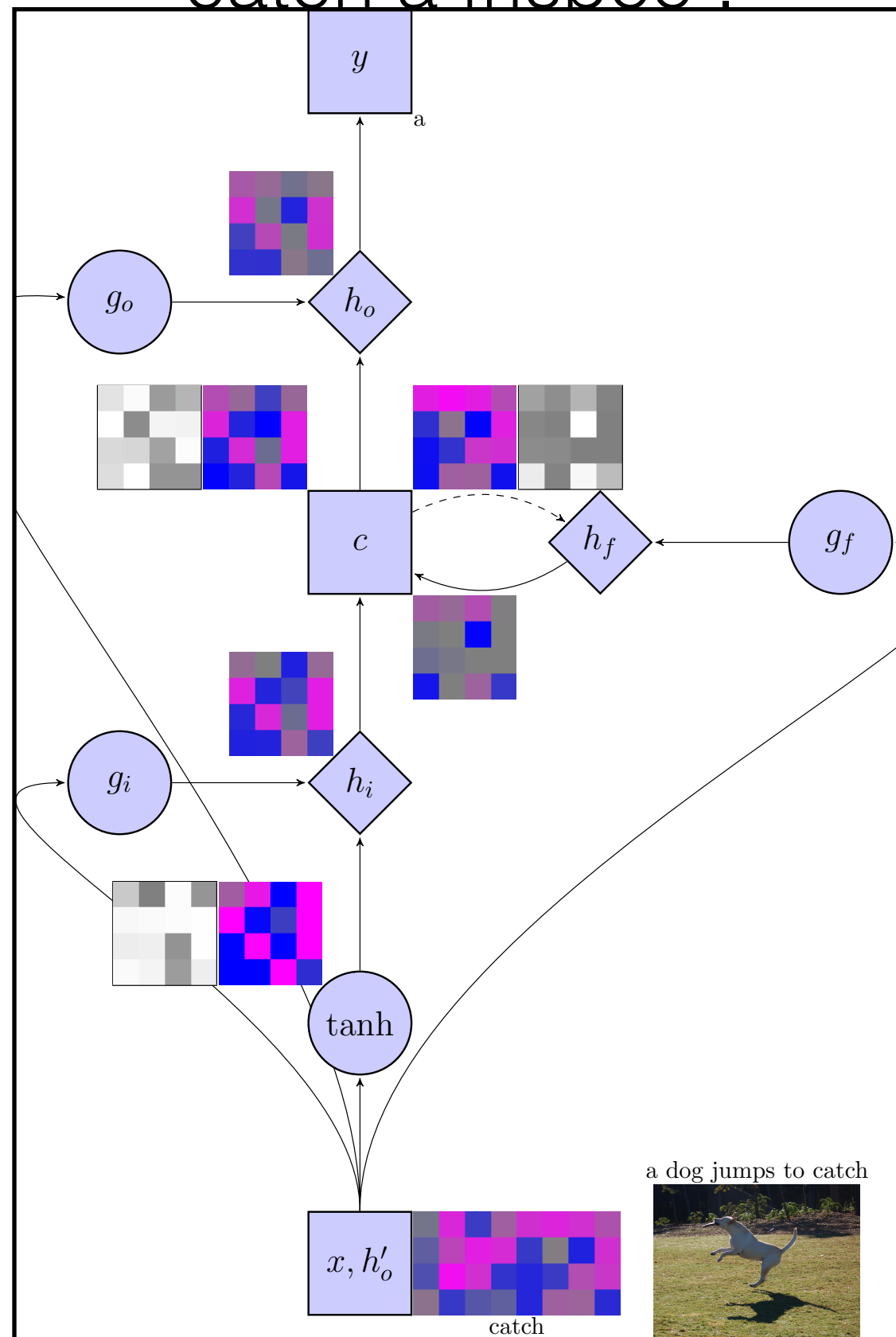
5

a dog **is jumping** to
catch a frisbee .



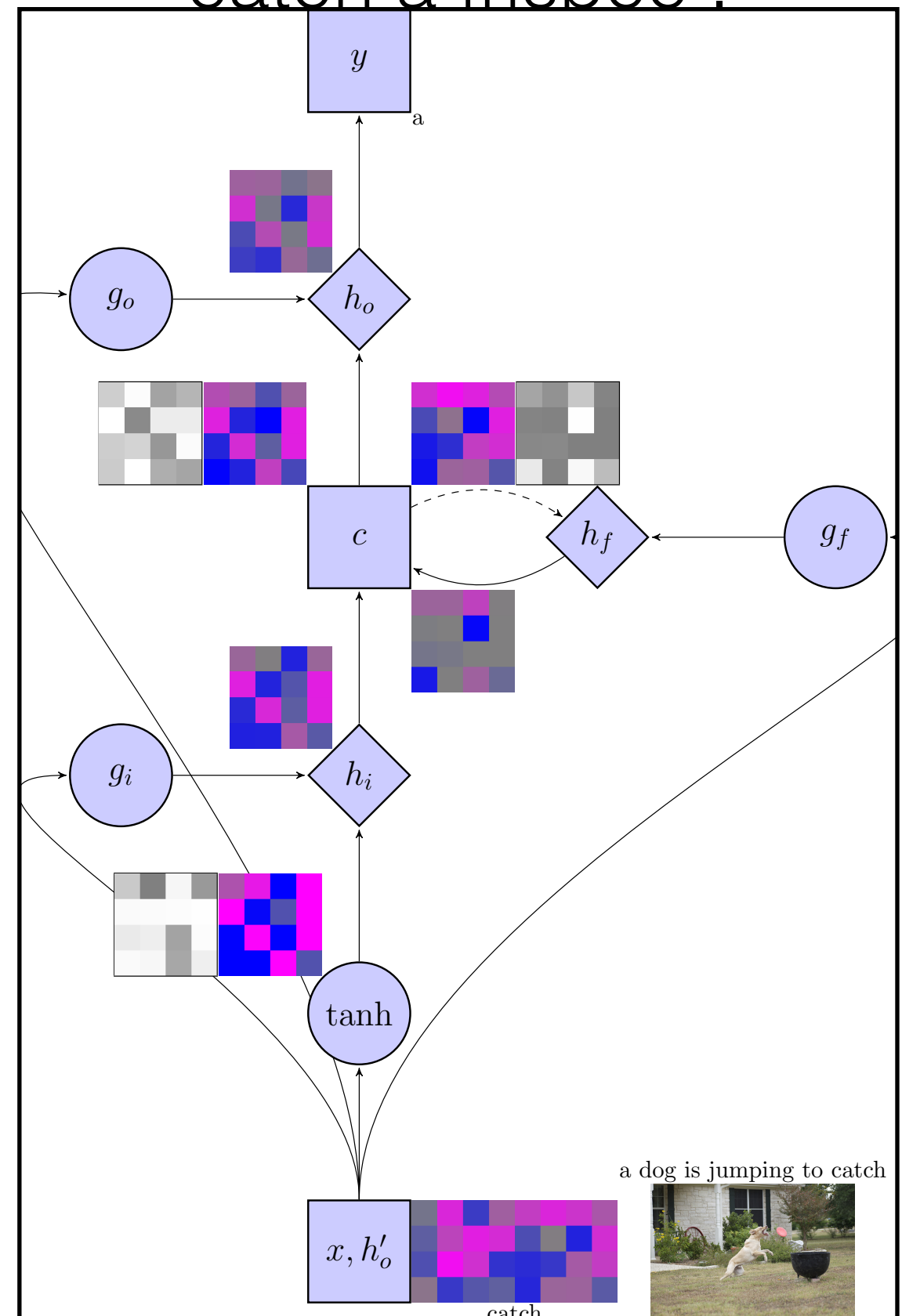
6

a dog **jumps** to
catch a frisbee .



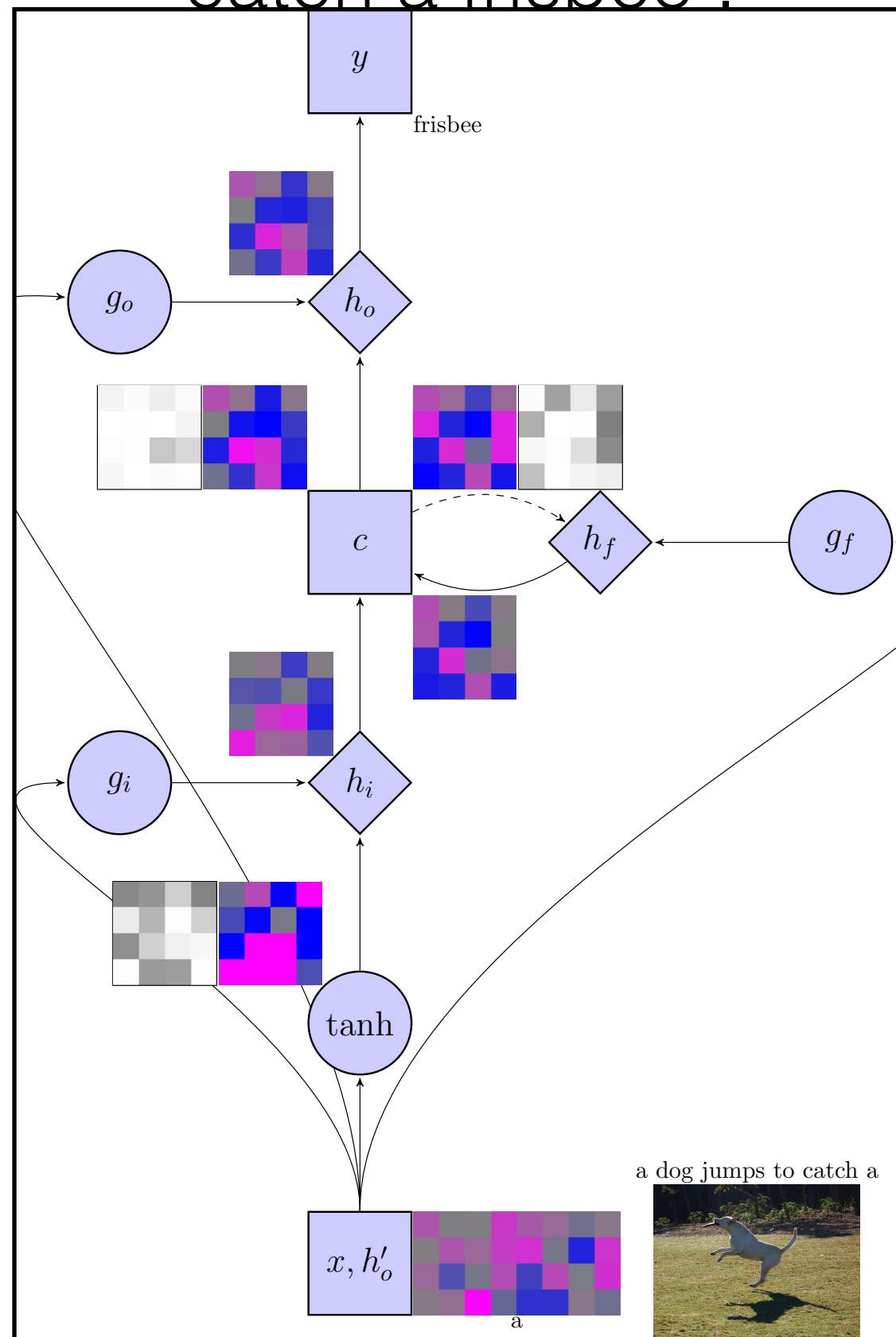
6

a dog **is jumping** to
catch a frisbee .



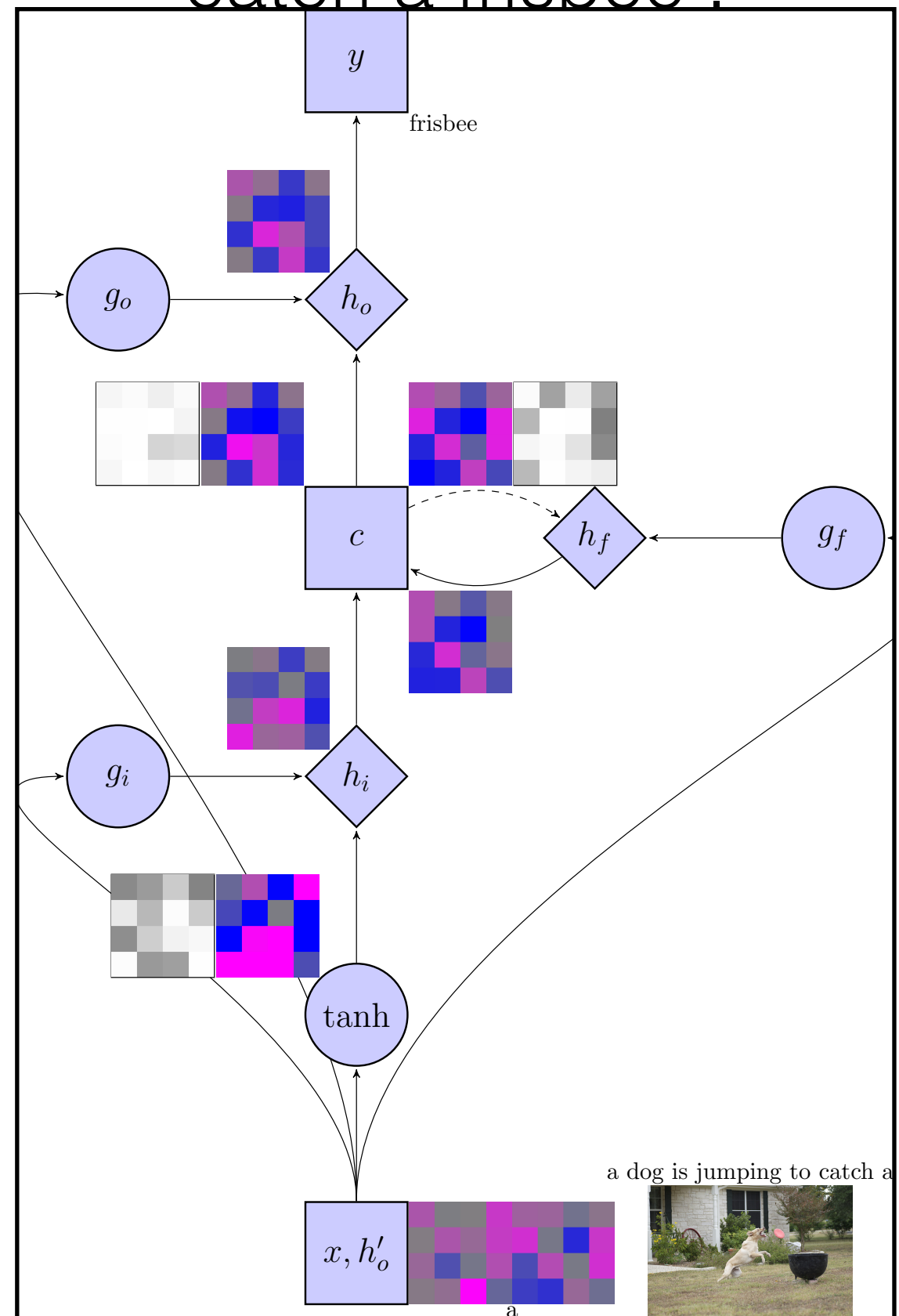
7

a dog **jumps** to
catch a frisbee .



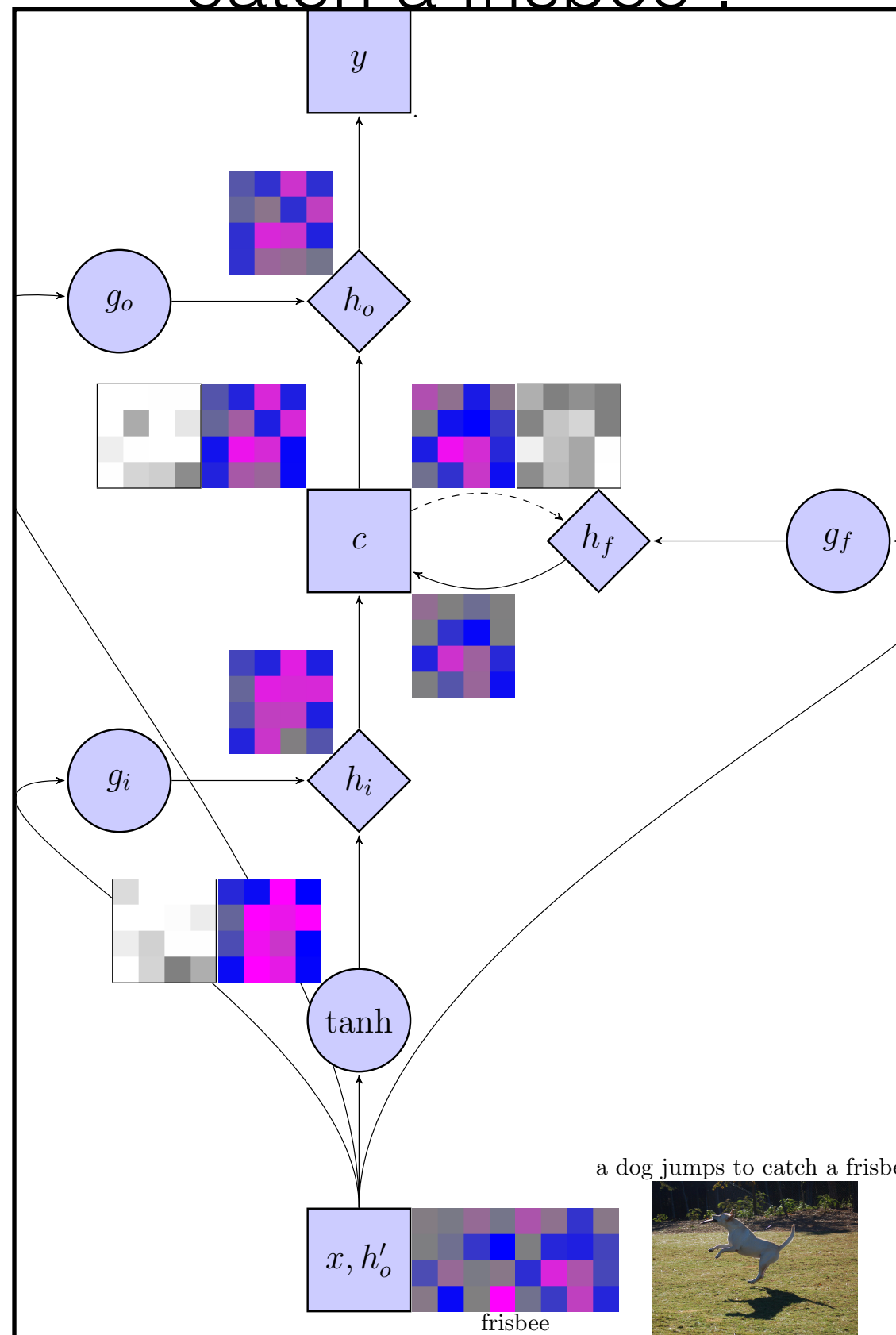
7

a dog **is jumping** to
catch a frisbee .



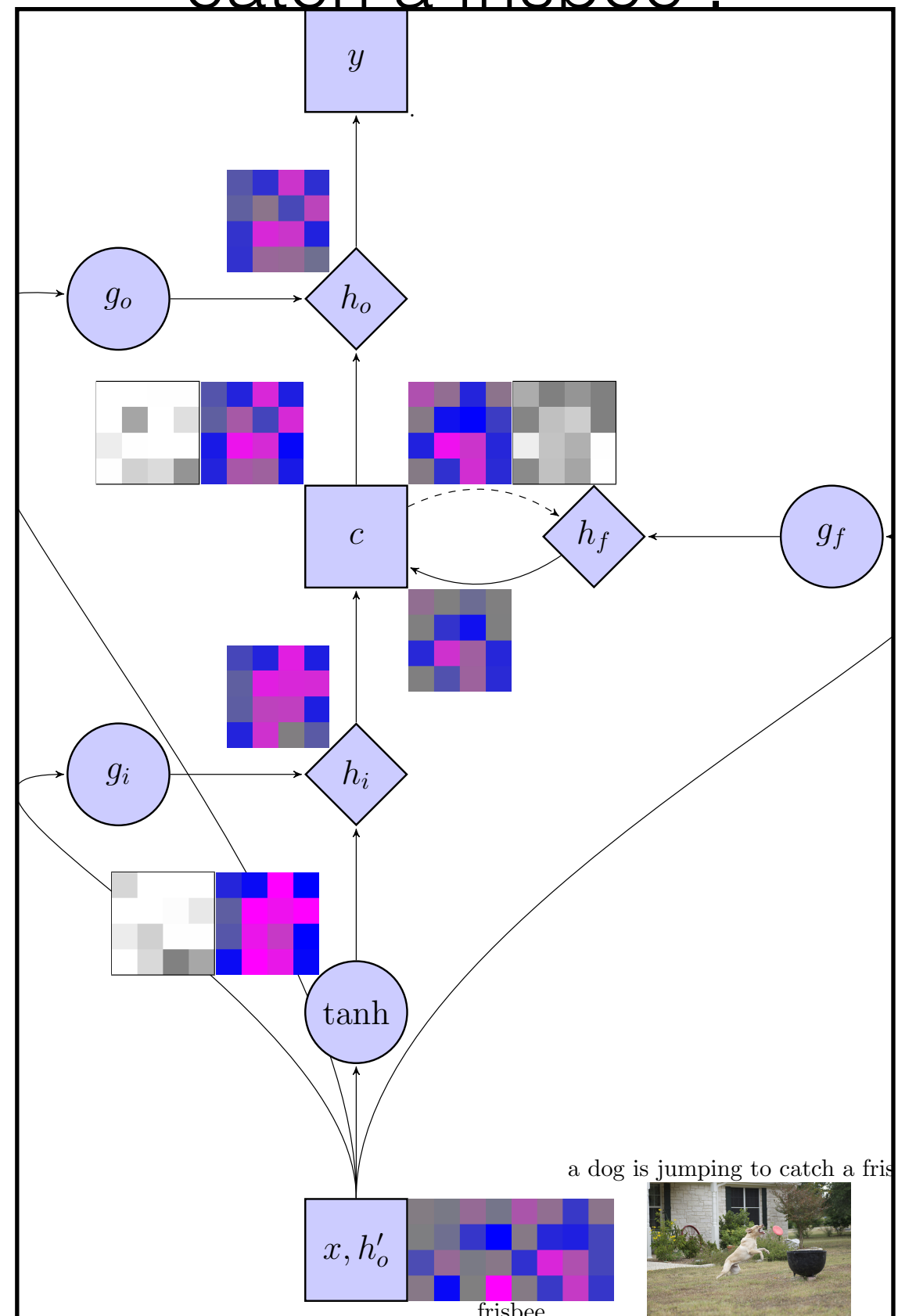
8

a dog **jumps** to
catch a frisbee .



8

a dog **is jumping** to
catch a frisbee .



9

a black dog is jumping to catch a frisbee .



a dog is jumping to catch a frisbee .

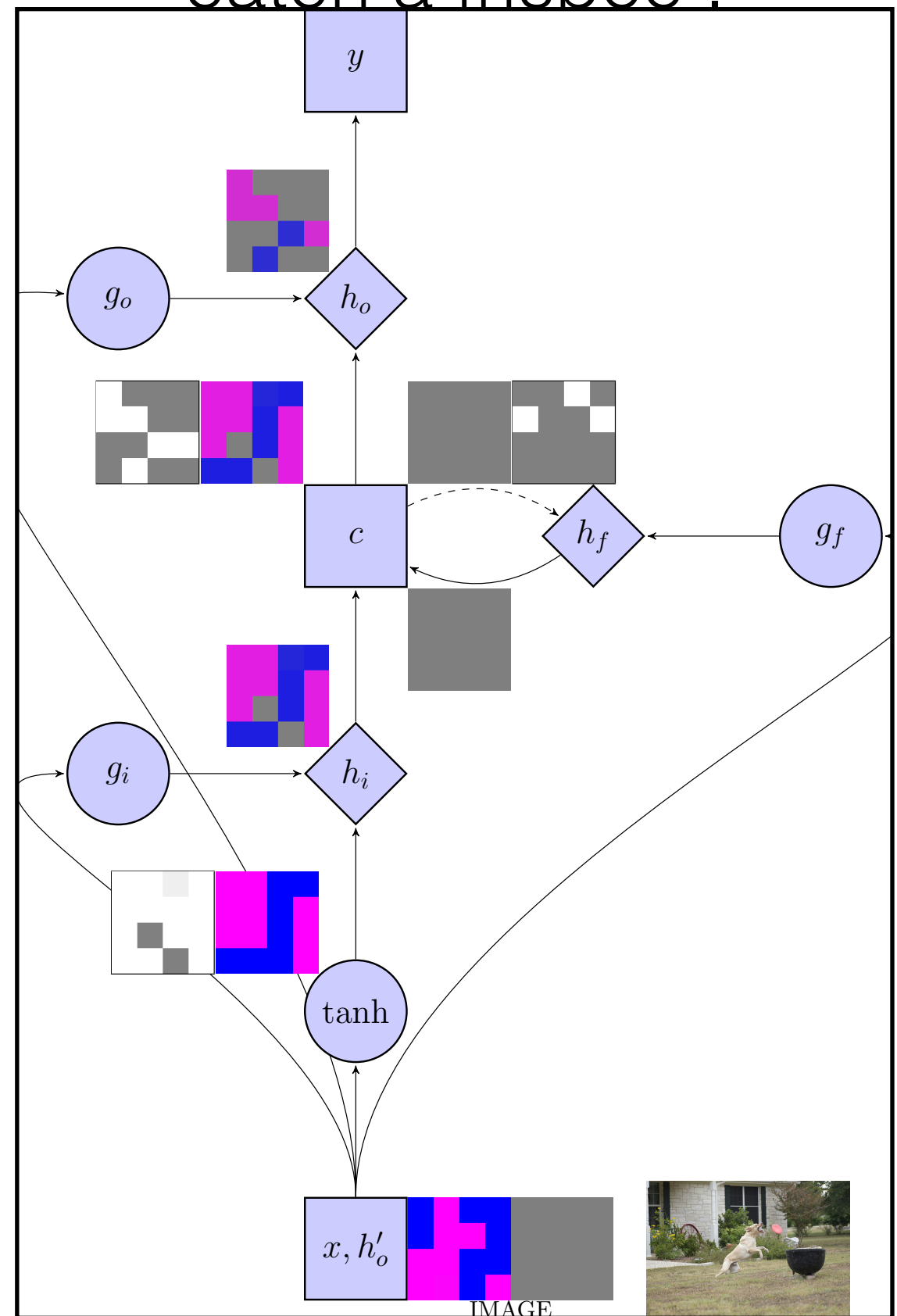


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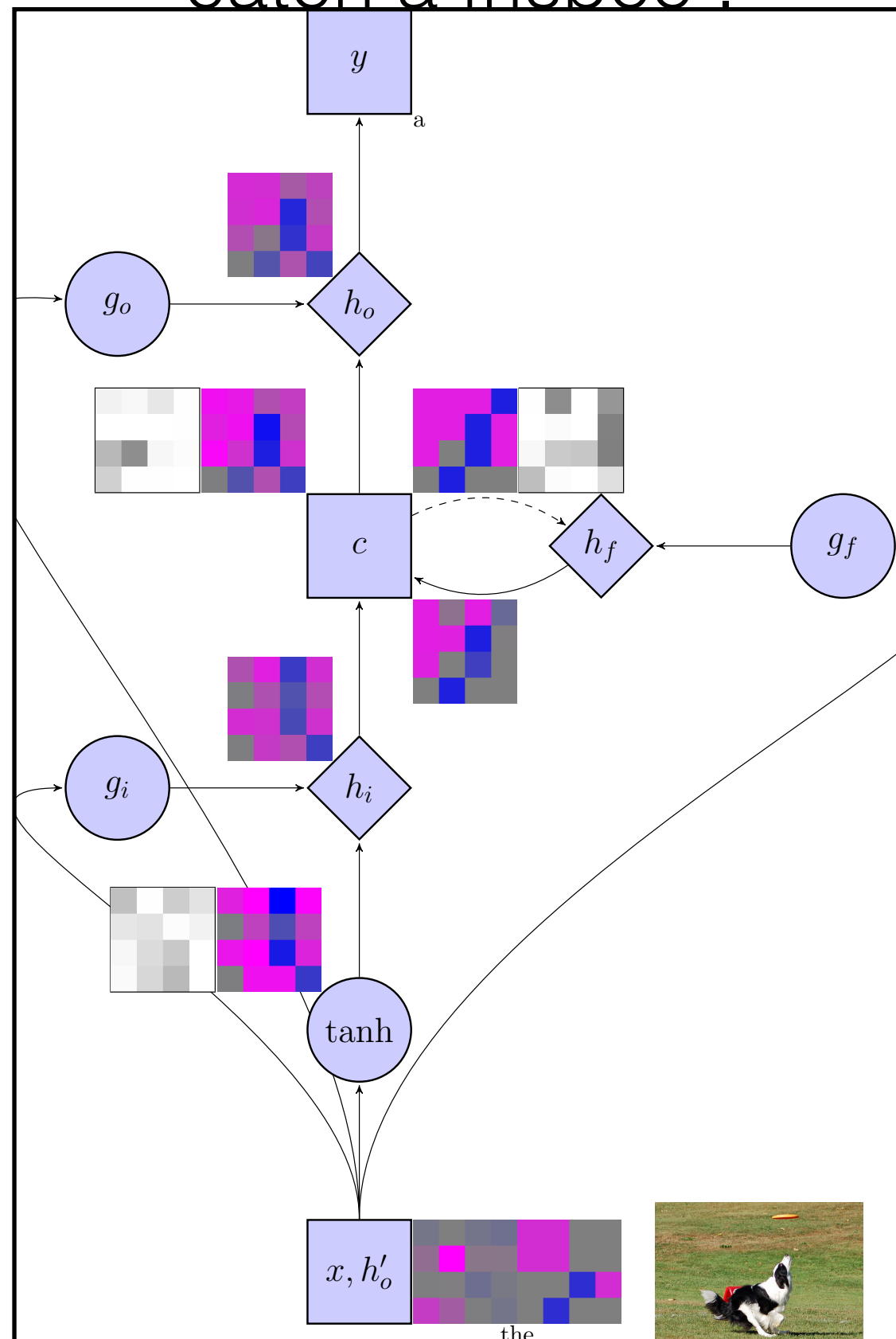
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0

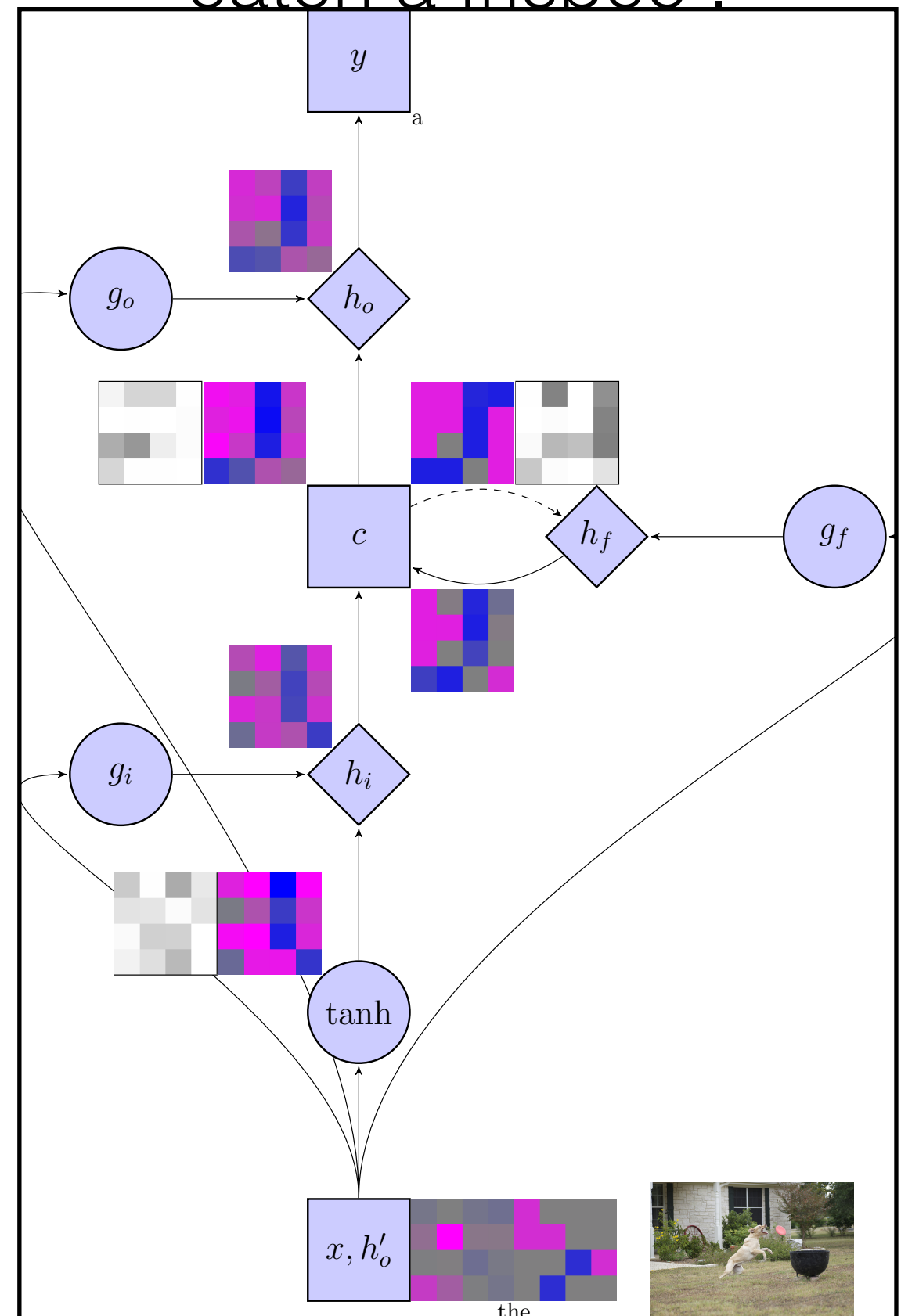


a **black dog** is jumping to catch a frisbee .



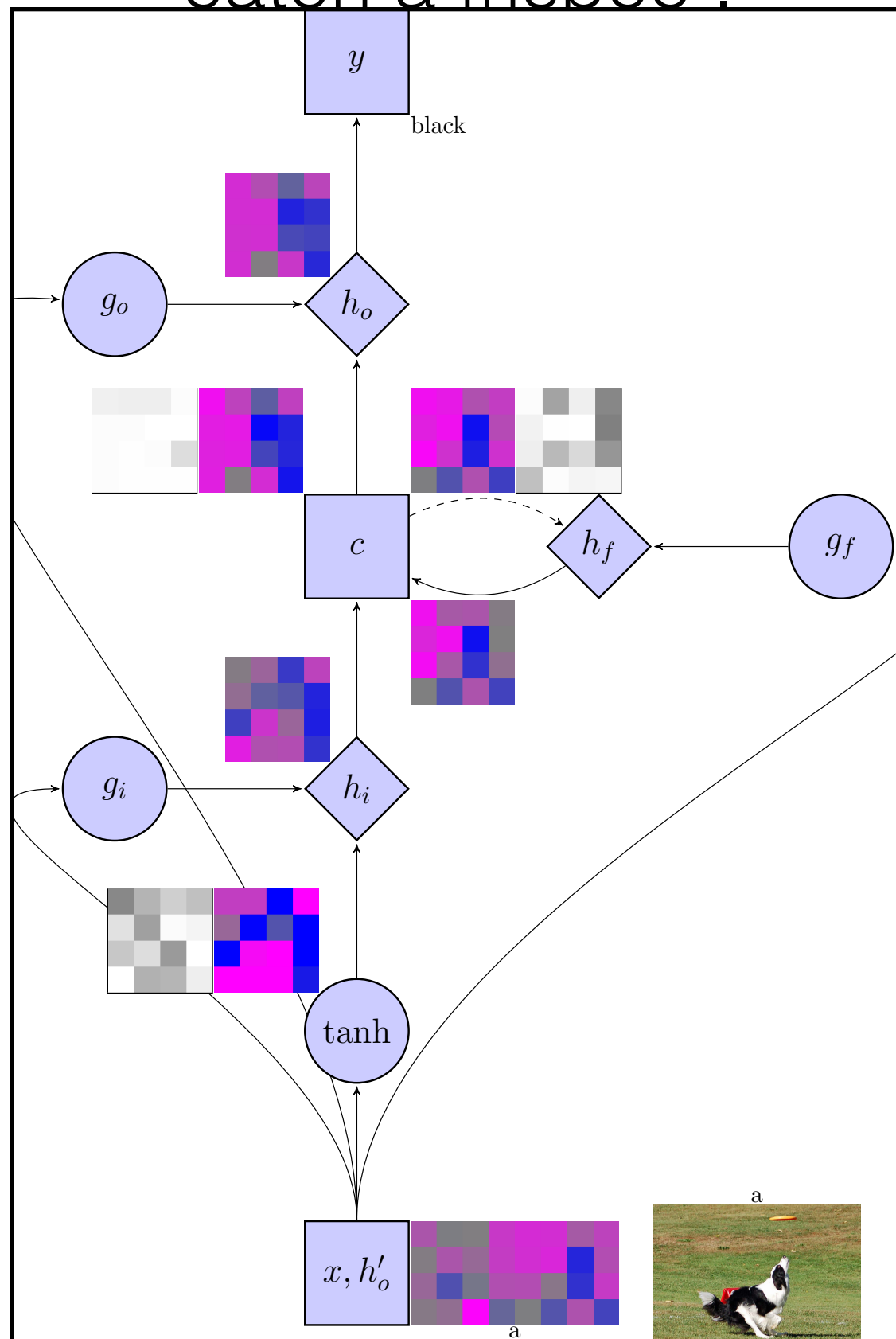
1

a **dog** is jumping to catch a frisbee .



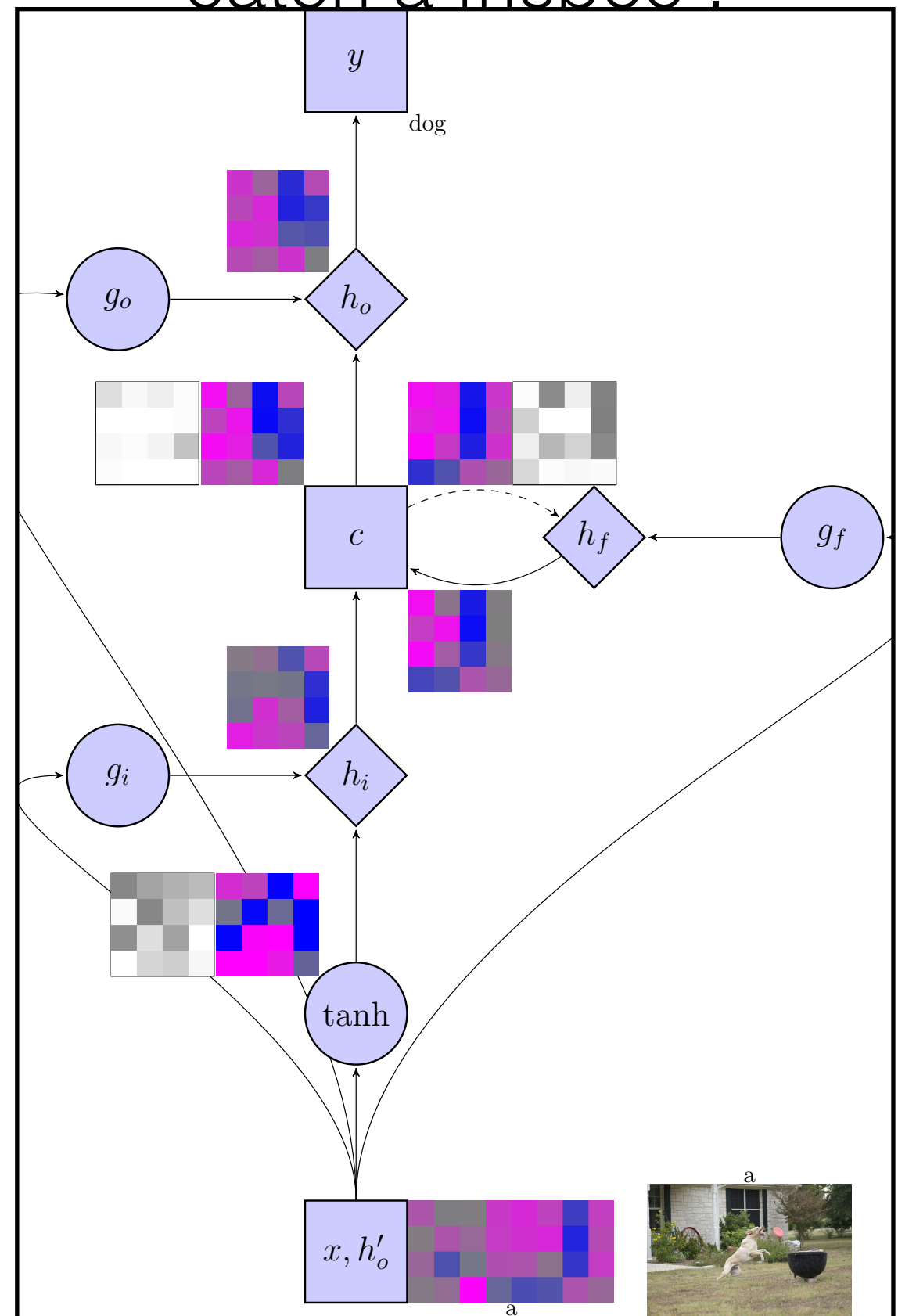
1

a **black dog** is jumping to catch a frisbee .



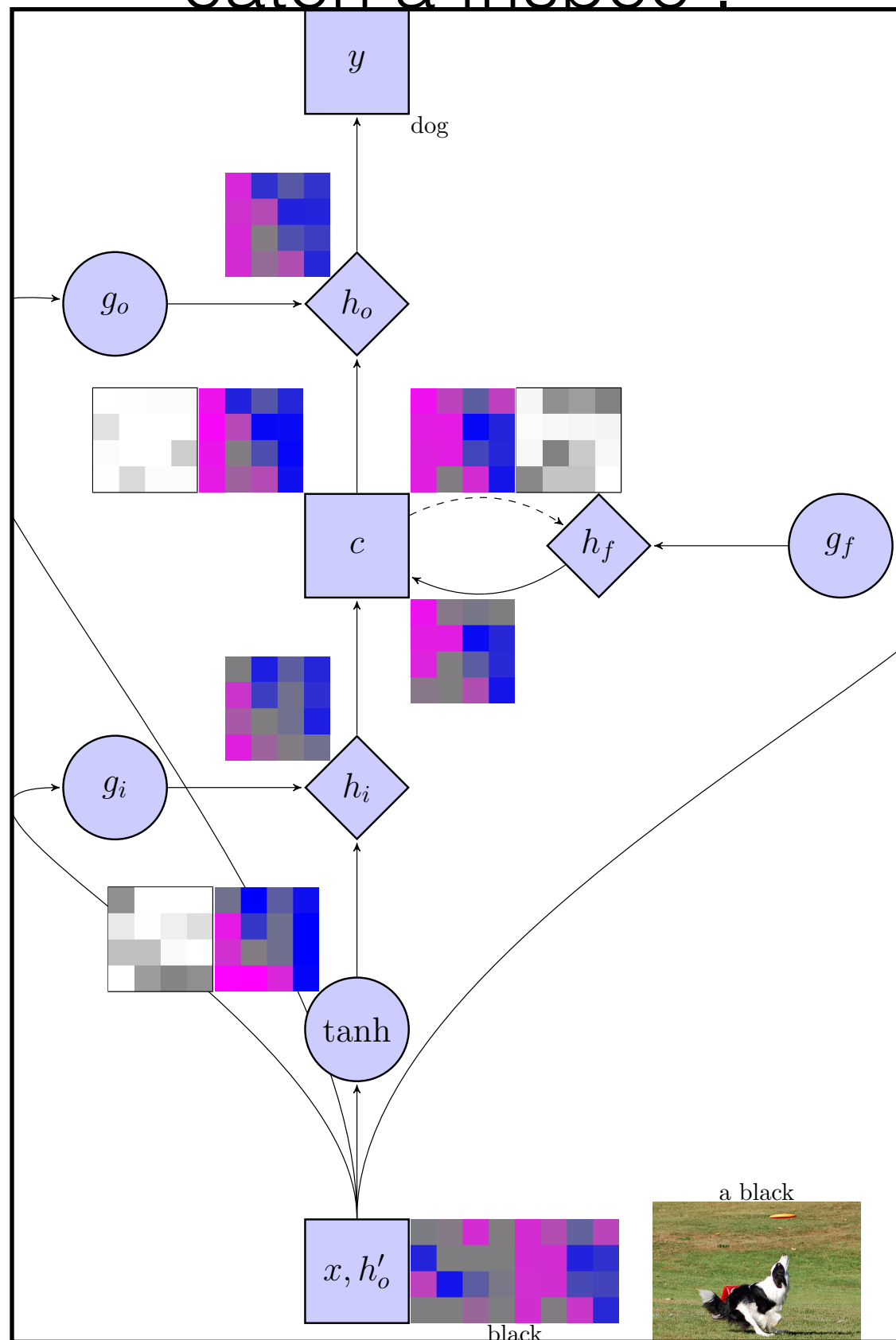
2

a **dog** is jumping to catch a frisbee .



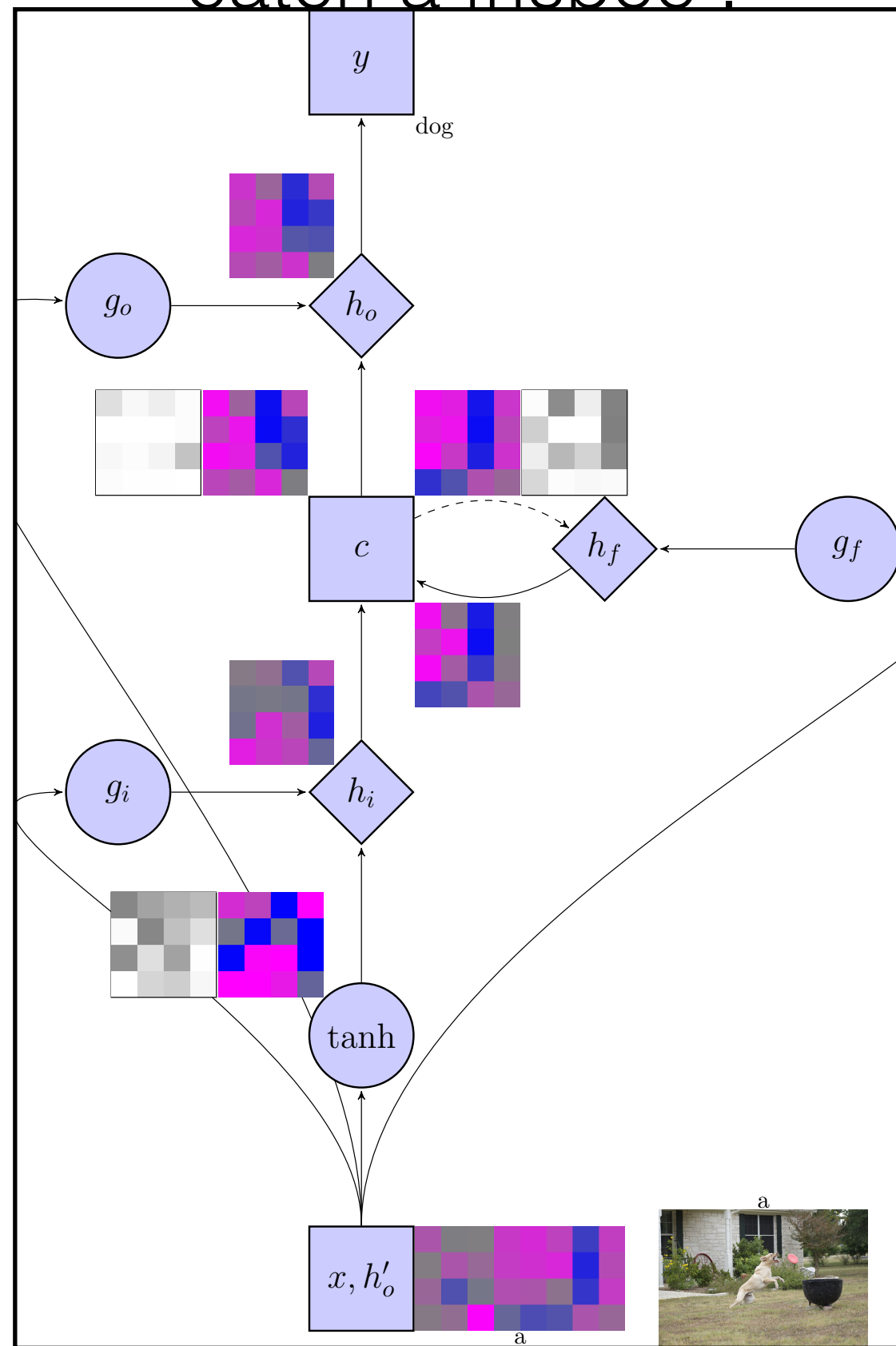
2

a **black dog** is jumping to catch a frisbee .



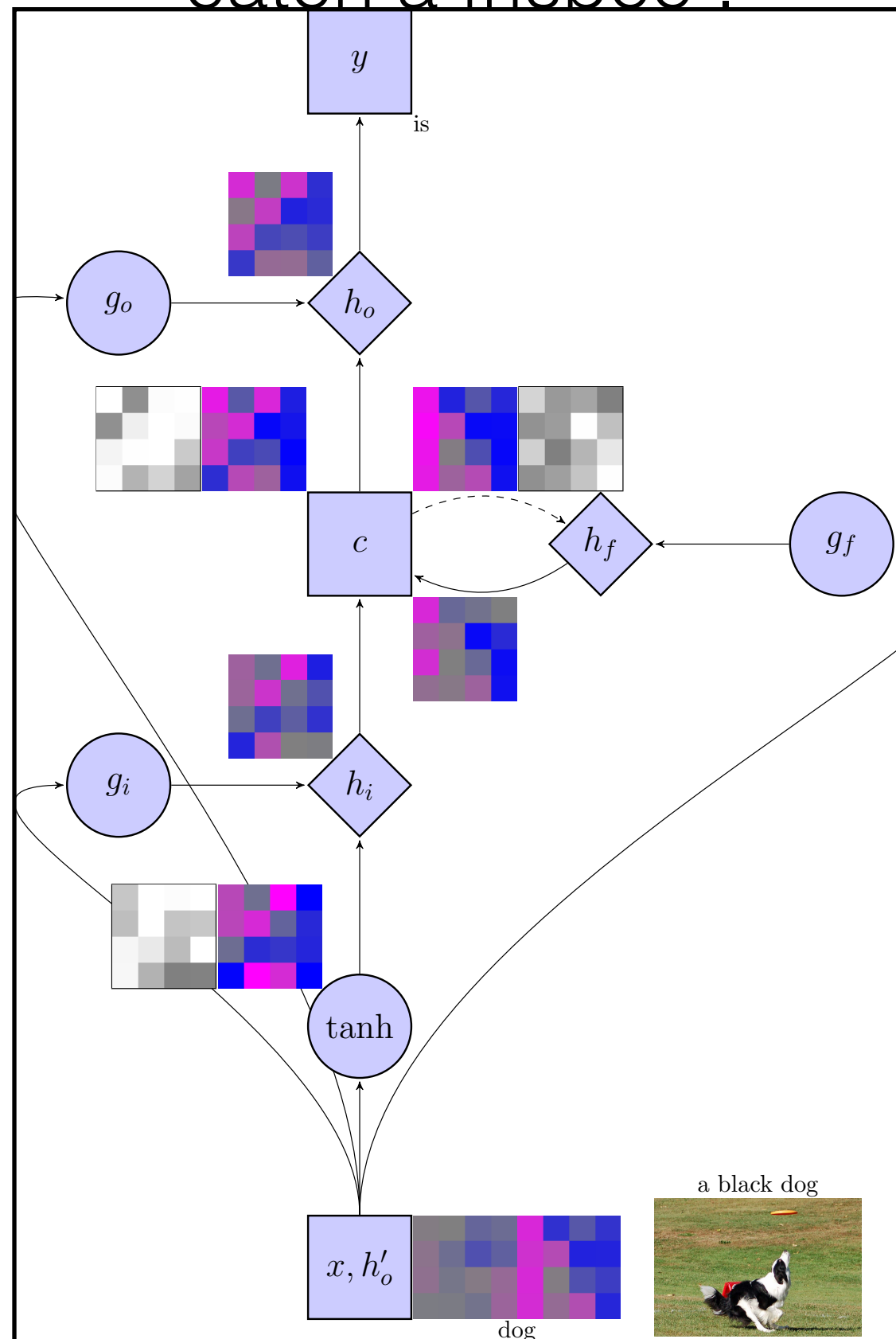
3

a **dog** is jumping to catch a frisbee .



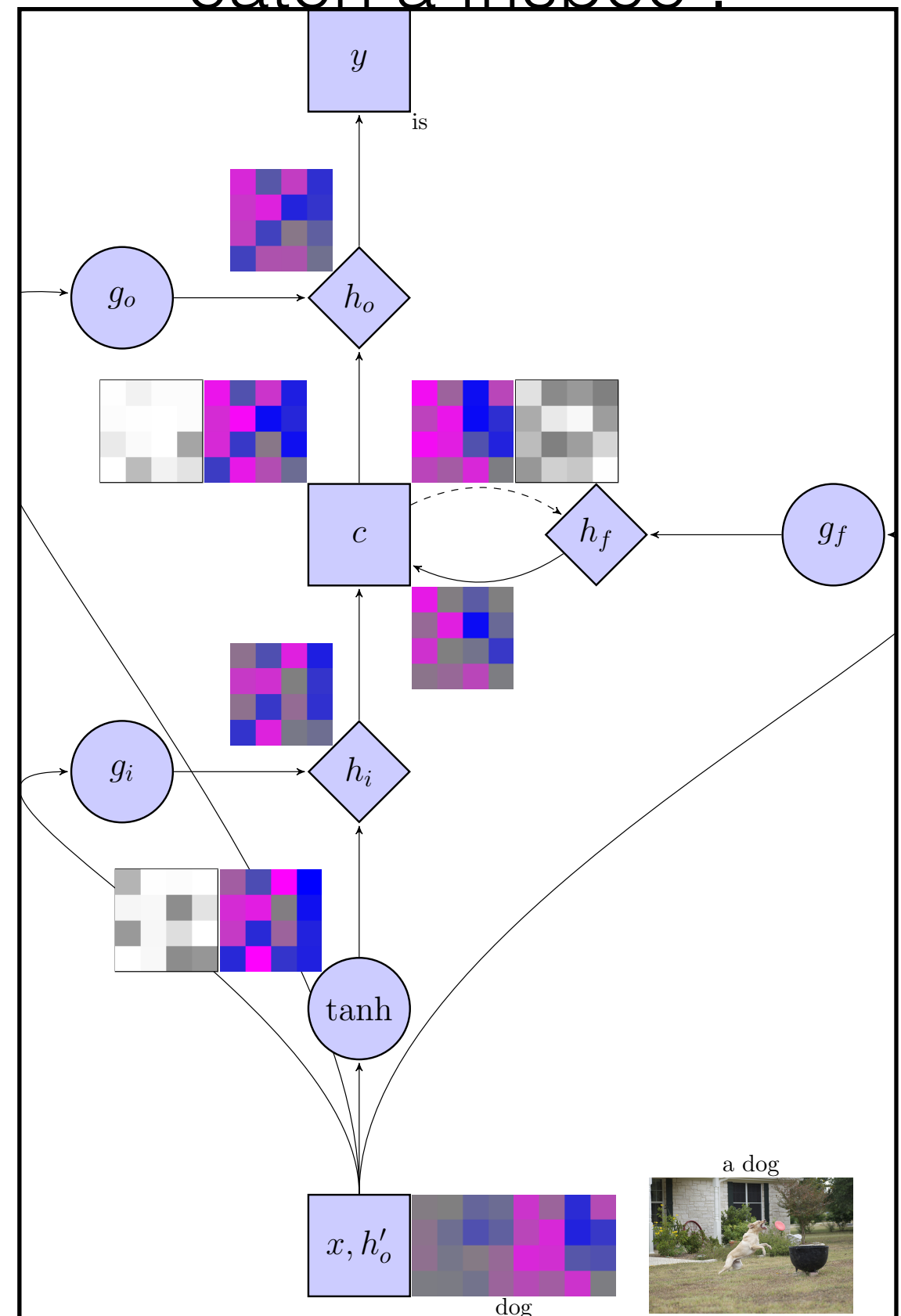
2

a **black dog** is jumping to catch a frisbee .



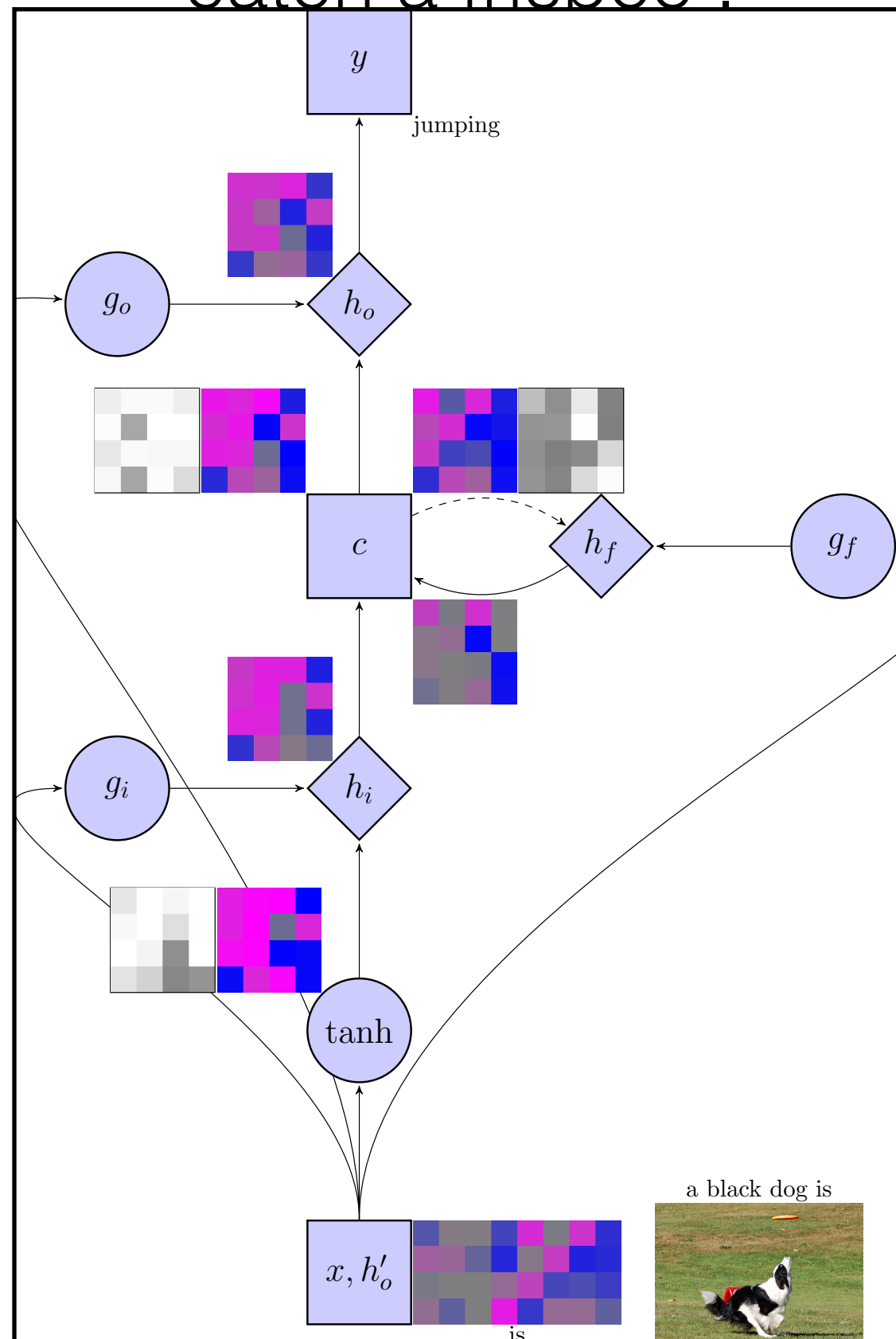
4

a **dog** is jumping to catch a frisbee .



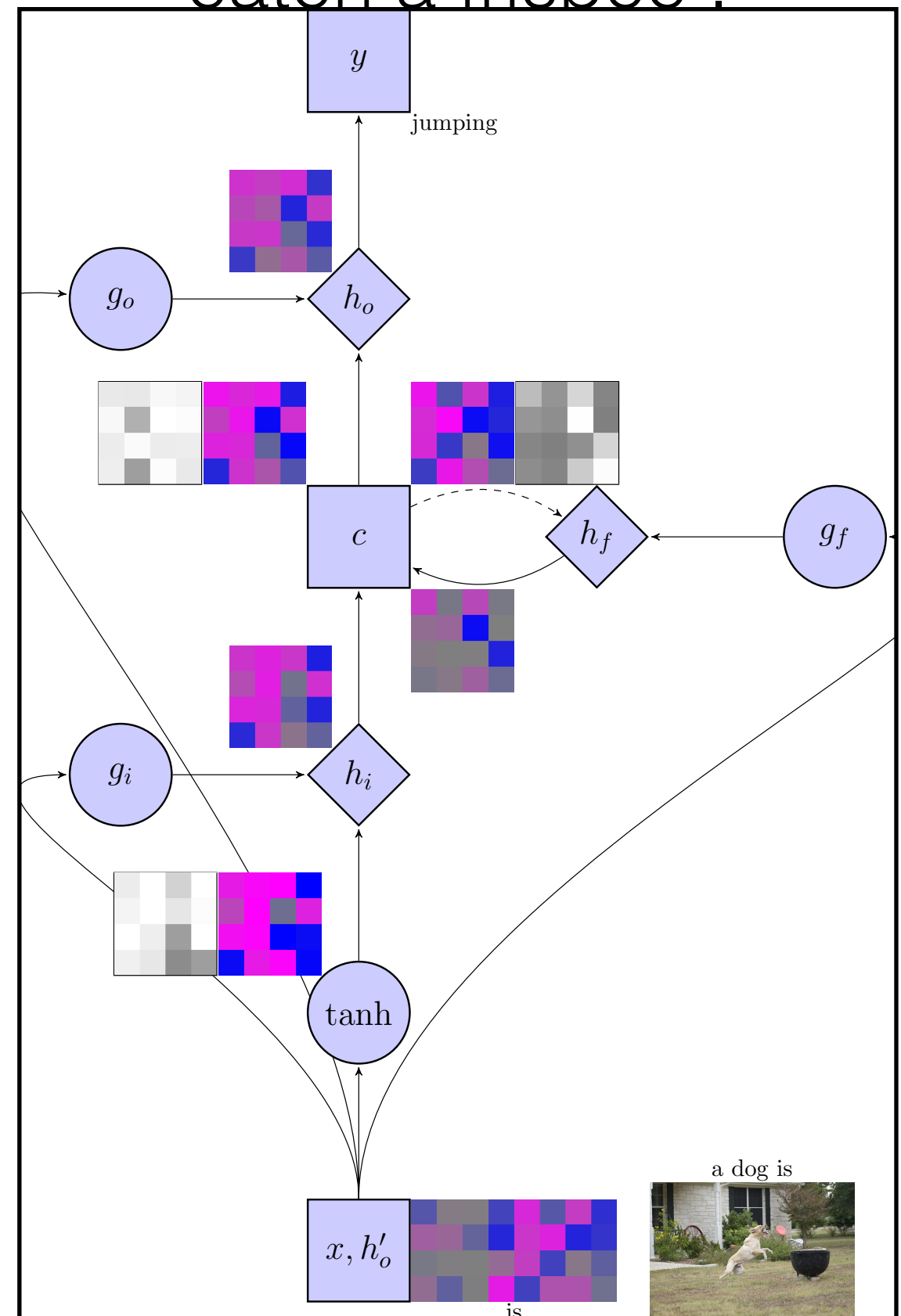
3

a **black dog** is jumping to catch a frisbee .



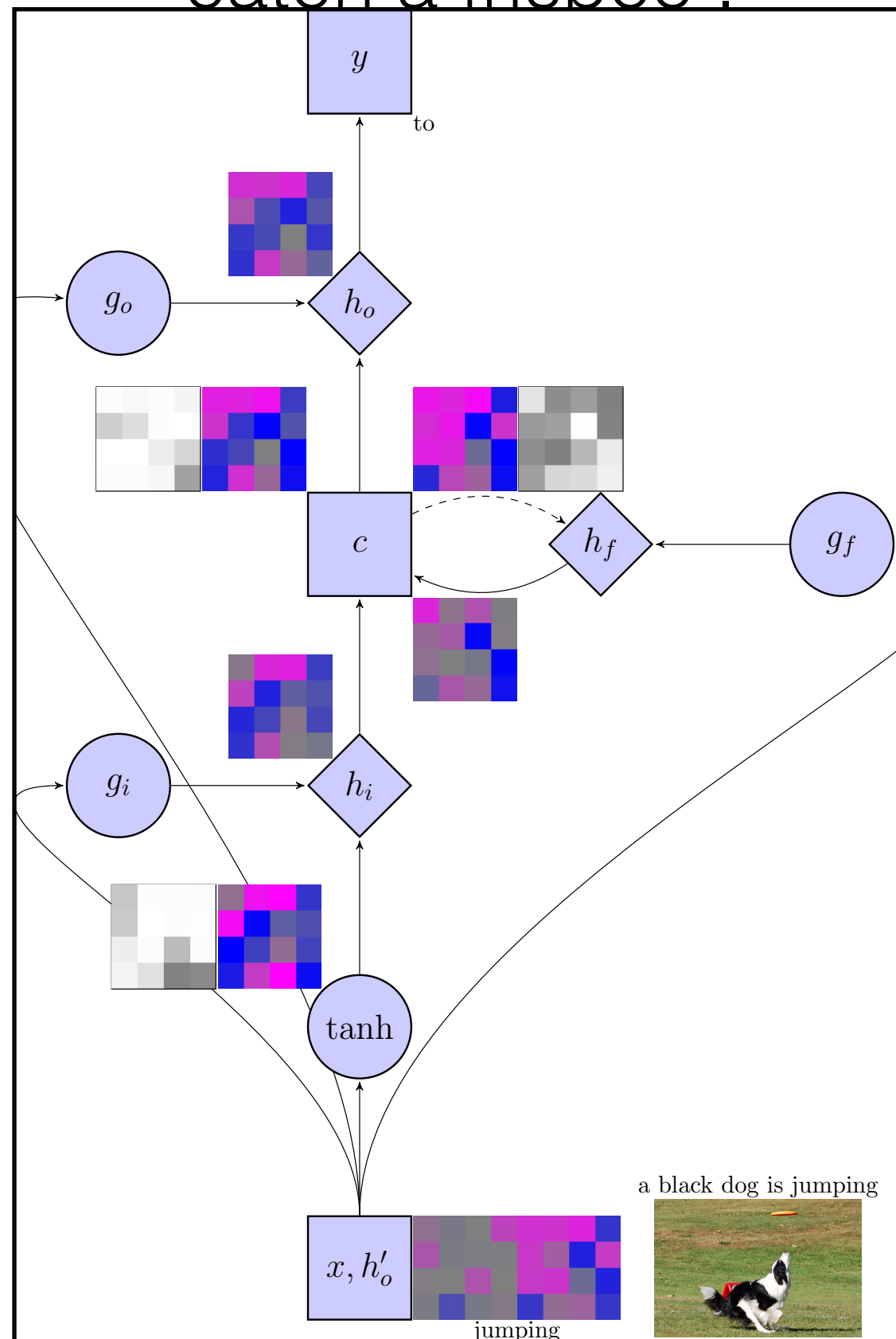
5

a **dog** is jumping to catch a frisbee .



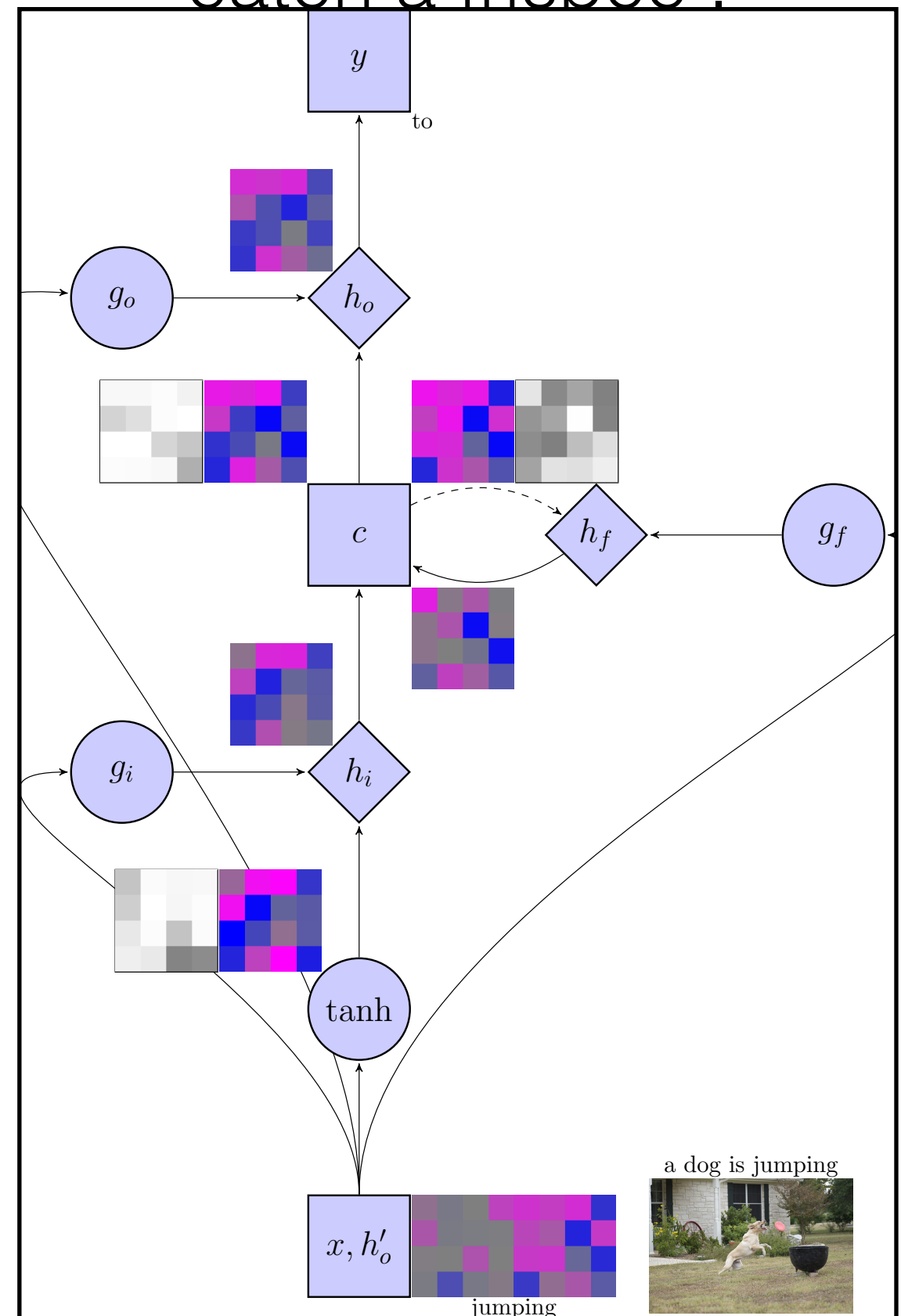
4

a **black dog** is jumping to
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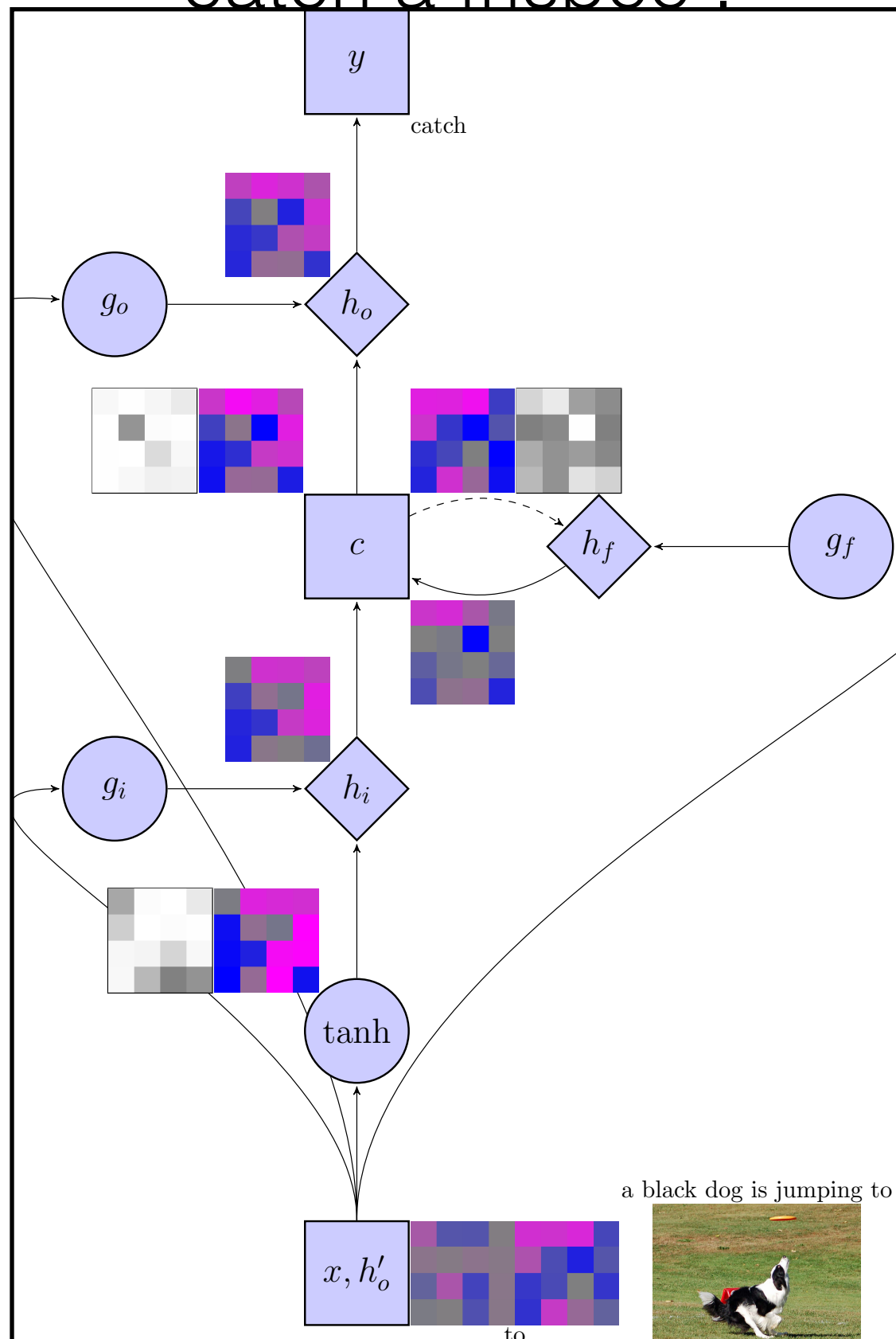
6

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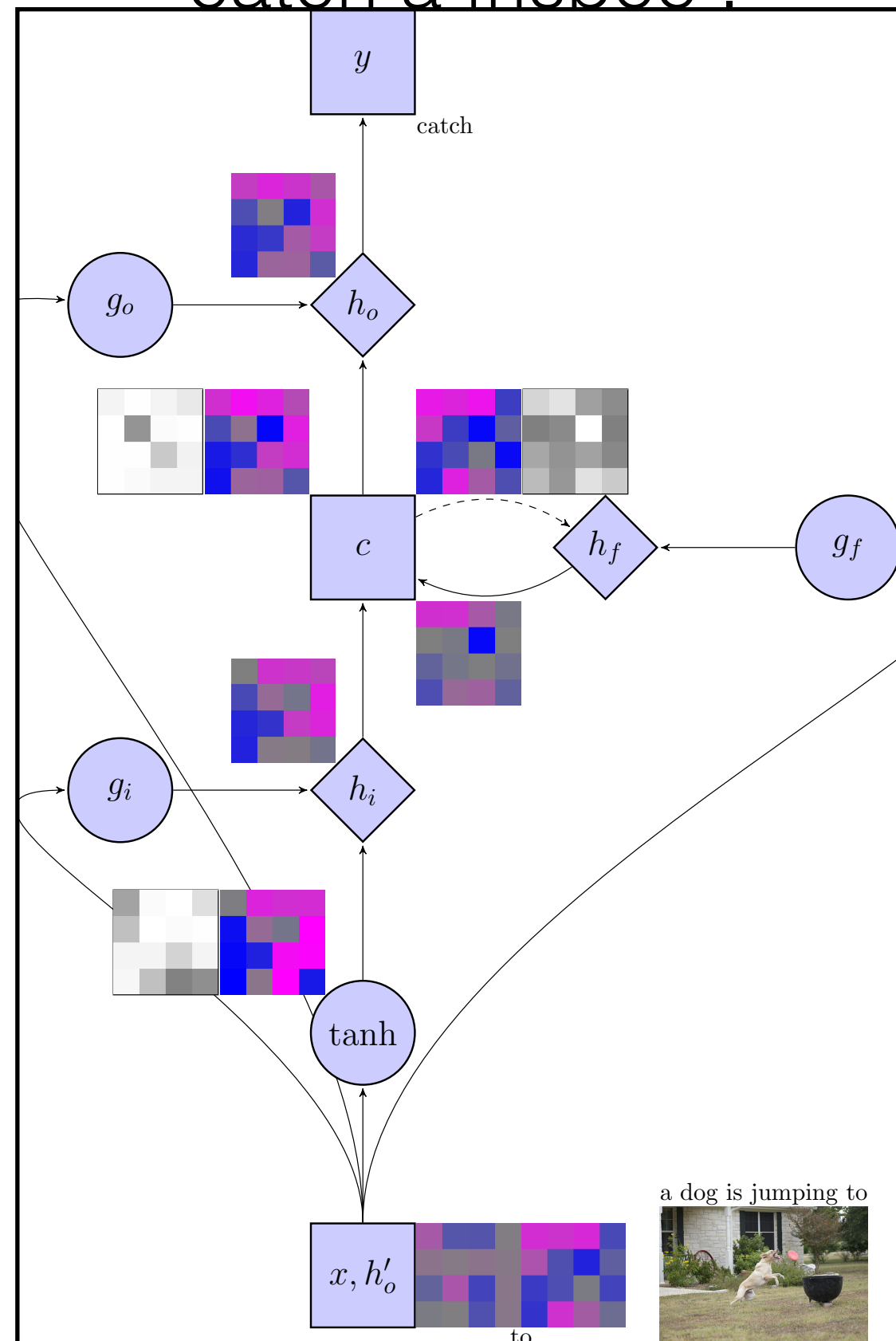
5

a **black dog** is jumping to
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7

a **dog** is jumping to
catch a frisbee .

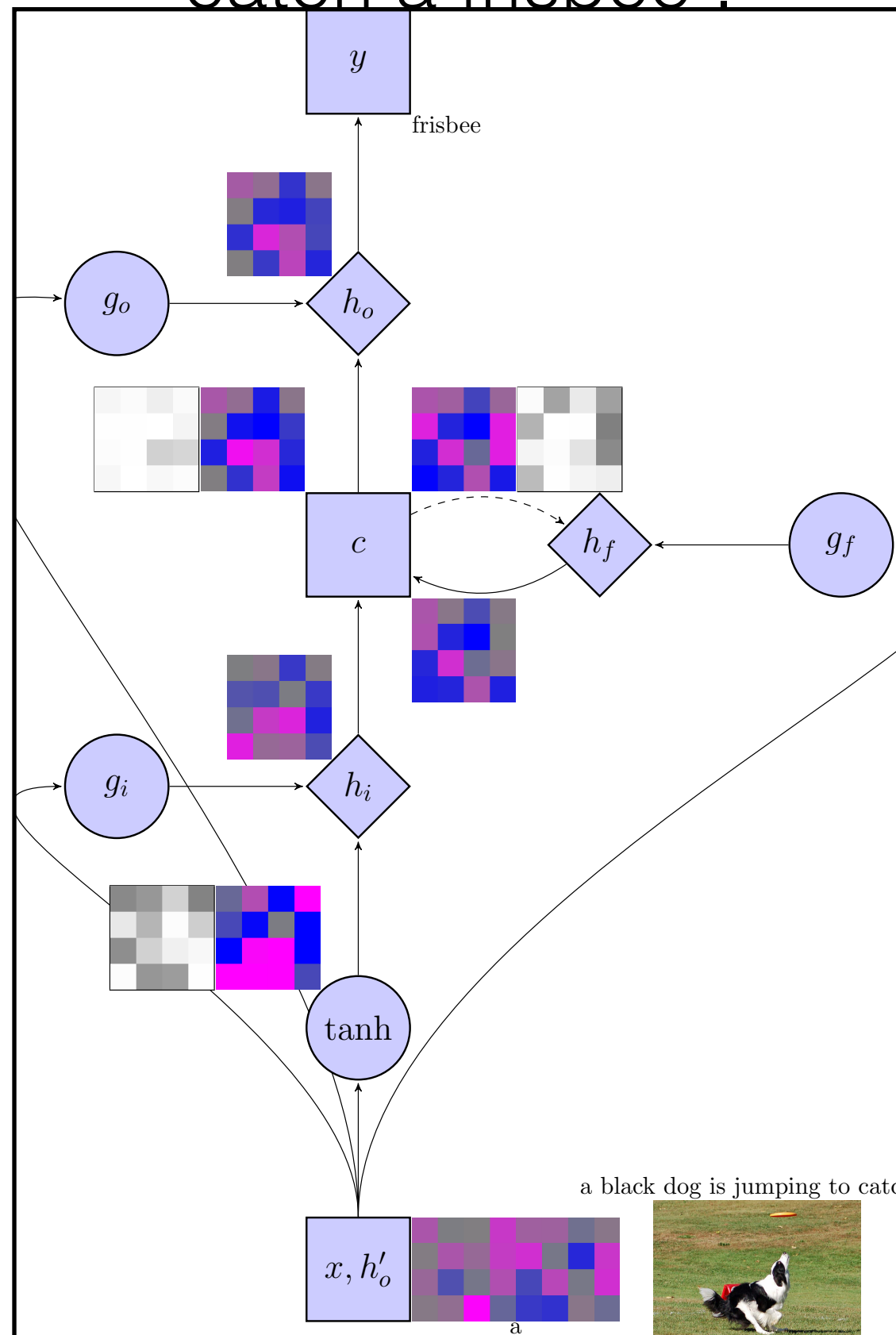


6

8

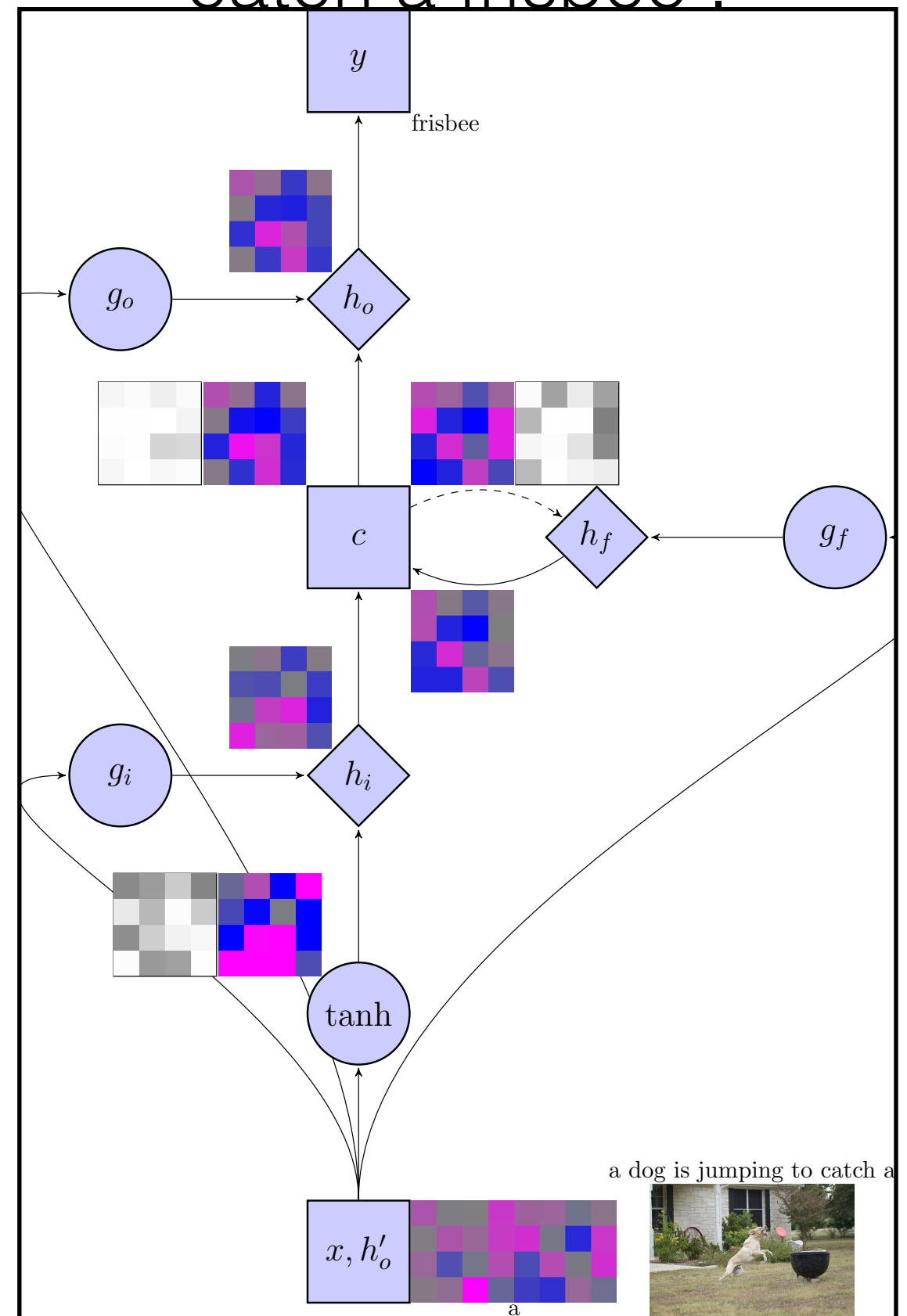
7

a **black dog** is jumping to catch a frisbee .



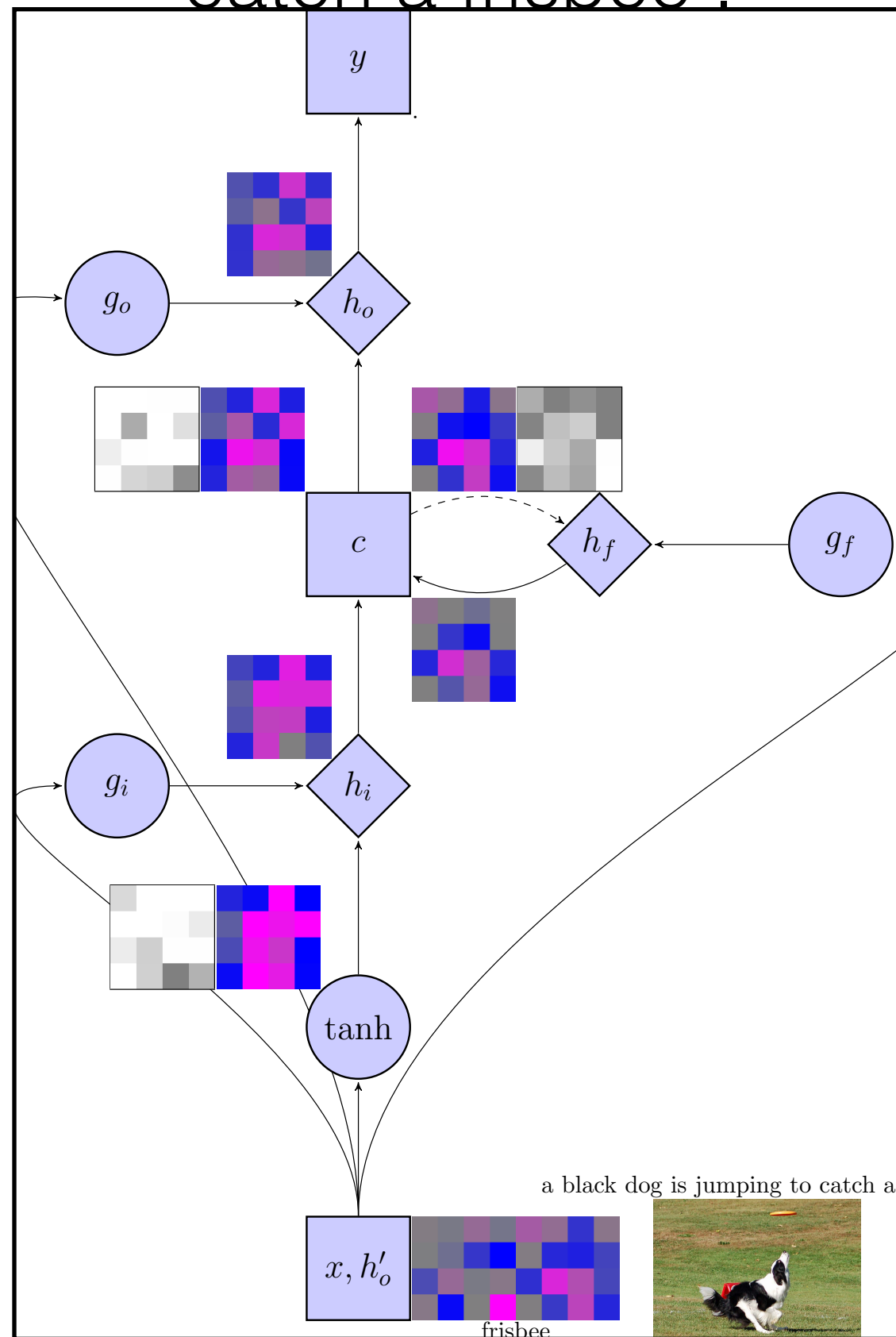
9

a **dog** is jumping to catch a frisbee .



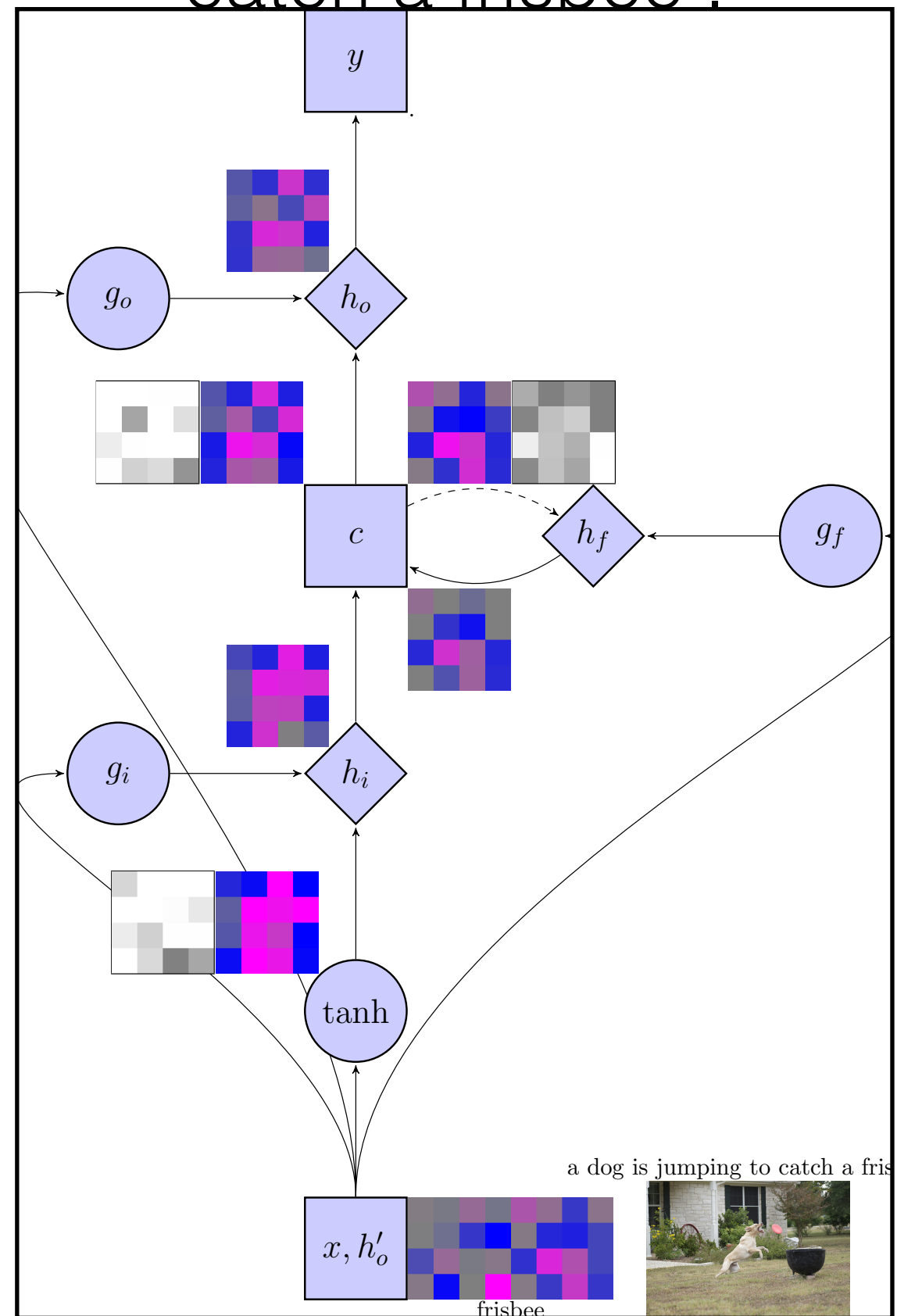
8

a **black dog** is jumping to catch a frisbee .



10

a **dog** is jumping to catch a frisbee .



9

Why all dogs end with “frisbee”?

Count last word in training sentences with “dog” and “frisbee”:

86 frisbee	6 yard	4 it	2 other
30 mouth	6 disc	4 ground	2 mouths
15 snow	6 air	4 fence	2 man
15 grass	5 watches	4 beach	2 legs
11 field	5 midair	3 road	2 hand
11 dog	5 background	3 object	2 dogs
8 toy	4 watch	3 boat	1 underfoot
7 water	4 park	3 ball	1 ...

a man in a blue shirt is riding a bike on a dirt track .



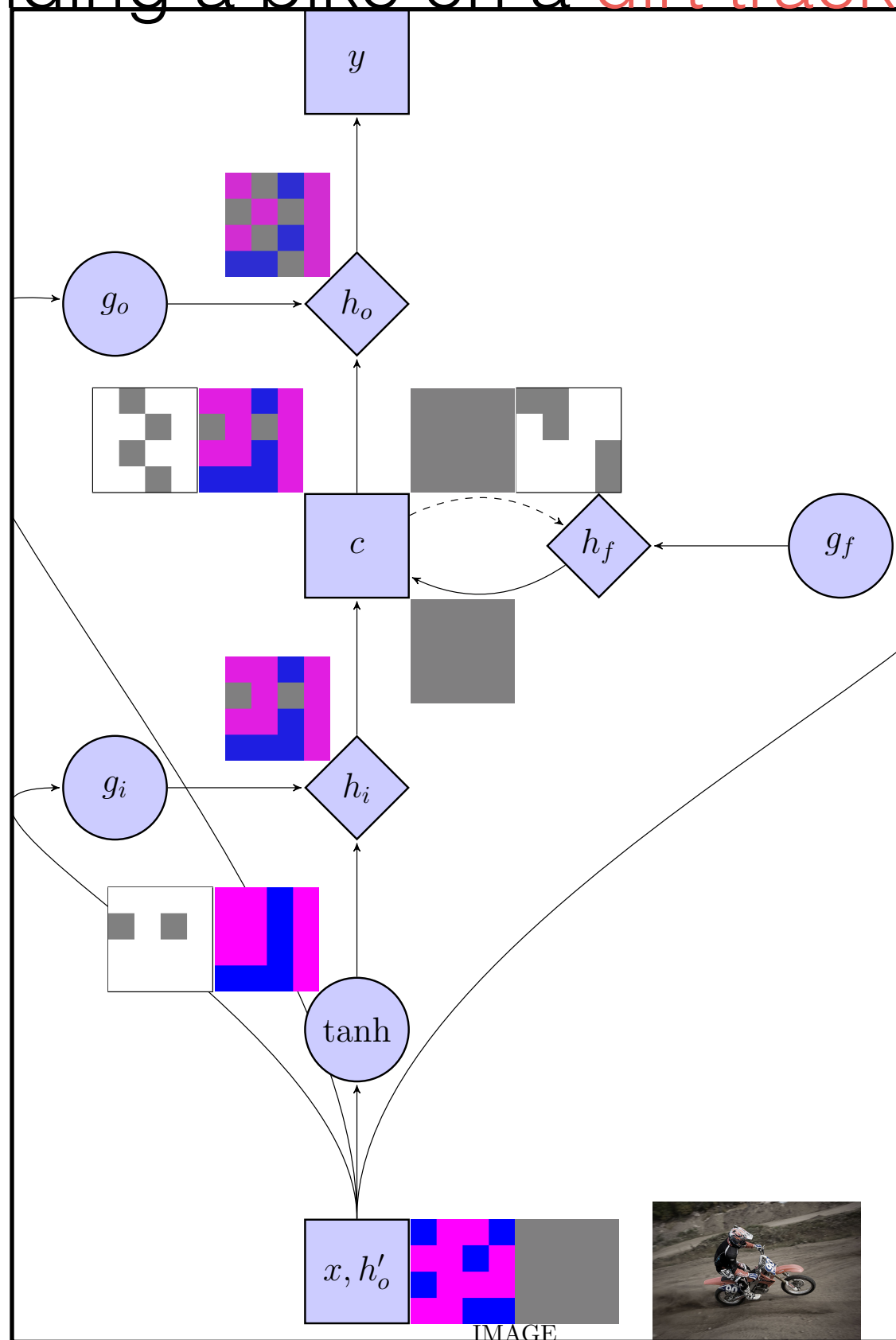
2891617125_f939f604c7.jpg

a man in a blue shirt is riding a bike on a ramp .



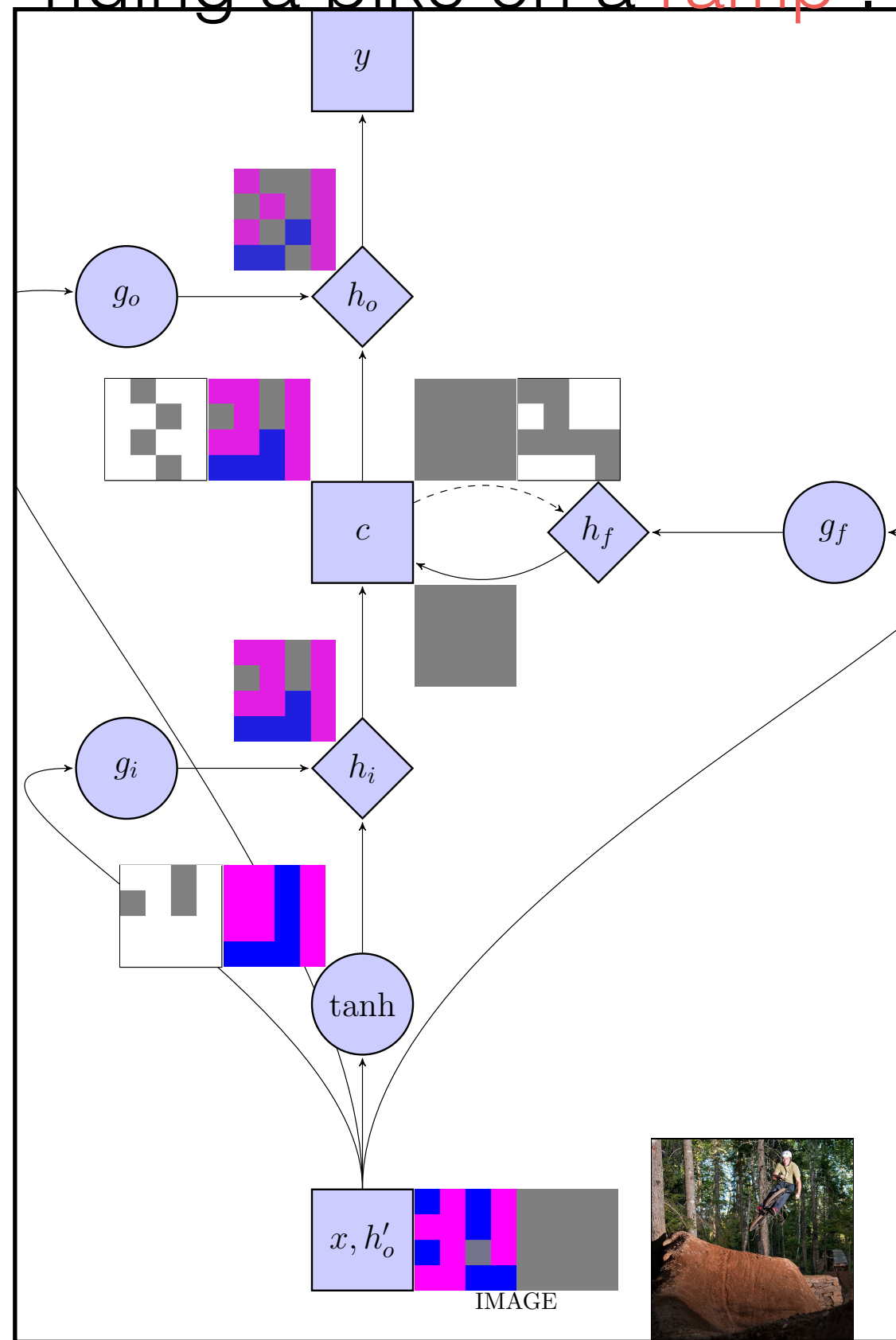
3640422448_a0f42e4559.jpg

a man in a blue shirt is riding a bike on a dirt track .



0

a man in a blue shirt is riding a bike on a ramp .



0

the

Diagram illustrating a deep learning architecture for image captioning, showing the flow of data and the interaction between various components:

- Input:** A pair (x, h'_o) is provided, where x is a 4x4 grid of colored squares (magenta, blue, grey) and h'_o is a 4x4 grid of colored squares (magenta, blue, grey).
- Processing:** The input is processed by a \tanh activation function.
- Generators and Discriminators:** The output of the \tanh function is fed into two parallel paths:
 - Left Path:** A generator g_i and a discriminator h_i . The output of g_i is fed into h_i .
 - Right Path:** A generator g_f and a discriminator h_f . The output of g_f is fed into h_f .
- Central Block:** The outputs of h_i and h_f are fed into a central block c .
- Output:** The output of block c is fed into a final block y .

47

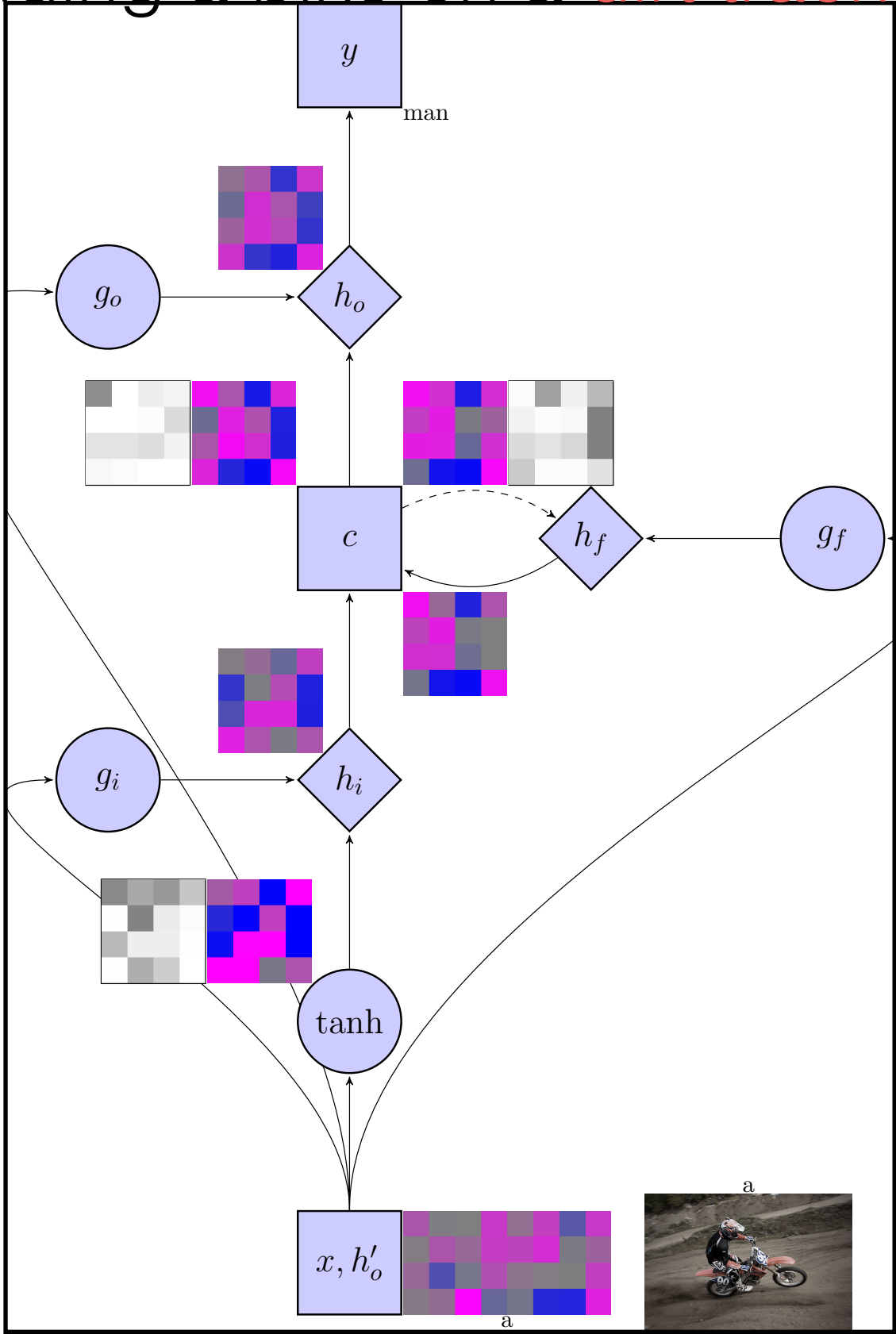
The diagram illustrates the proposed model architecture for image captioning. The input sequence, consisting of the word "the" and an image of a person climbing a rock, is processed by a \tanh activation function. The output of this function is fed into three parallel processing paths:

- Path 1 (Left):** The input is processed by a generator g_i and a hidden state h_i to produce a feature map c .
- Path 2 (Top):** The input is processed by a generator g_o and a hidden state h_o to produce a feature map y .
- Path 3 (Right):** The input is processed by a generator g_f and a hidden state h_f to produce a feature map c .

The feature map c is then used to generate the final output sequence, which includes the word "the" and an image of a person climbing a rock.

0

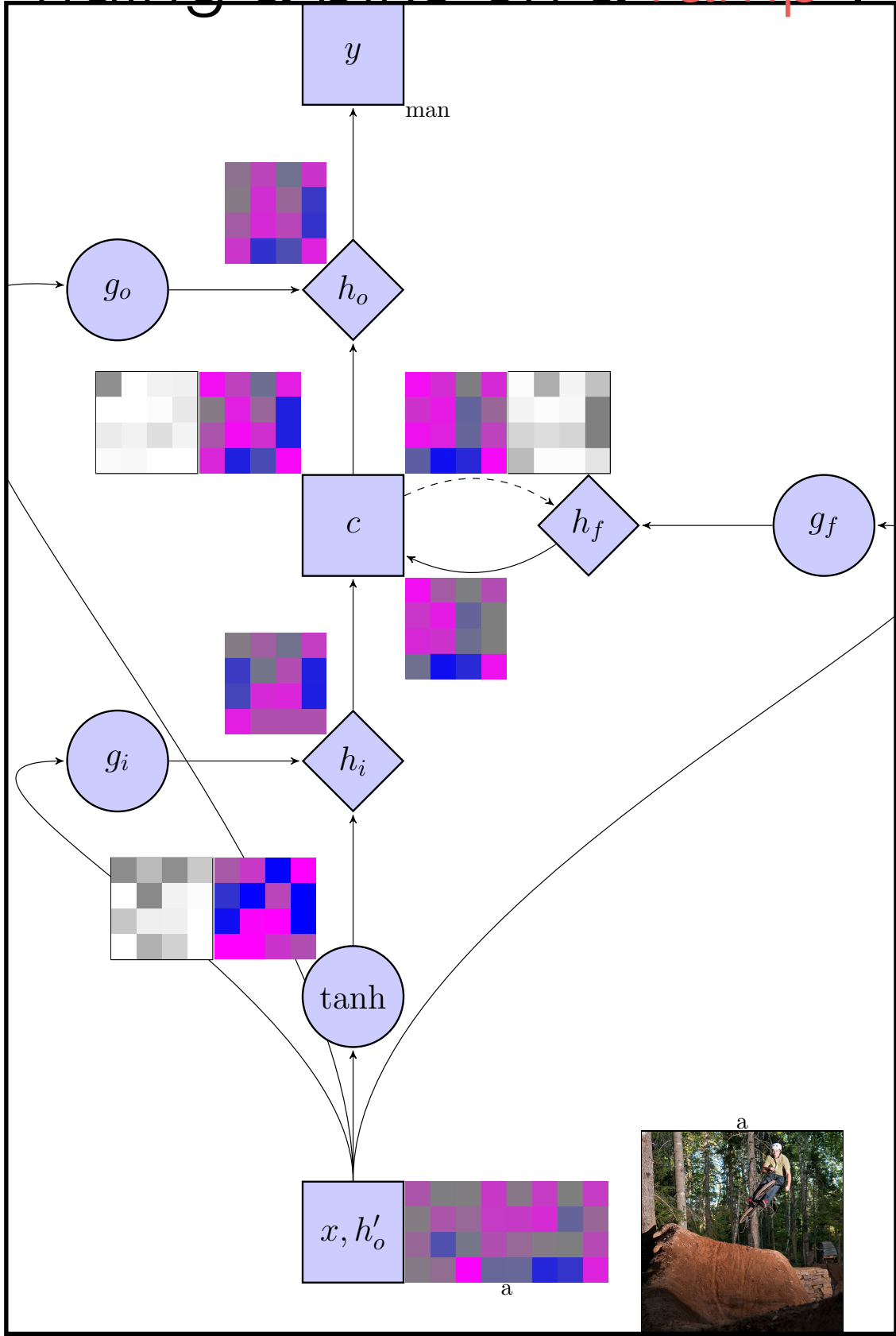
riding a bike on a dirt track.



0

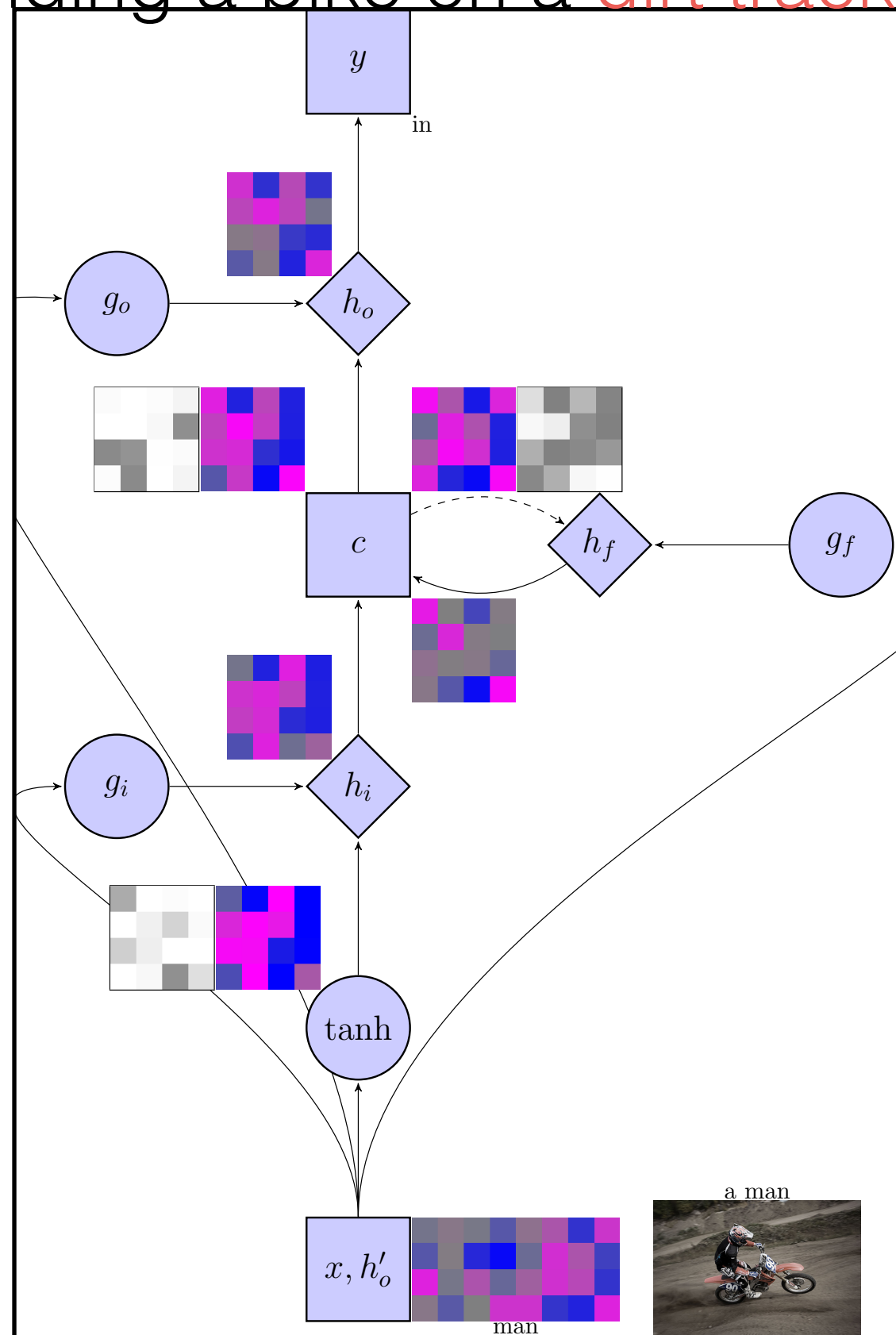
48

riding a bike on a ramp .



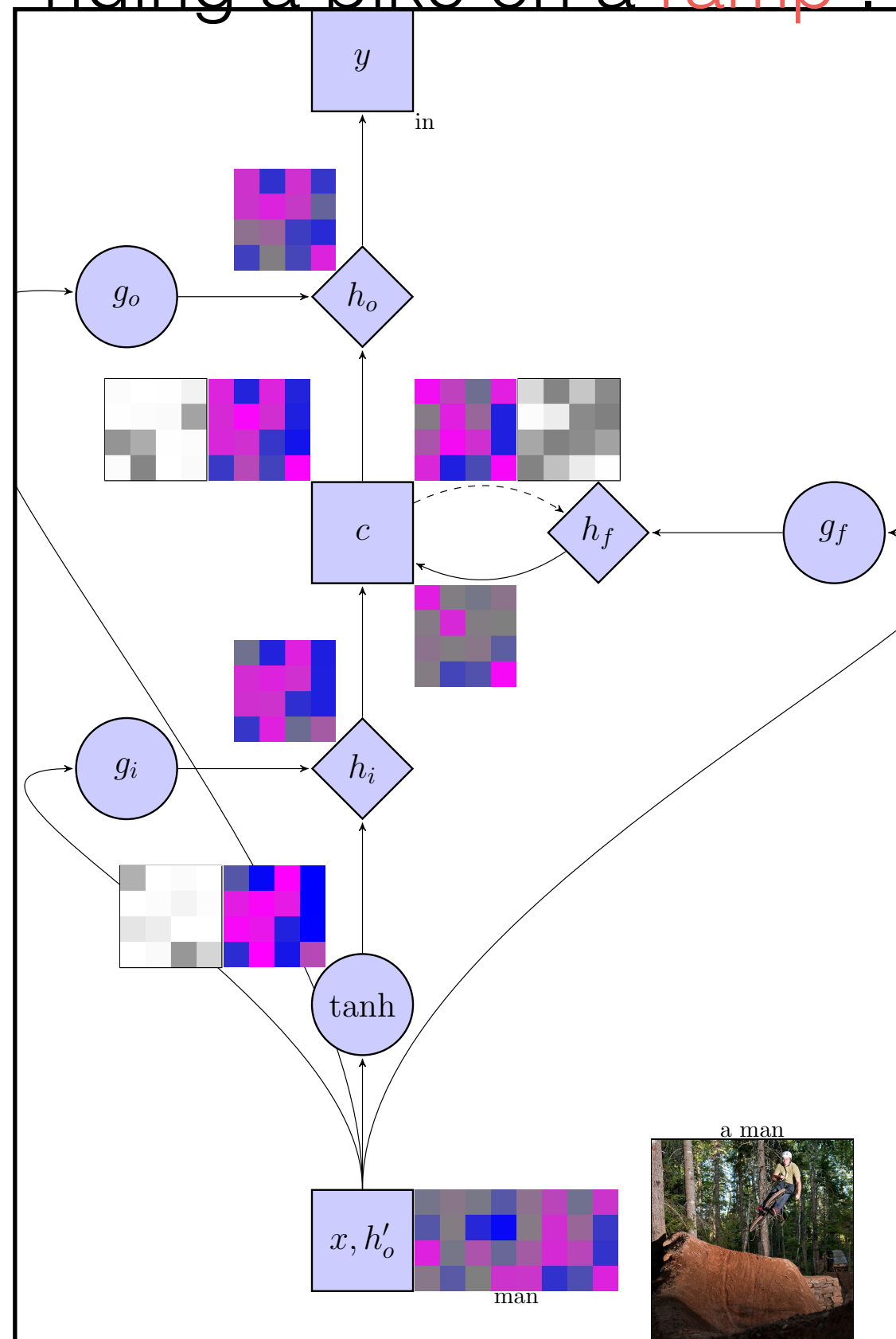
0

a man in a blue shirt is riding a bike on a dirt track .



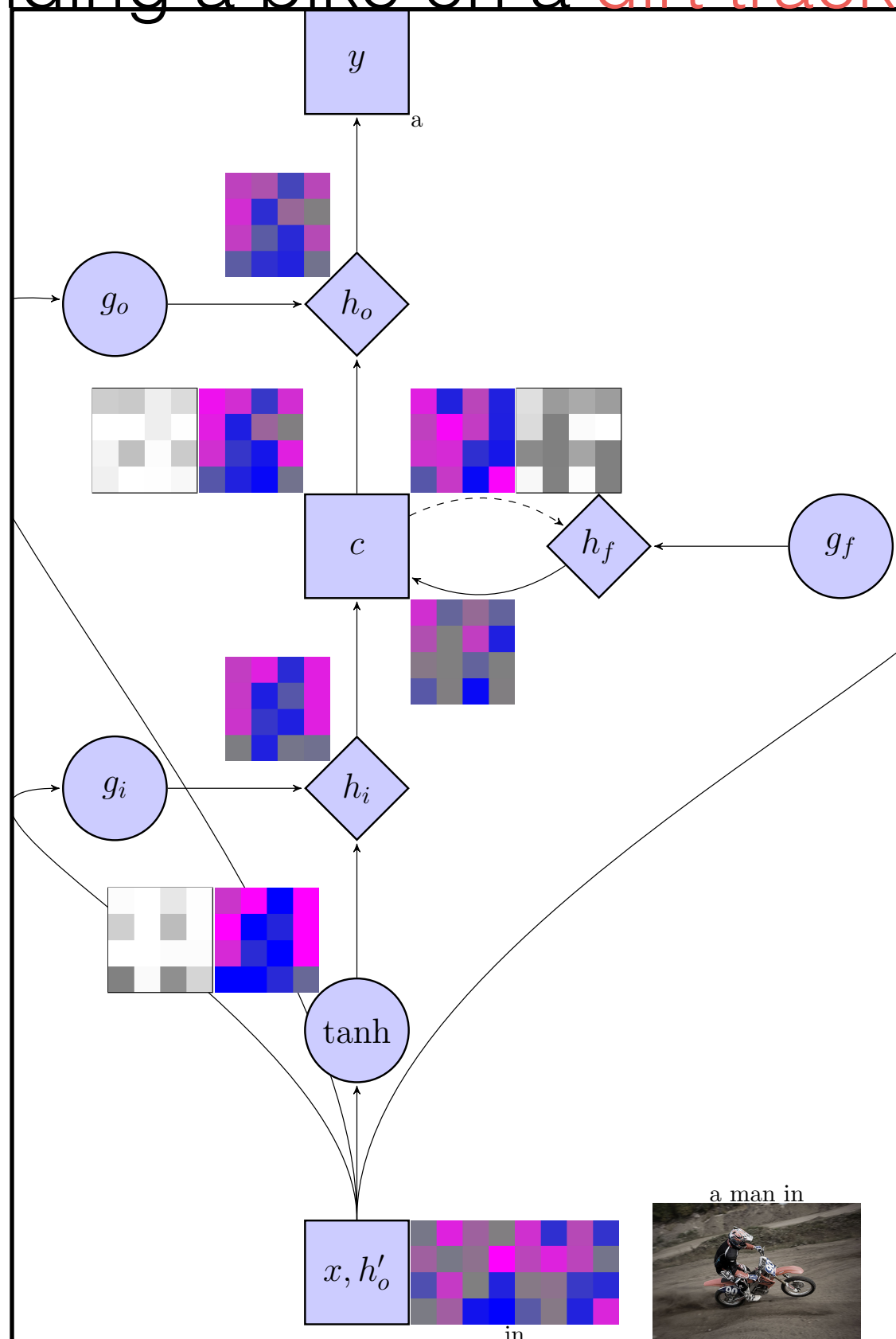
0

a man in a blue shirt is riding a bike on a ramp .



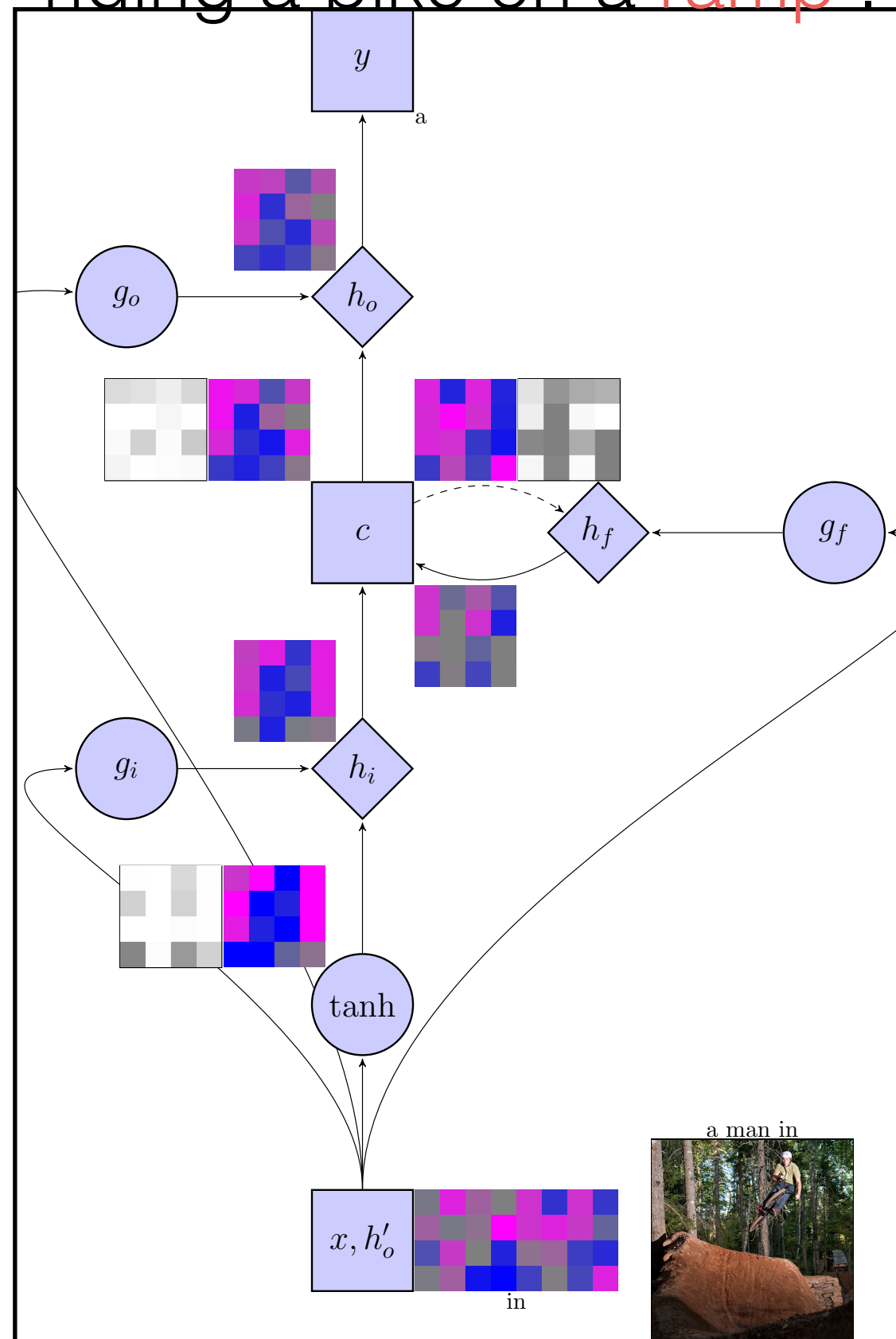
0

a man in a blue shirt is riding a bike on a dirt track .



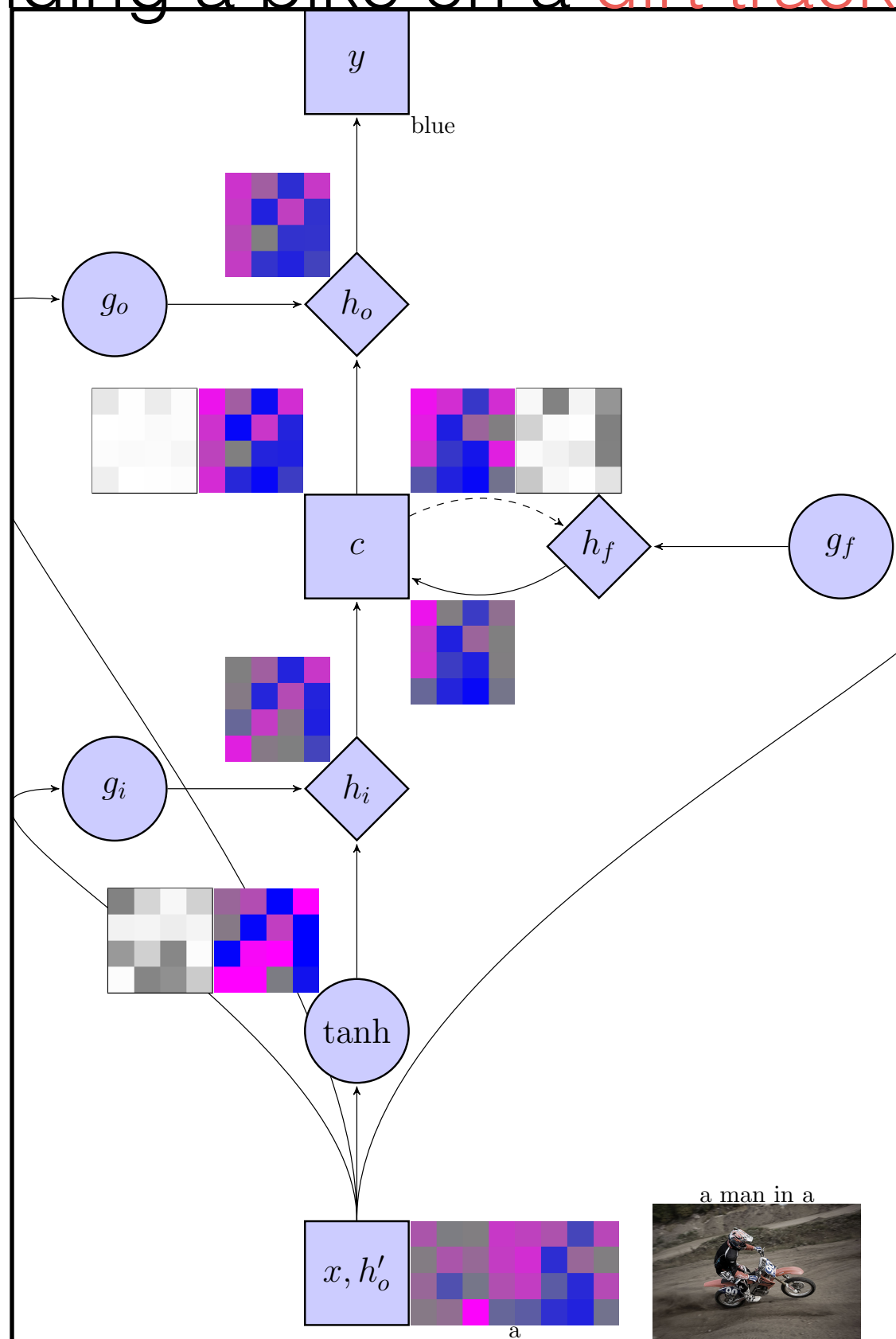
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a man in a blue shirt is riding a bike on a ramp .



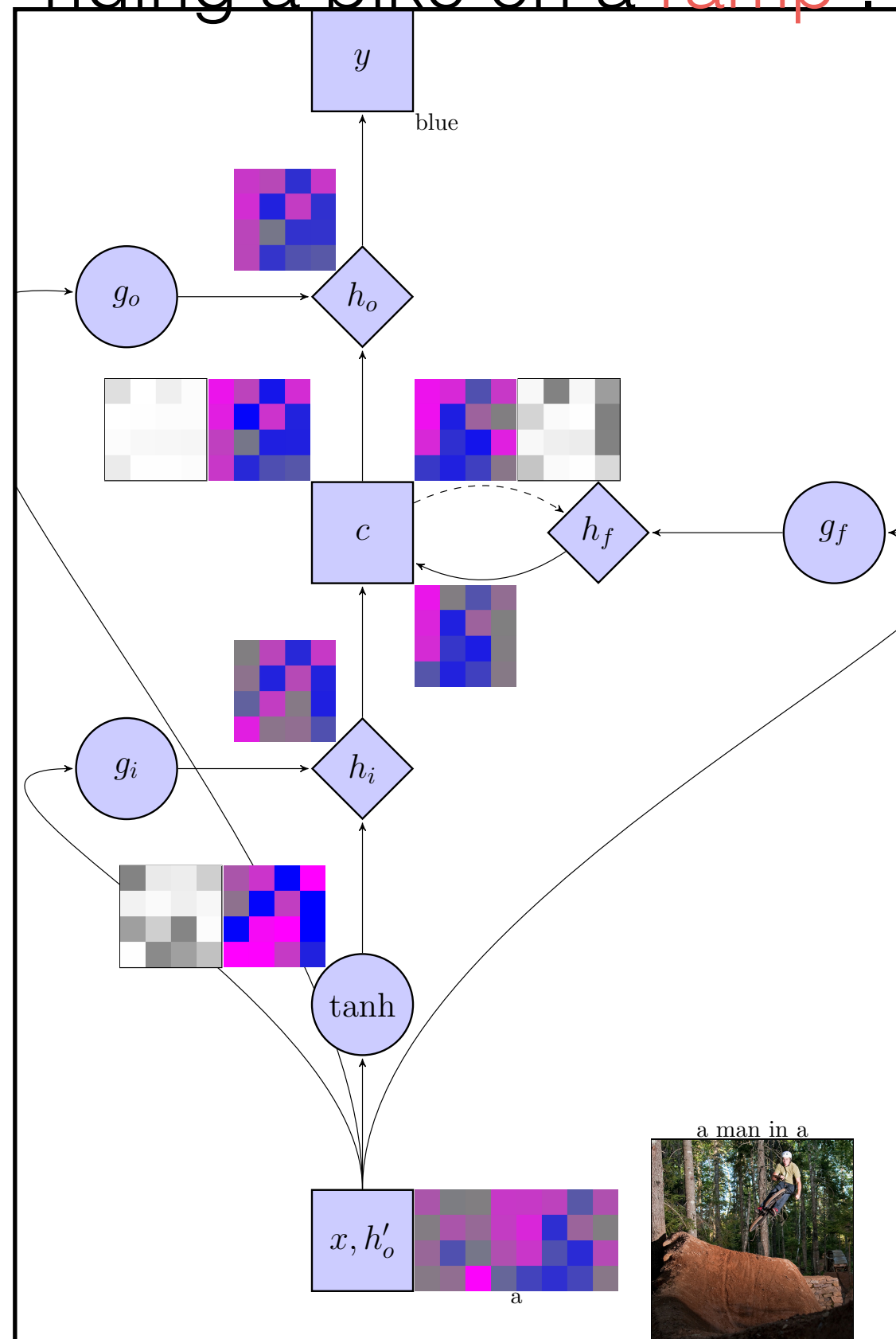
0

a man in a blue shirt is riding a bike on a dirt track .



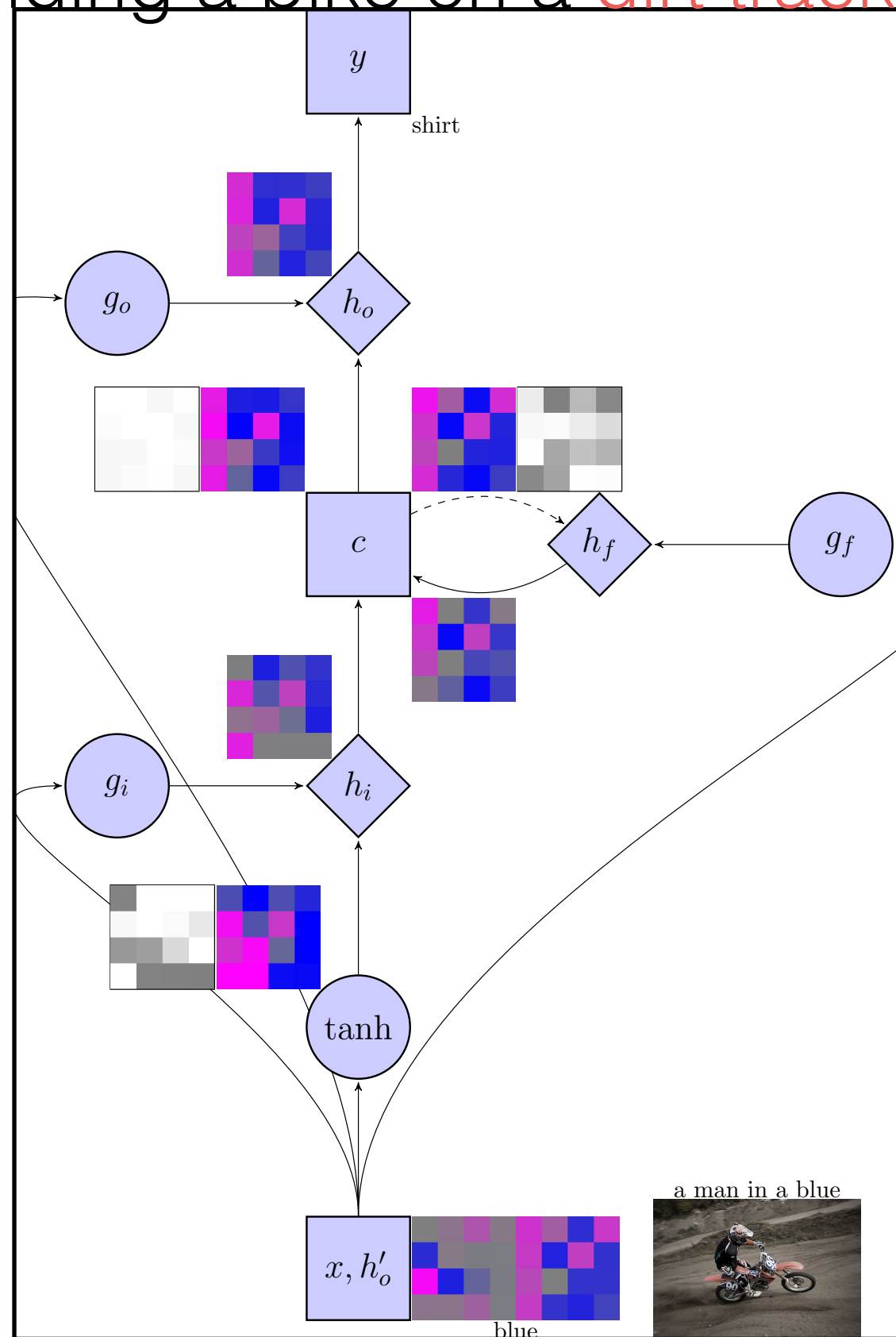
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a man in a blue shirt is riding a bike on a ramp .



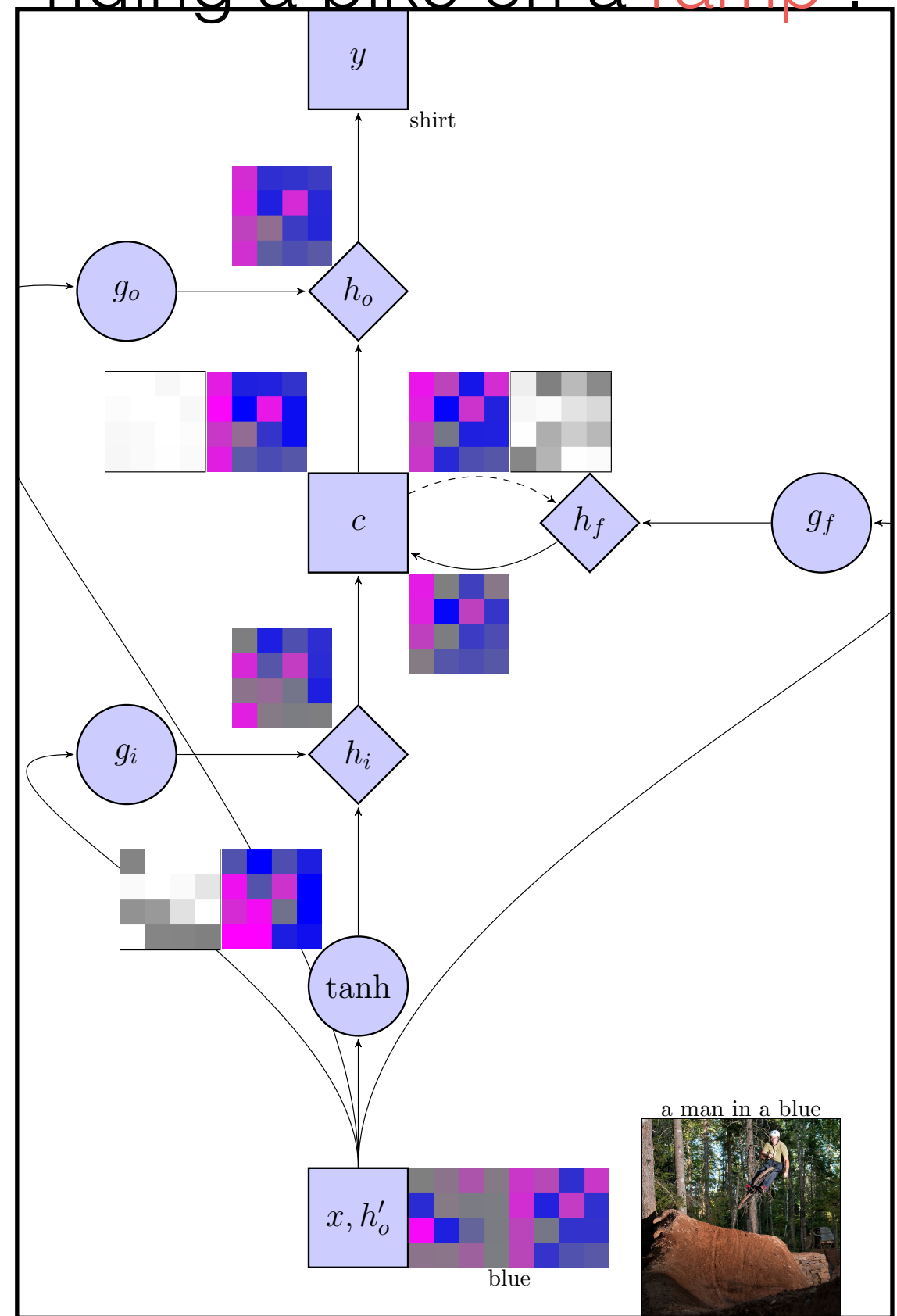
0

a man in a blue shirt is riding a bike on a dirt track .



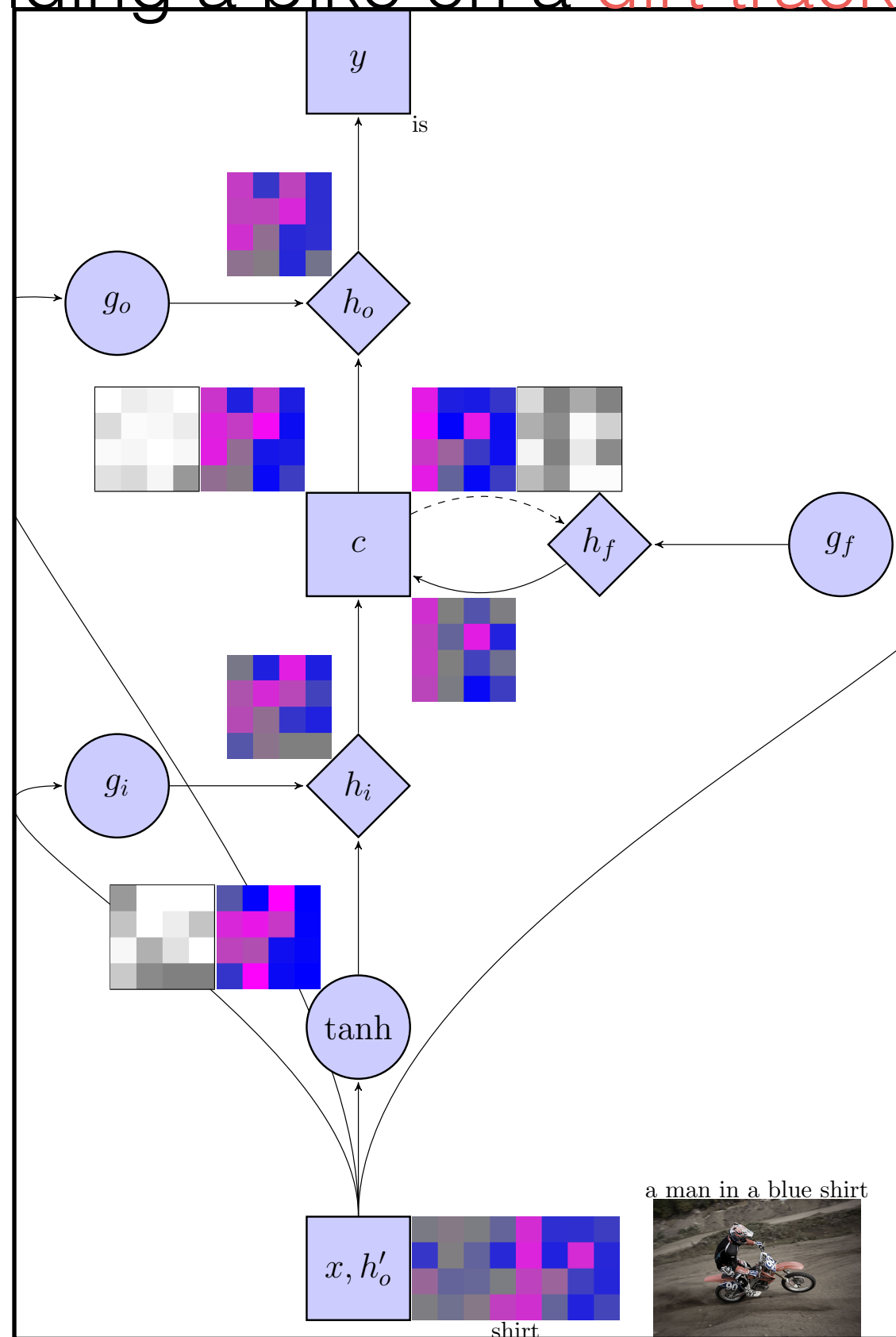
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a man in a blue shirt is riding a bike on a ramp .



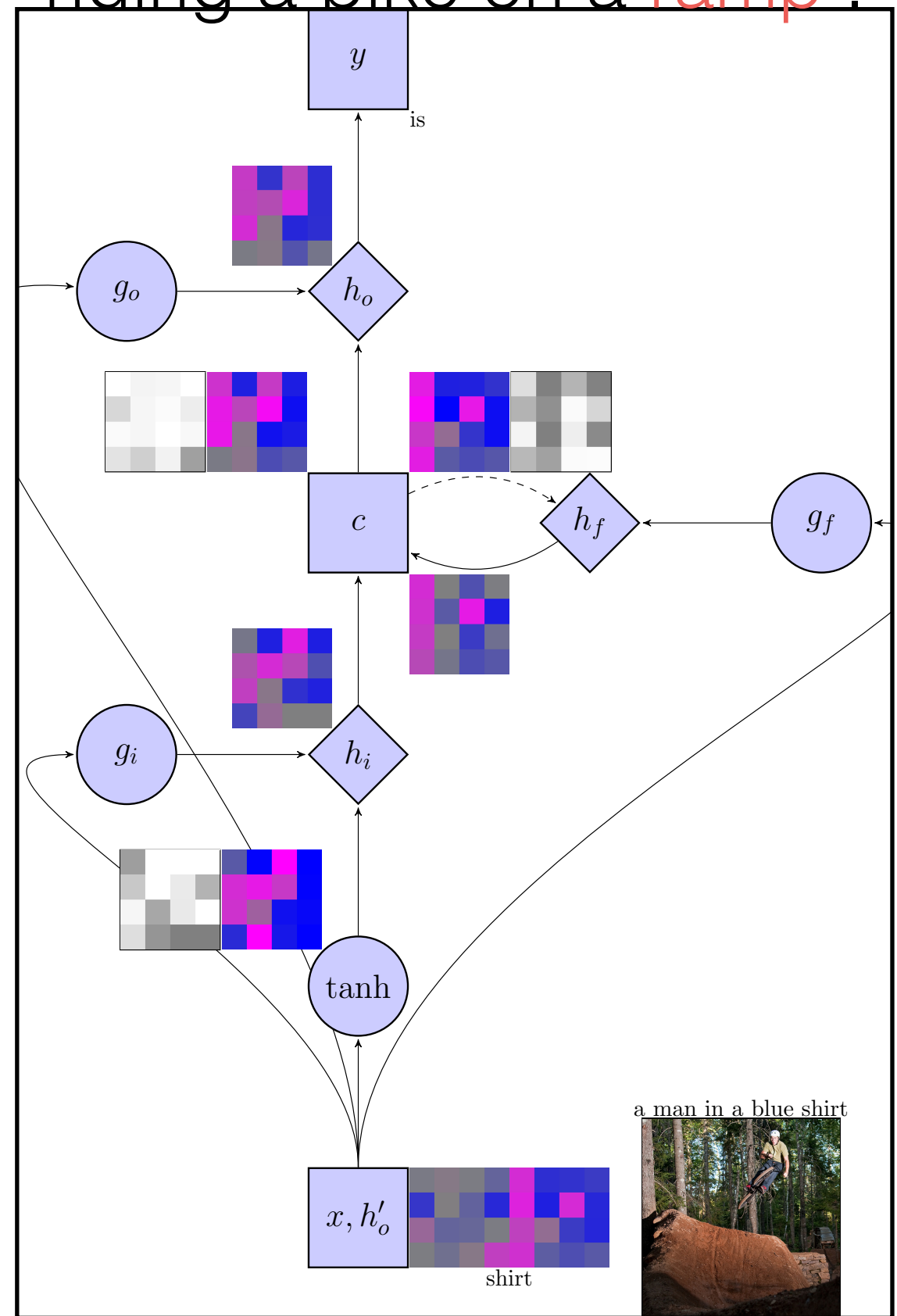
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a man in a blue shirt is riding a bike on a dirt track .



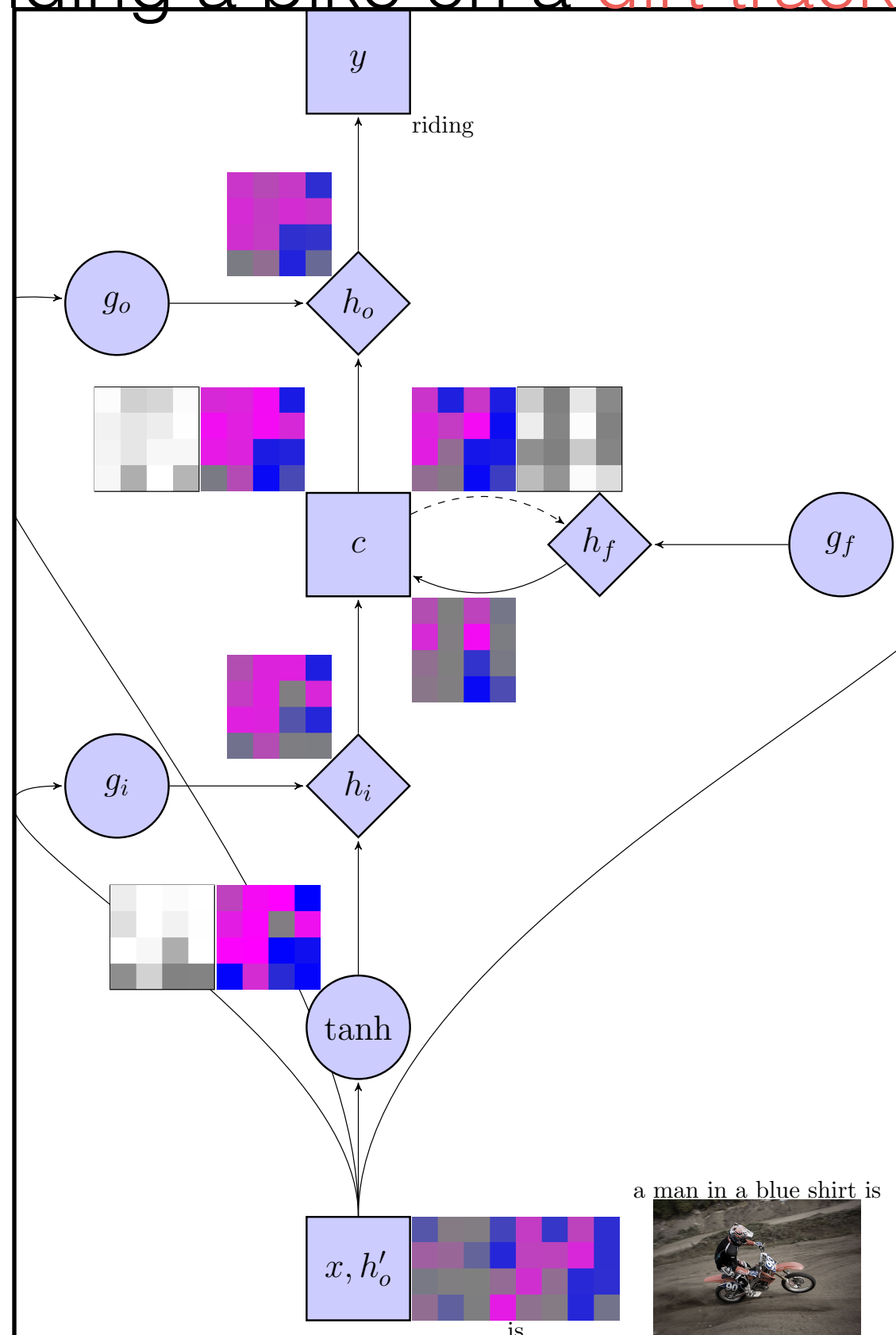
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a man in a blue shirt is riding a bike on a ramp .



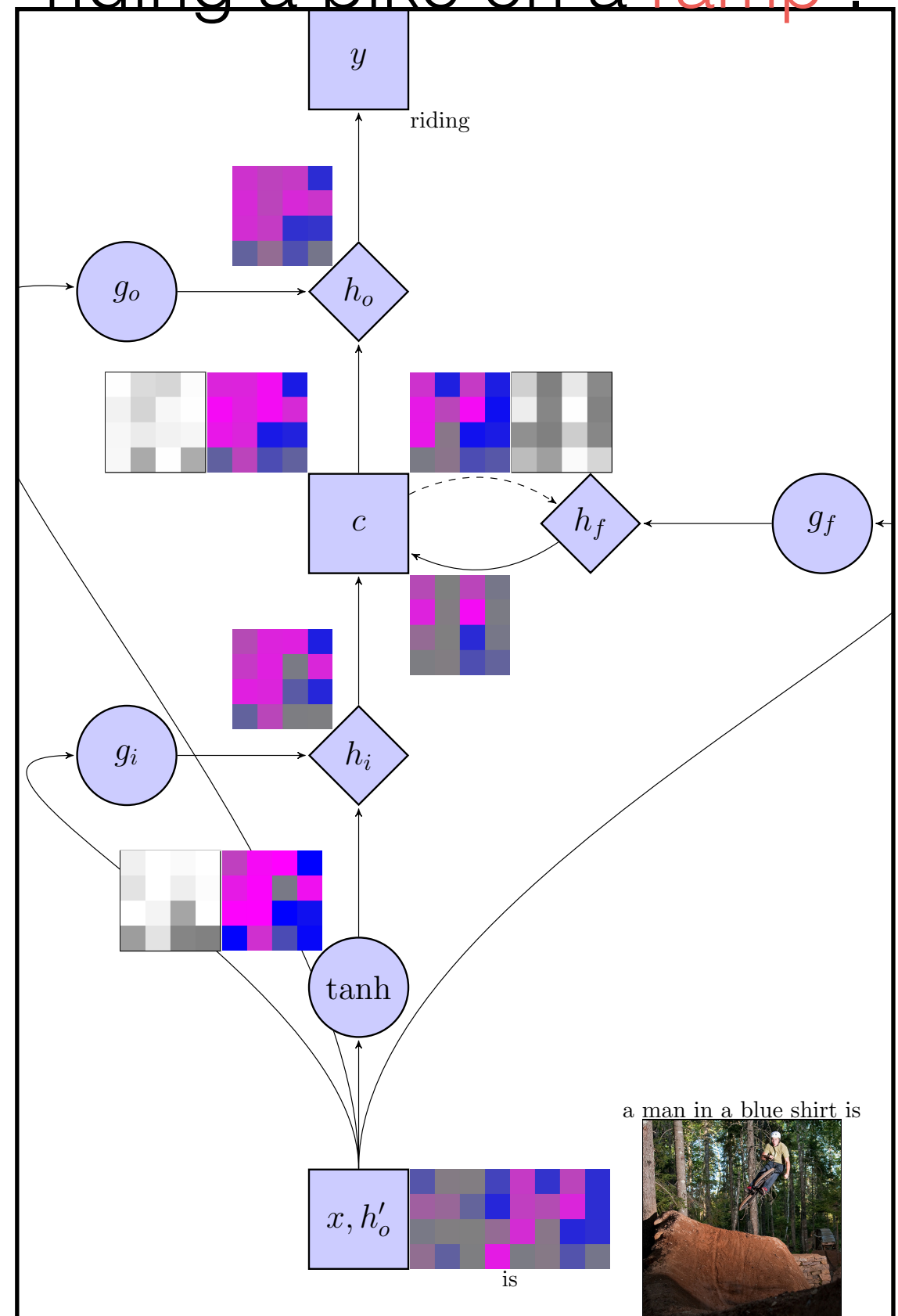
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a man in a blue shirt is riding a bike on a dirt track .



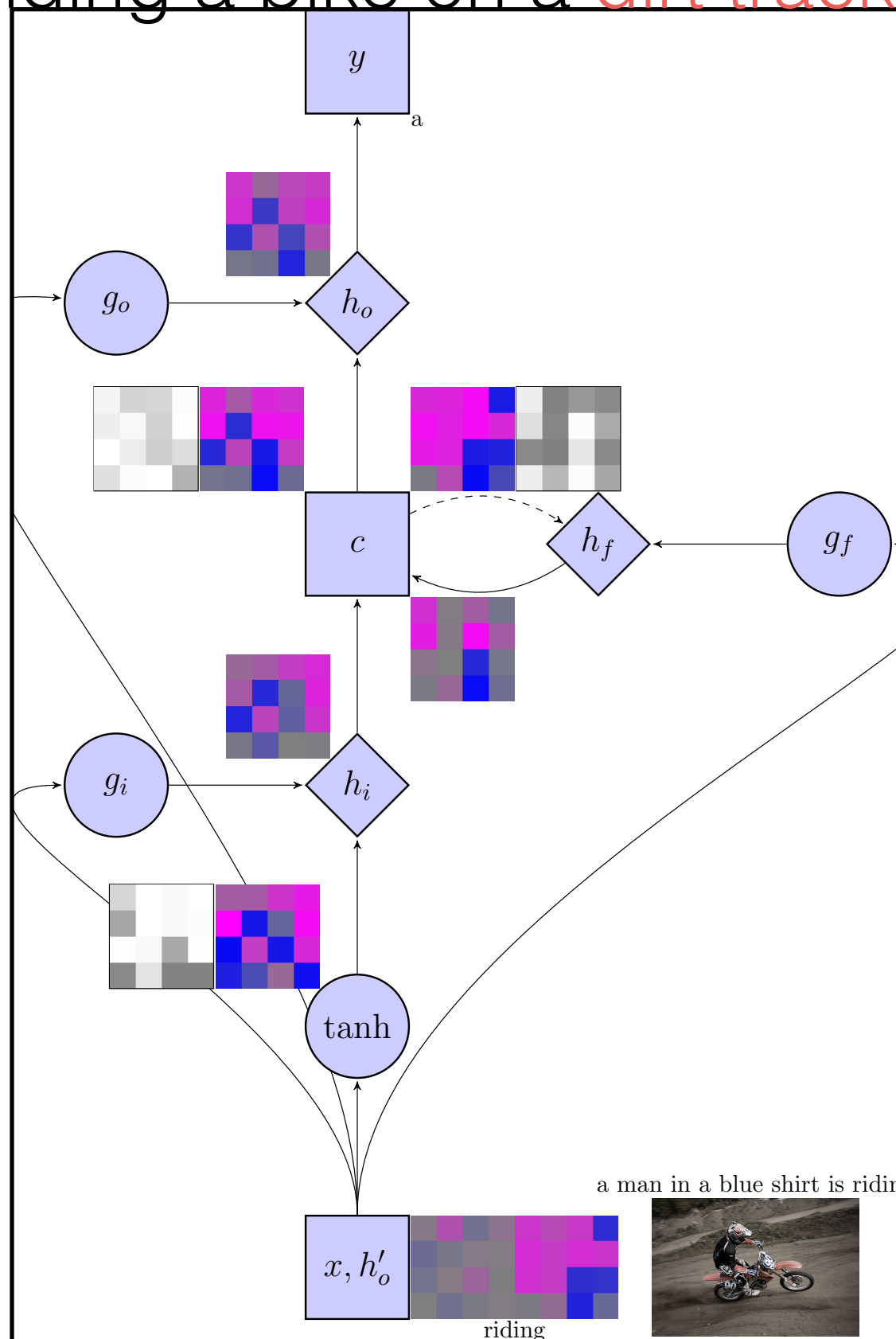
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a man in a blue shirt is riding a bike on a ramp .



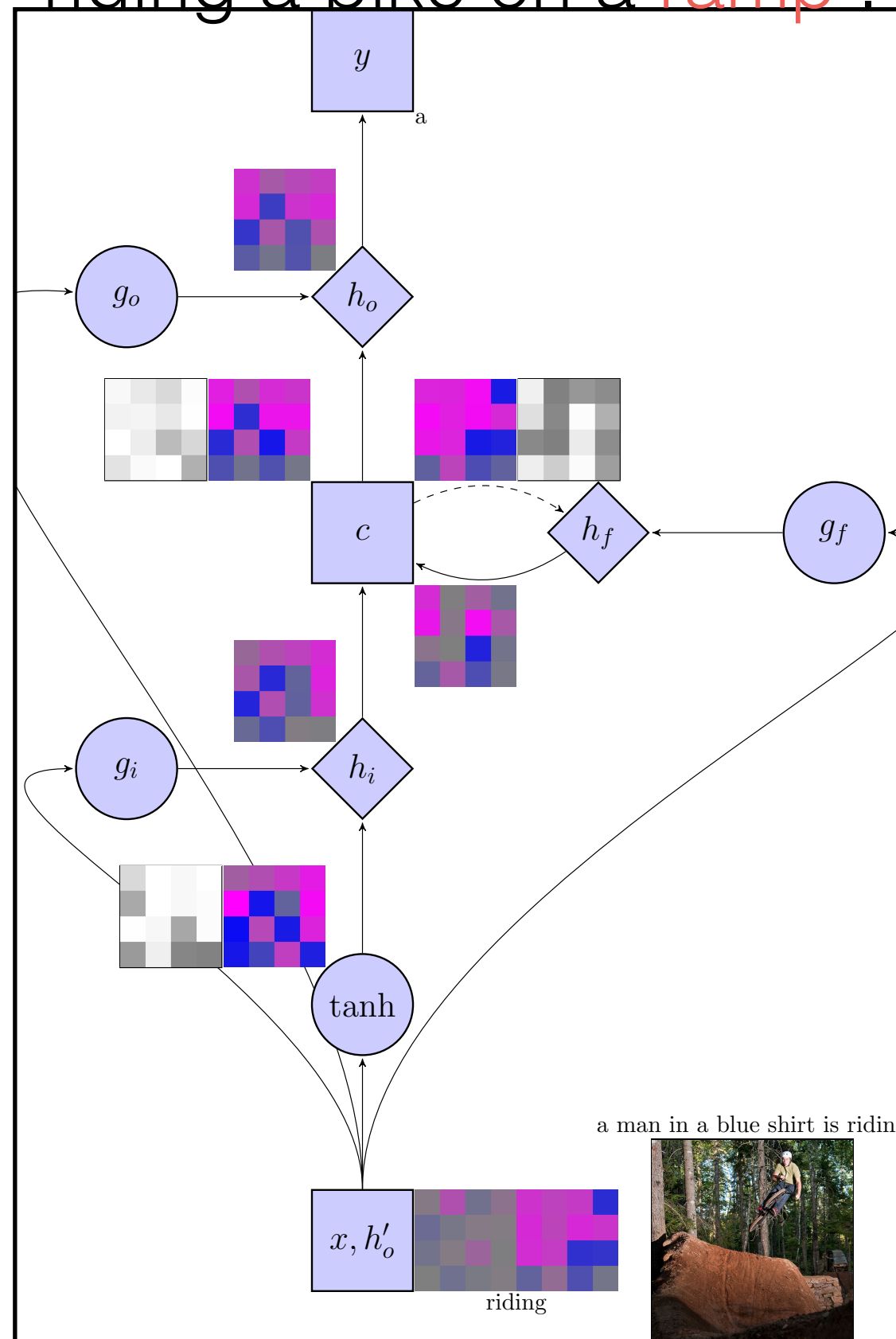
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a man in a blue shirt is riding a bike on a dirt track .



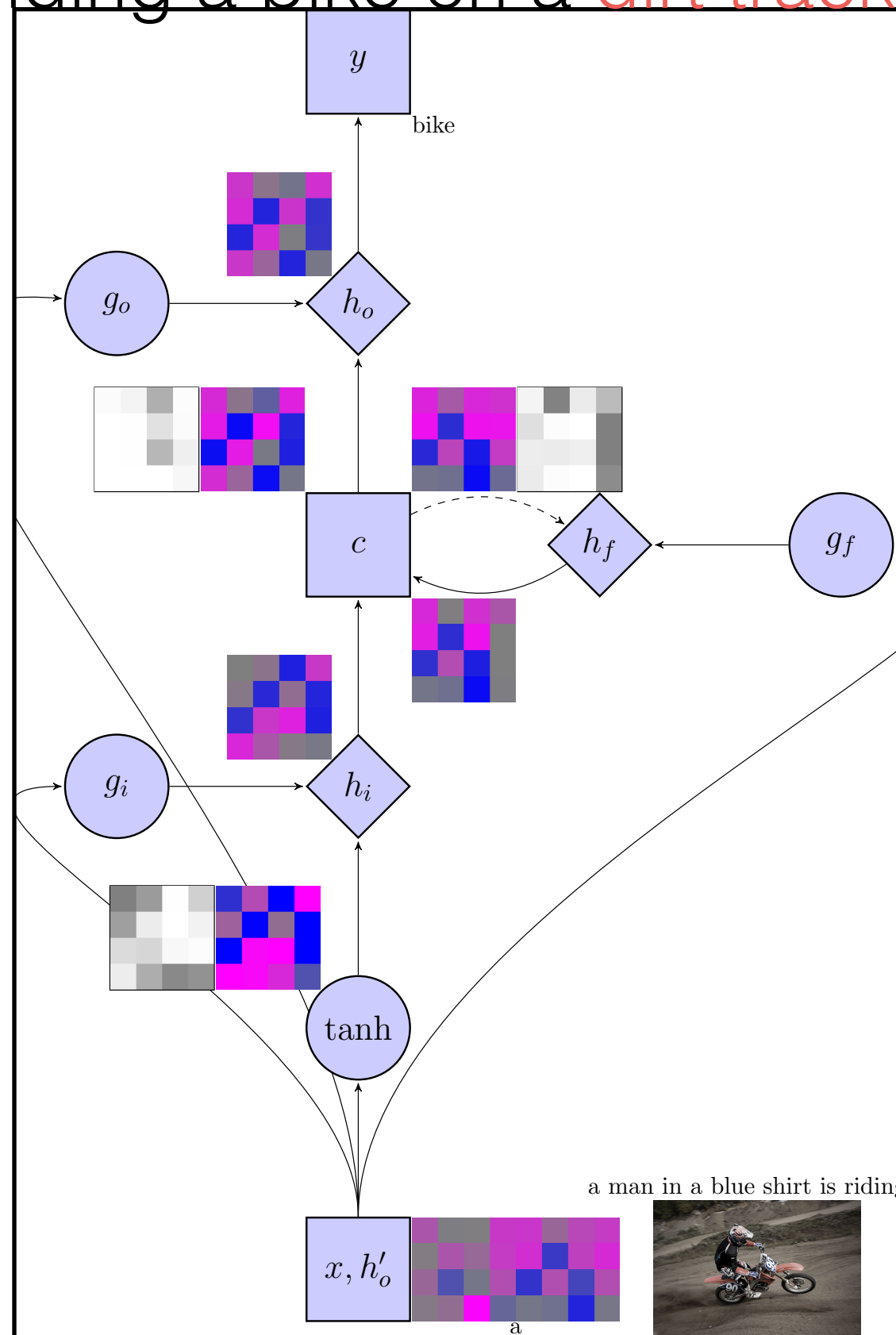
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a man in a blue shirt is riding a bike on a ramp .



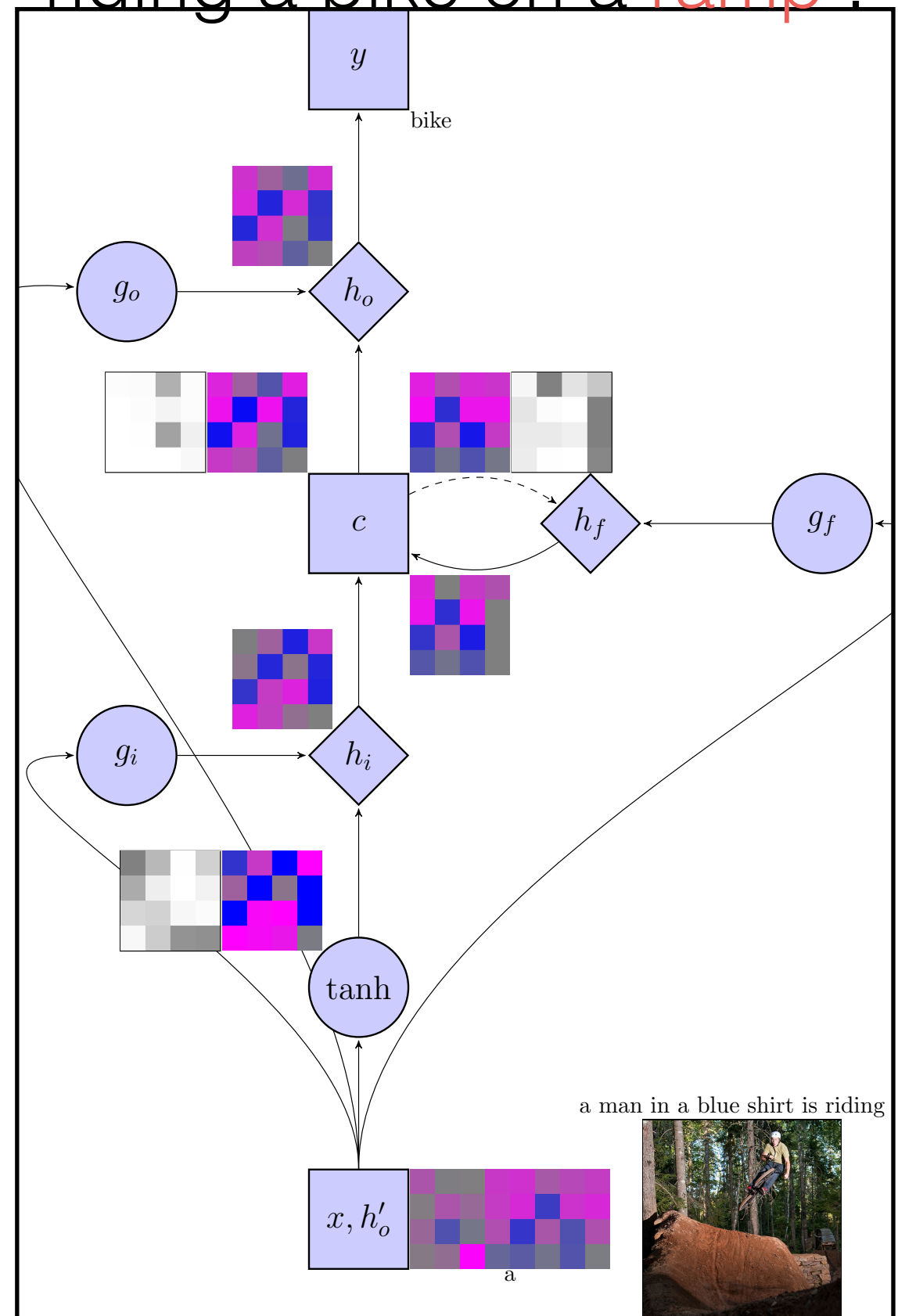
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a man in a blue shirt is riding a bike on a dirt track .



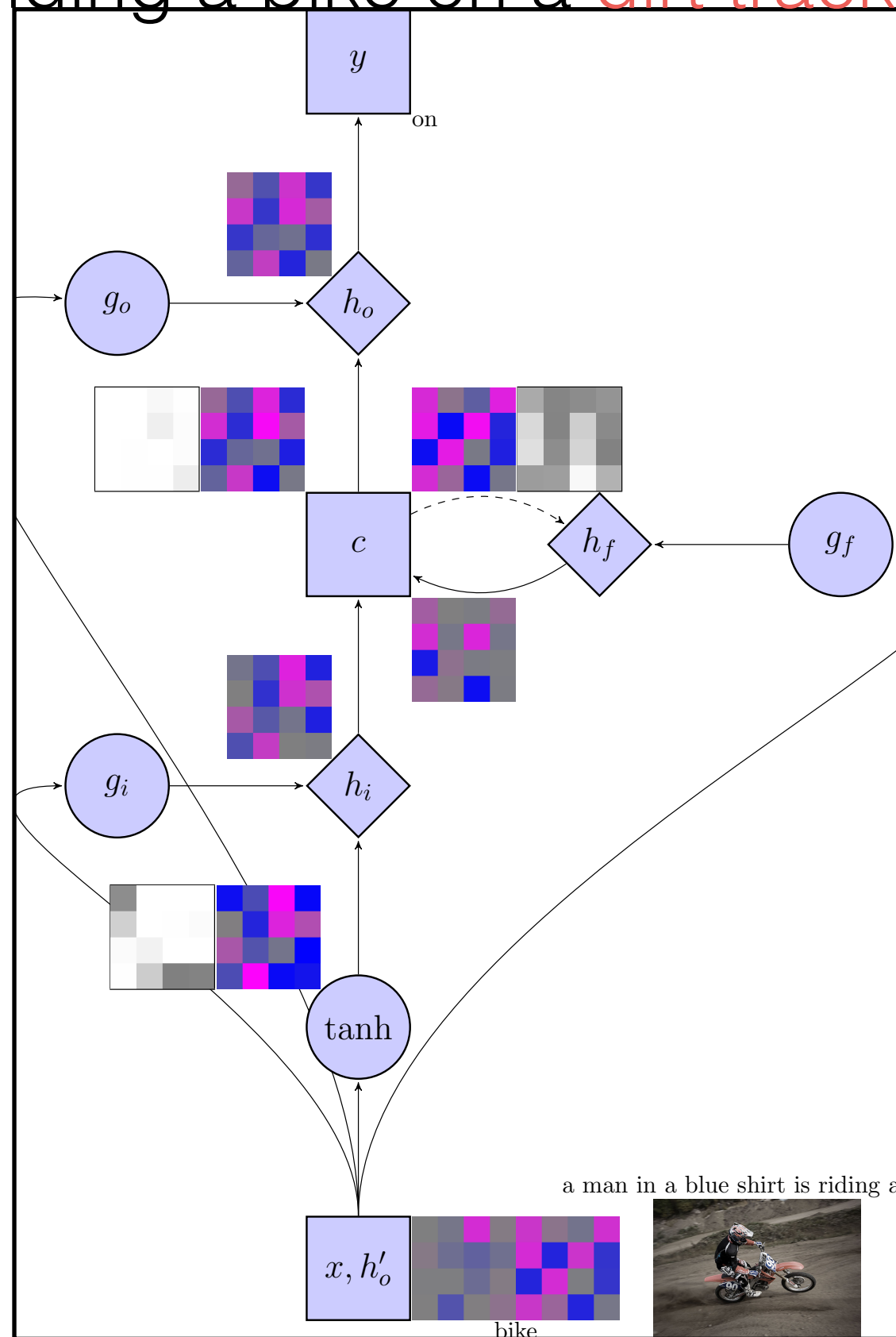
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a man in a blue shirt is riding a bike on a ramp .



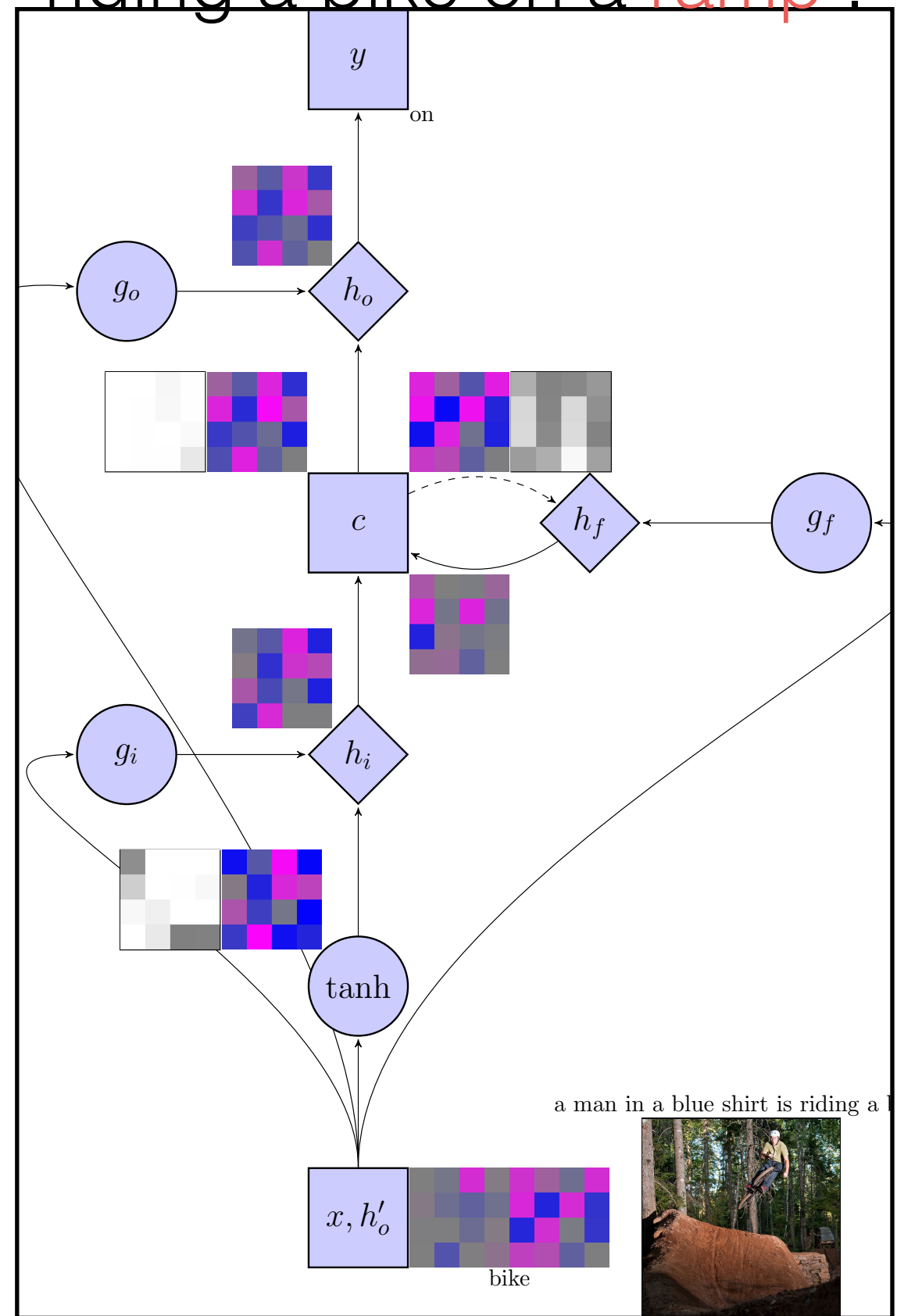
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a man in a blue shirt is riding a bike on a dirt track .



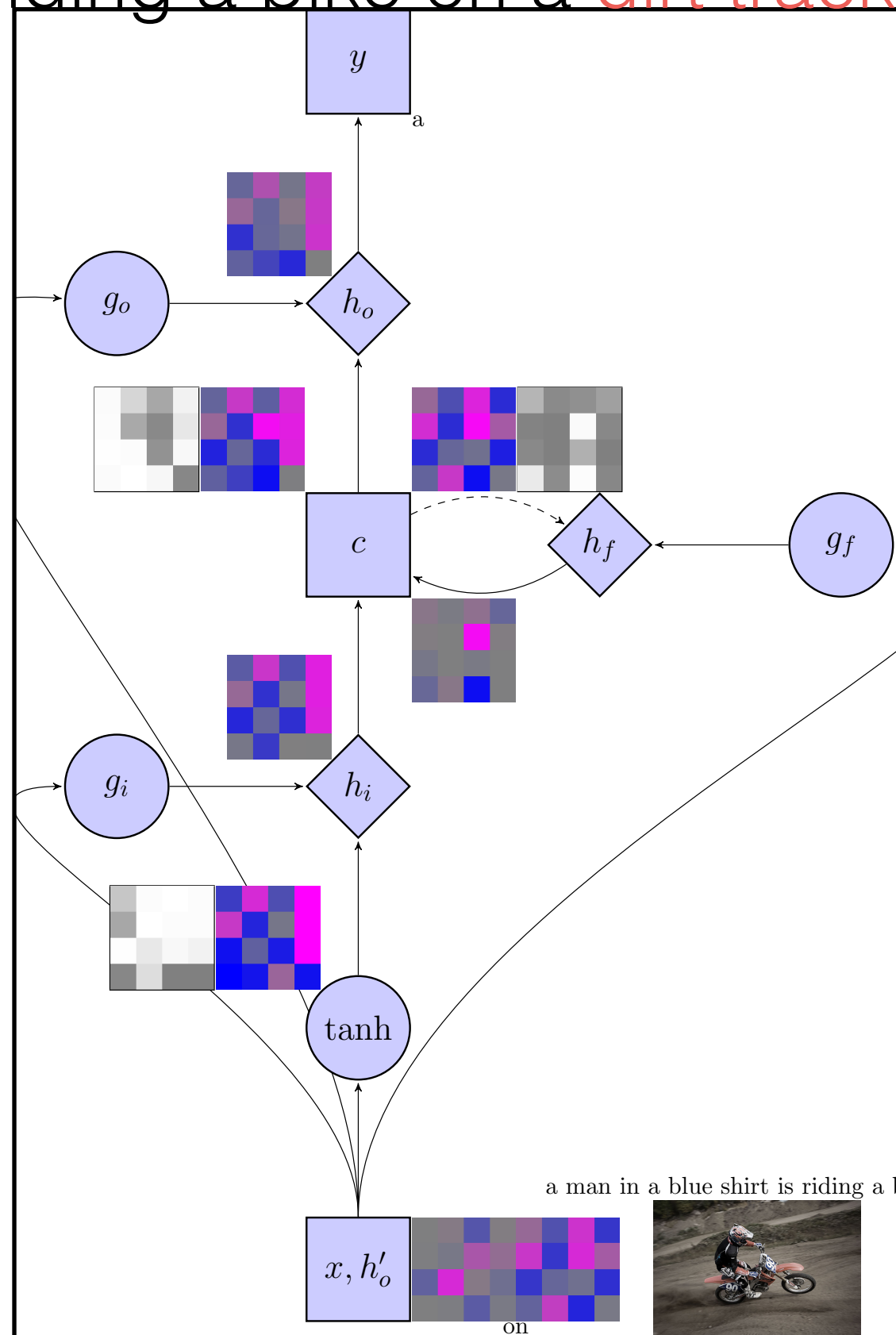
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a man in a blue shirt is riding a bike on a ramp .



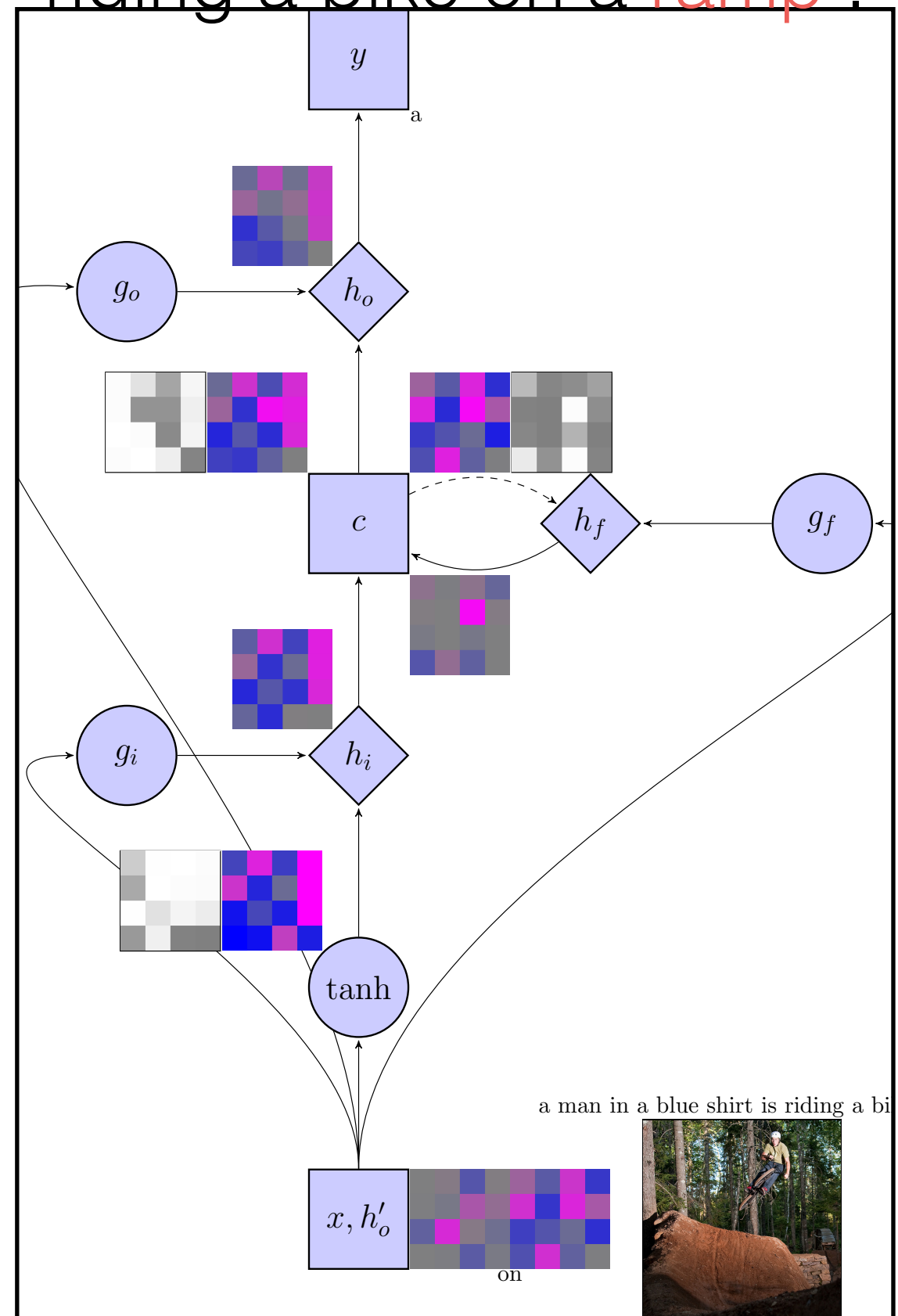
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a man in a blue shirt is riding a bike on a dirt track .



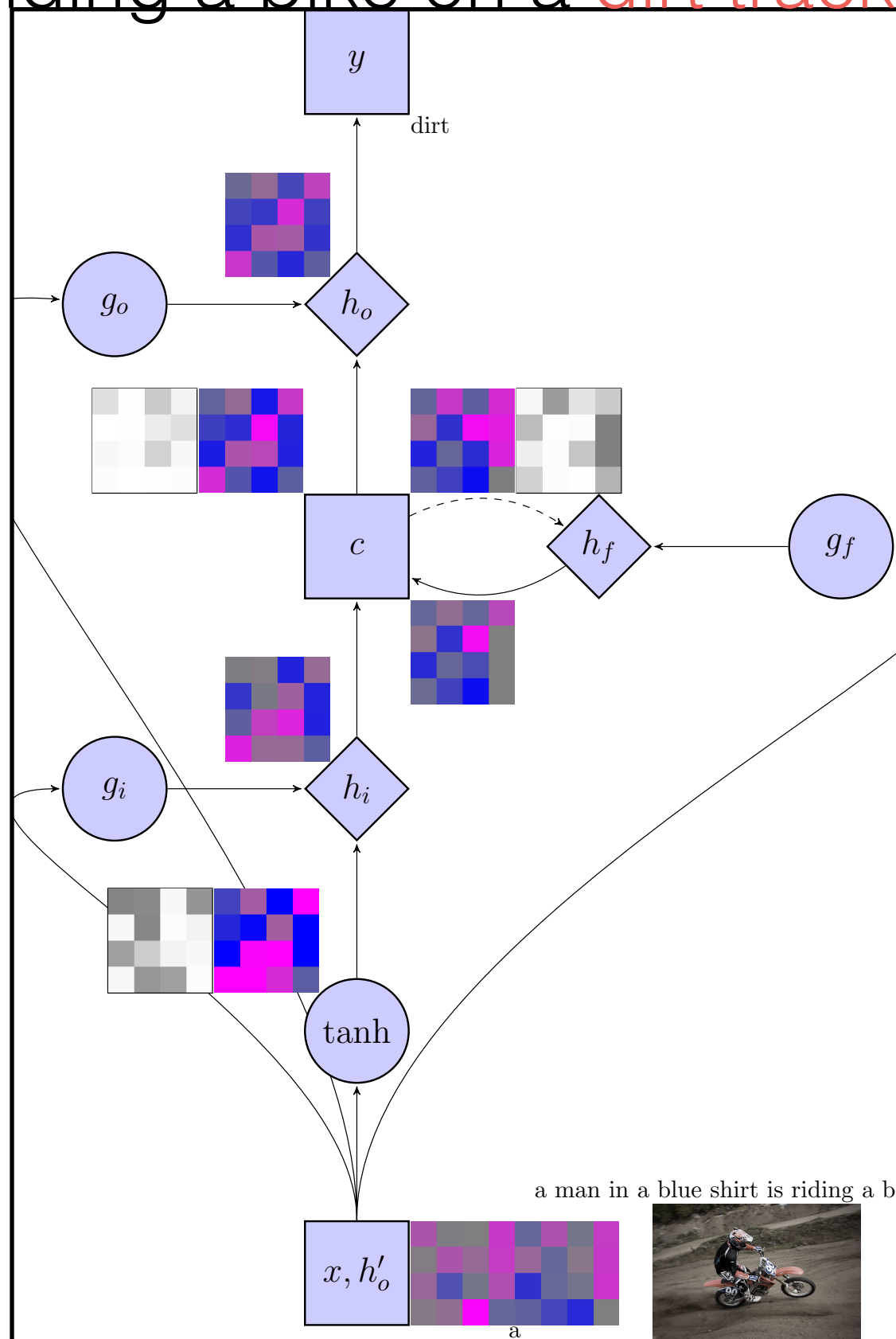
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a man in a blue shirt is riding a bike on a ramp .



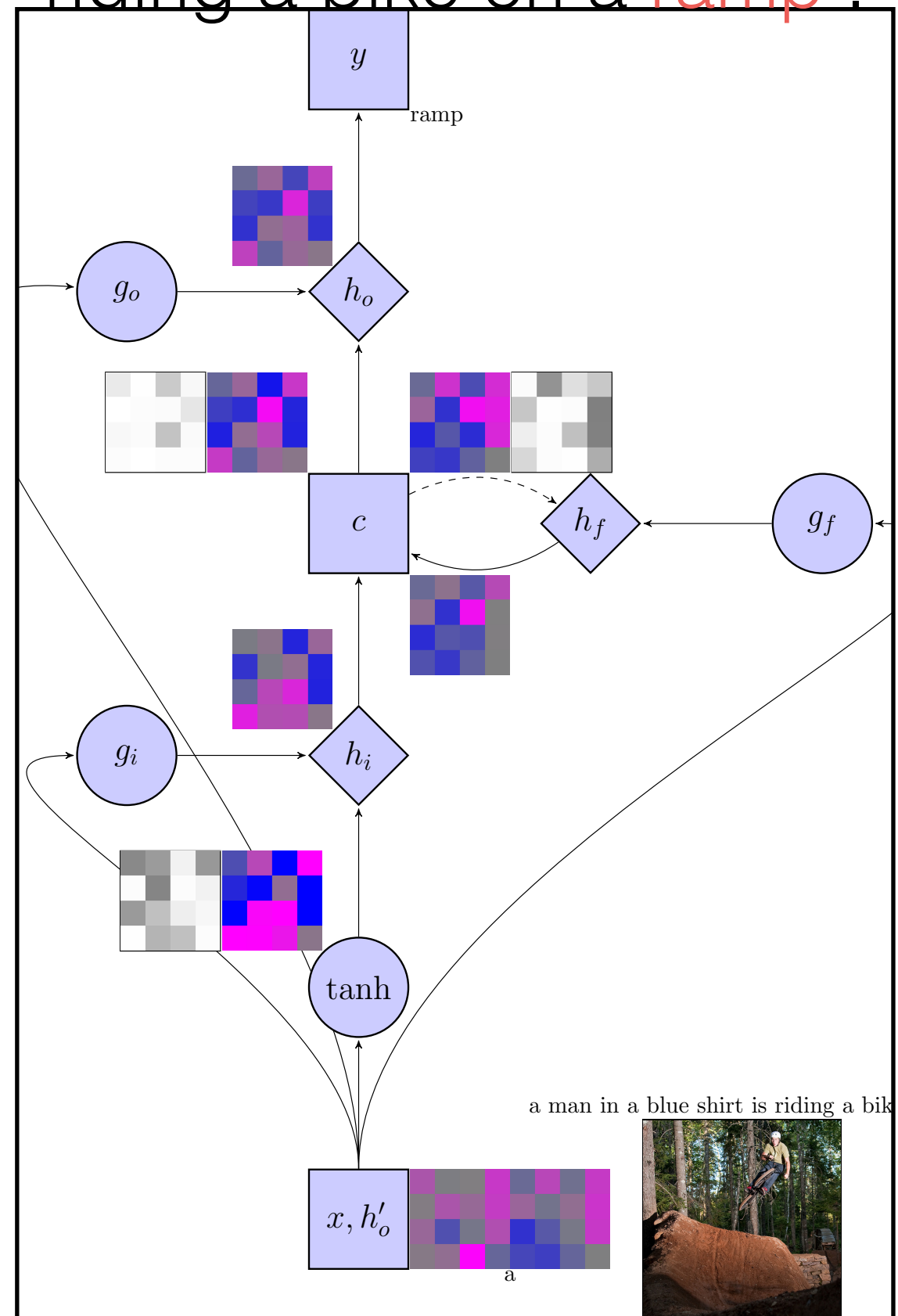
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a man in a blue shirt is riding a bike on a dirt track .



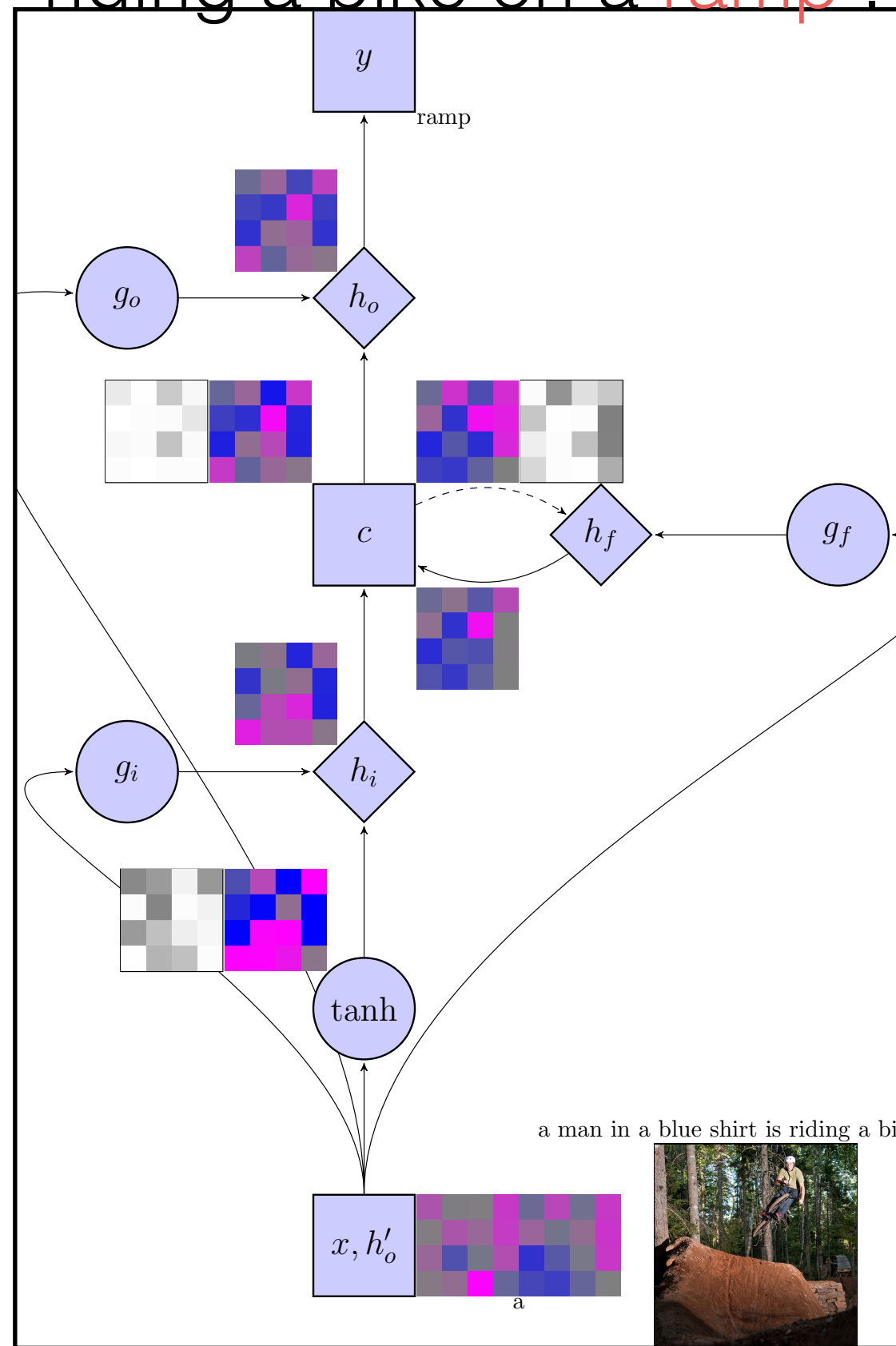
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a man in a blue shirt is riding a bike on a ramp .



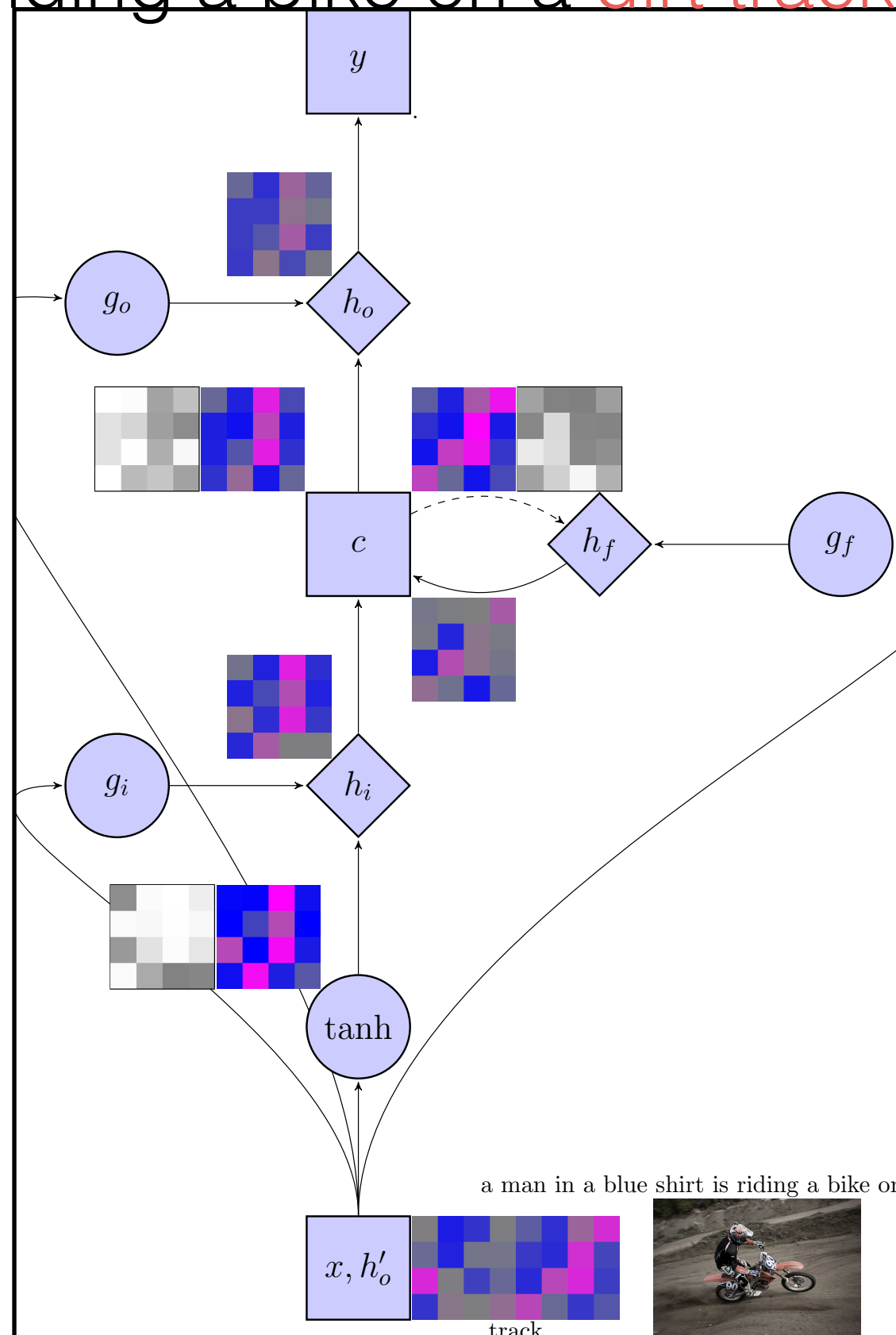
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a man in a blue shirt is riding a bike on a ramp .



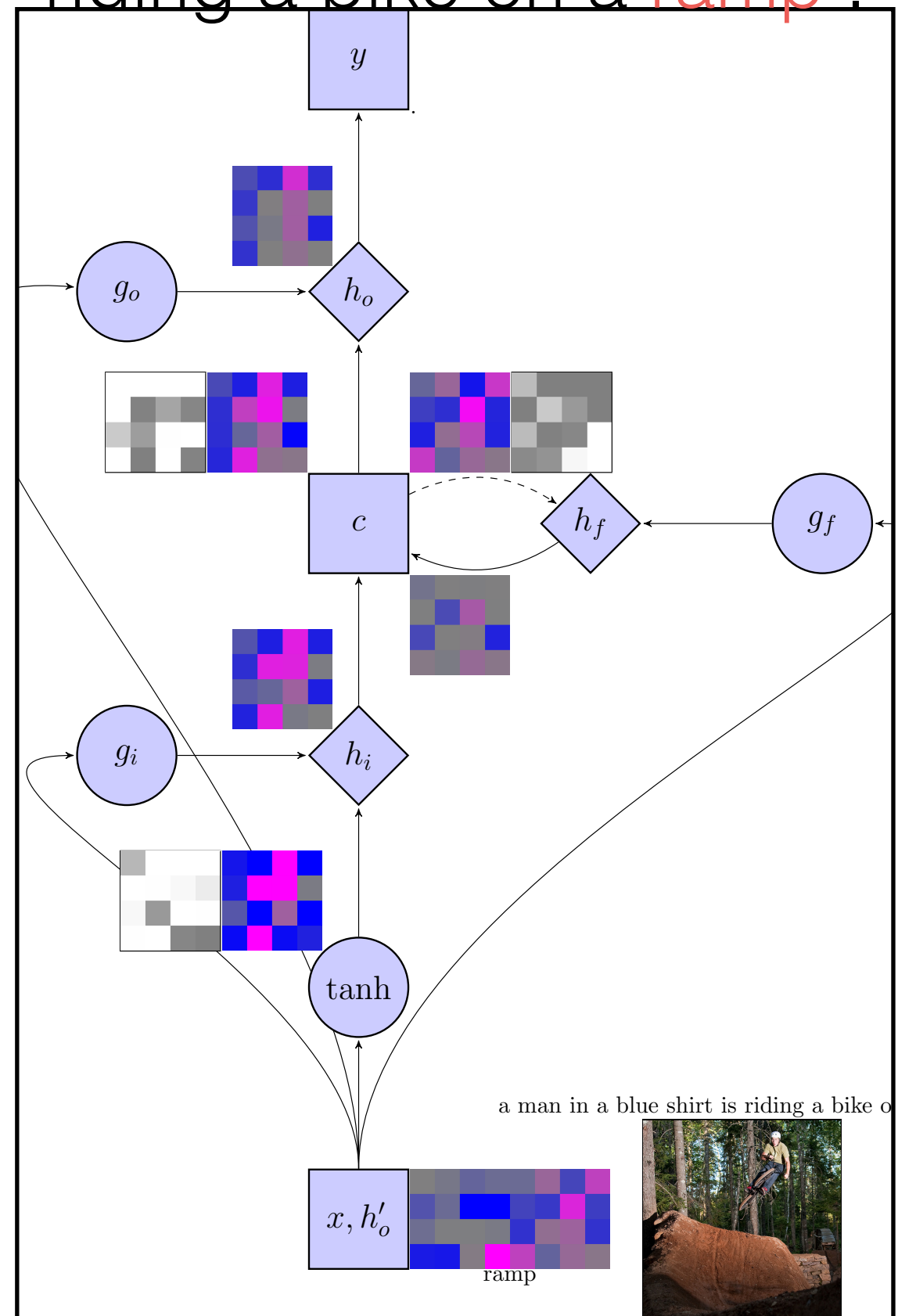
C

a man in a blue shirt is riding a bike on a dirt track .



0

a man in a blue shirt is riding a bike on a ramp .



0

Generating descriptions for the **regional** images

1

Dataset of images and sentence descriptions

training image

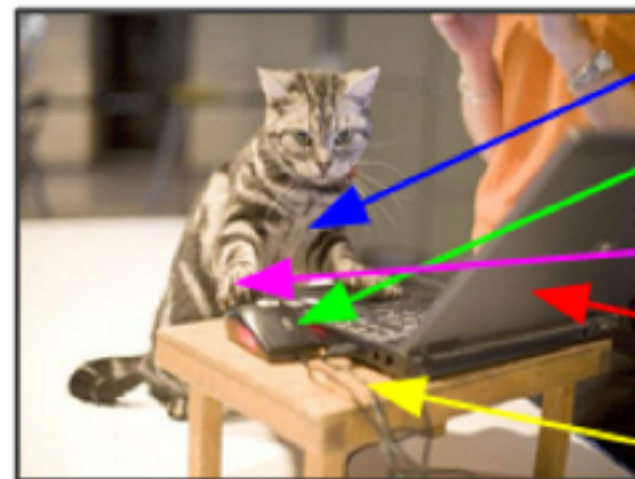


*"A Tabby cat is leaning
on a wooden table, with
one paw on a laser
mouse and the other on
a black laptop"*

2

Inferred correspondences

training image



"Tabby cat is leaning"

"laser mouse"

"paw"

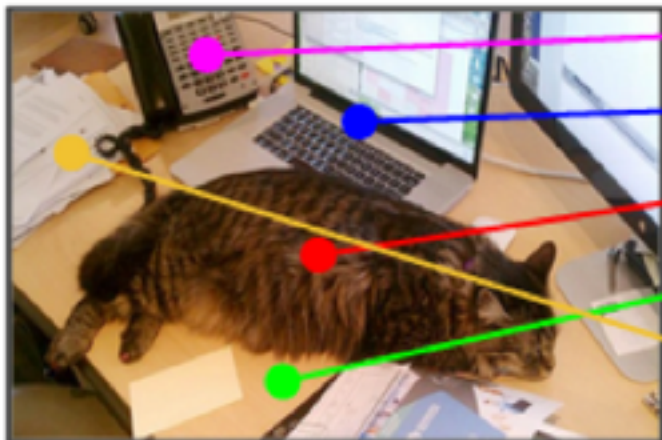
"black laptop"

"wooden table"

3

Generative model

test image



"office telephone"

"shiny laptop"

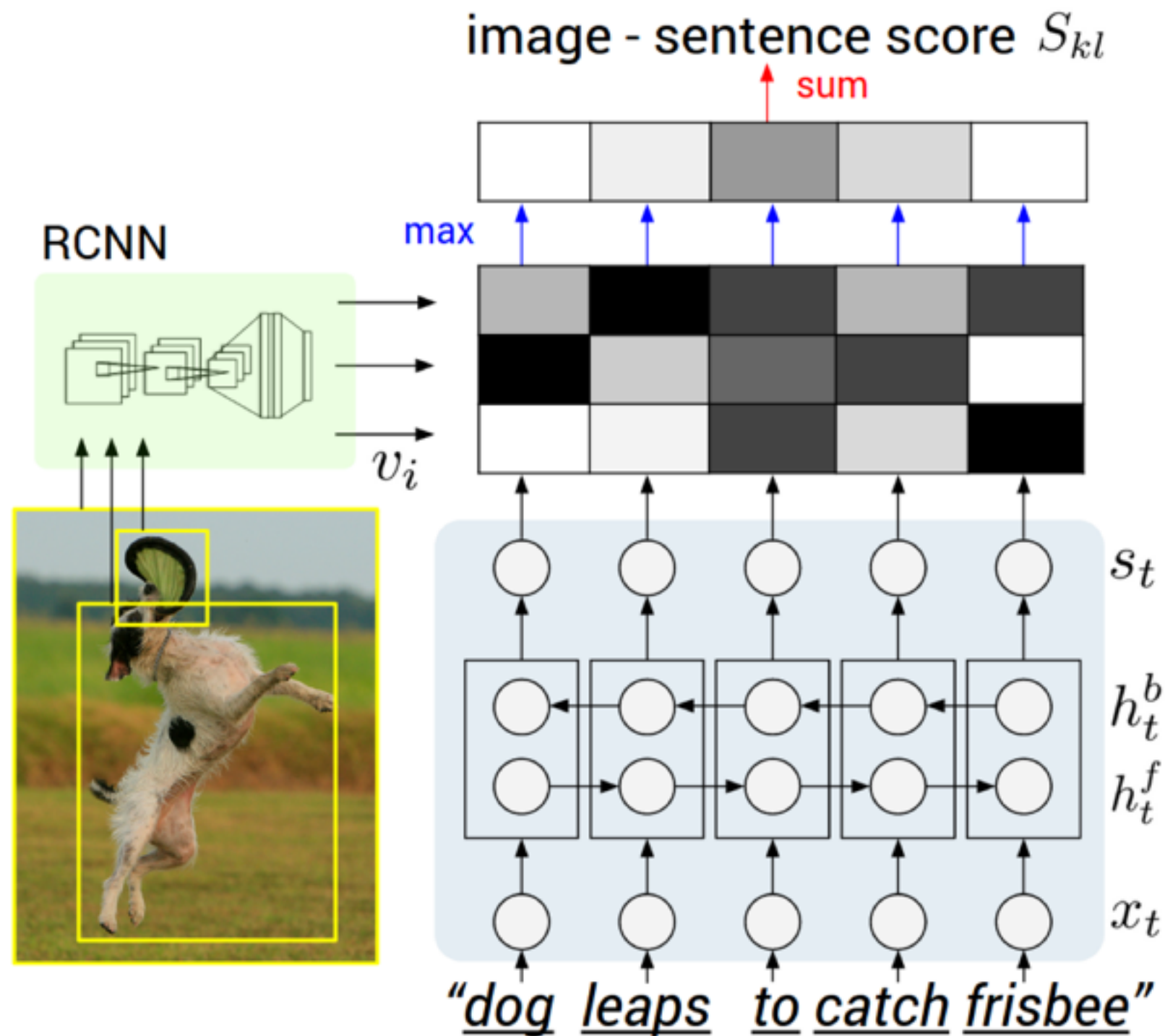
"Tabby cat is sleeping"

"wooden office desk"

"messy pile of documents"

Alignment is here

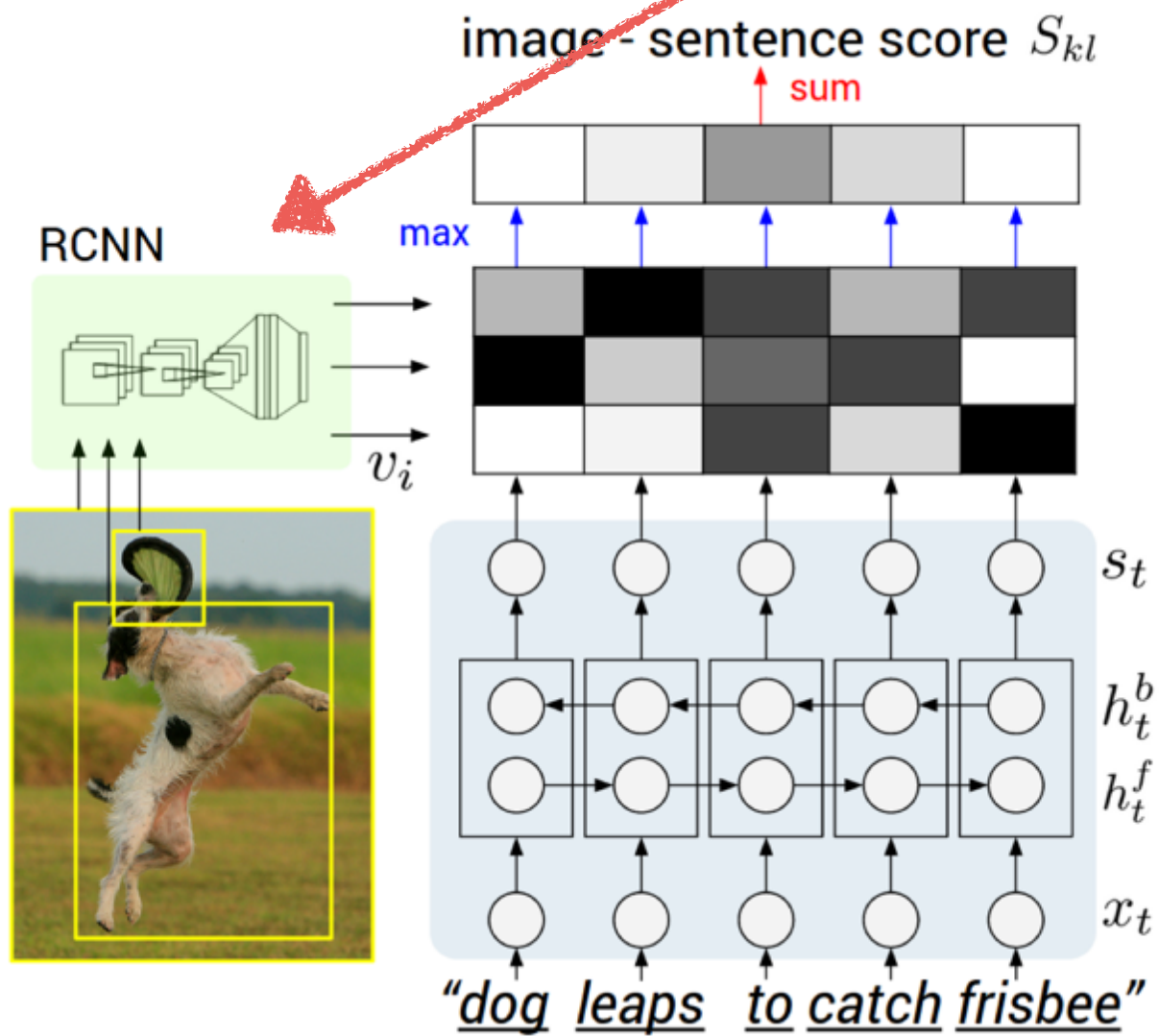
Alignment model



Algorithm

image
embedding

$$v = W_m [CNN_{\theta_c}(I_b)] + b_m$$



Algorithm

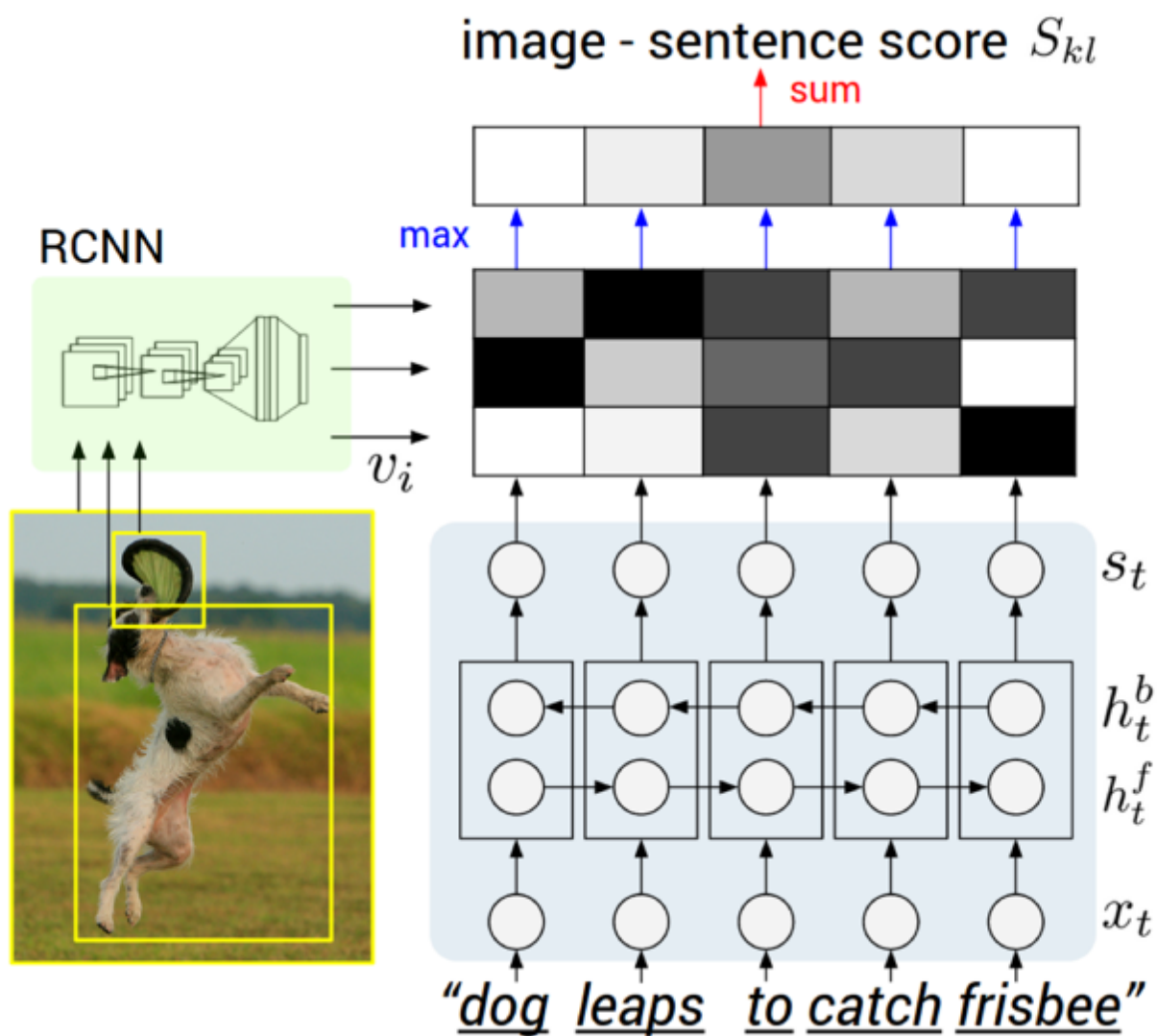
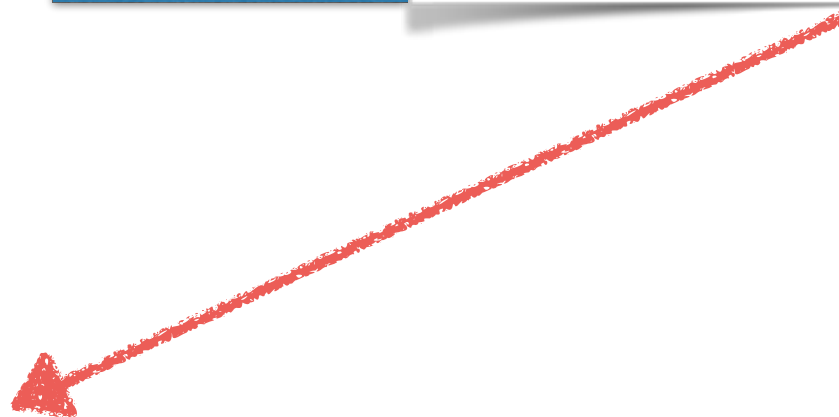


image
embedding

$$v = W_m [CNN_{\theta_c}(I_b)] + b_m$$

word
embedding

$$\begin{aligned} x_t &= W_w \mathbb{I}_t \\ e_t &= f(W_e x_t + b_e) \\ h_t^f &= f(e_t + W_f h_{t-1}^f + b_f) \\ h_t^b &= f(e_t + W_b h_{t+1}^b + b_b) \\ s_t &= f(W_d(h_t^f + h_t^b) + b_d). \end{aligned}$$

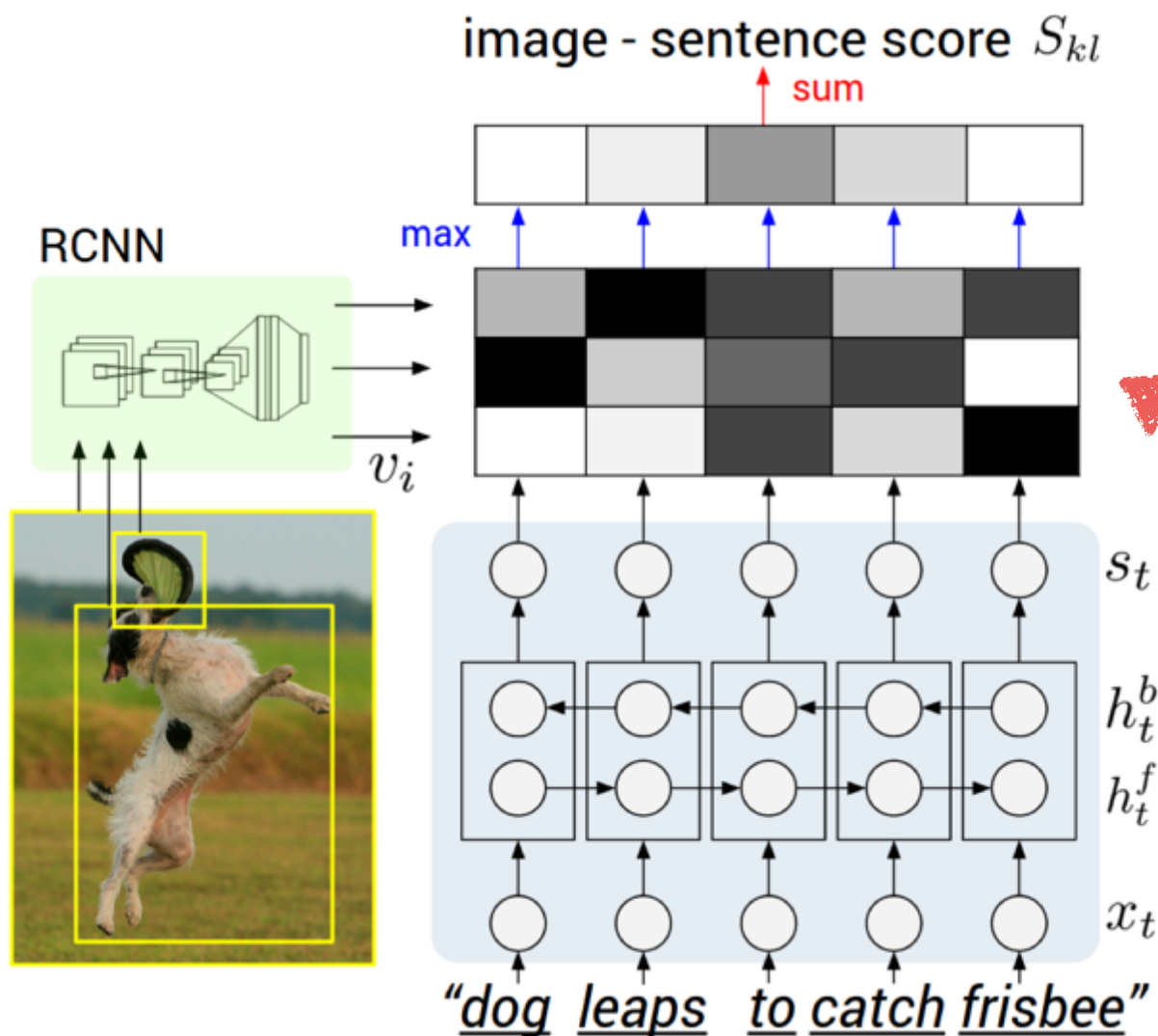


Algorithm

image
embedding

$$v = W_m [CNN_{\theta_c}(I_b)] + b_m$$

$$S_{kl} = \sum_{t \in g_l} \max_{i \in g_k} v_i^T s_t.$$



word
embedding

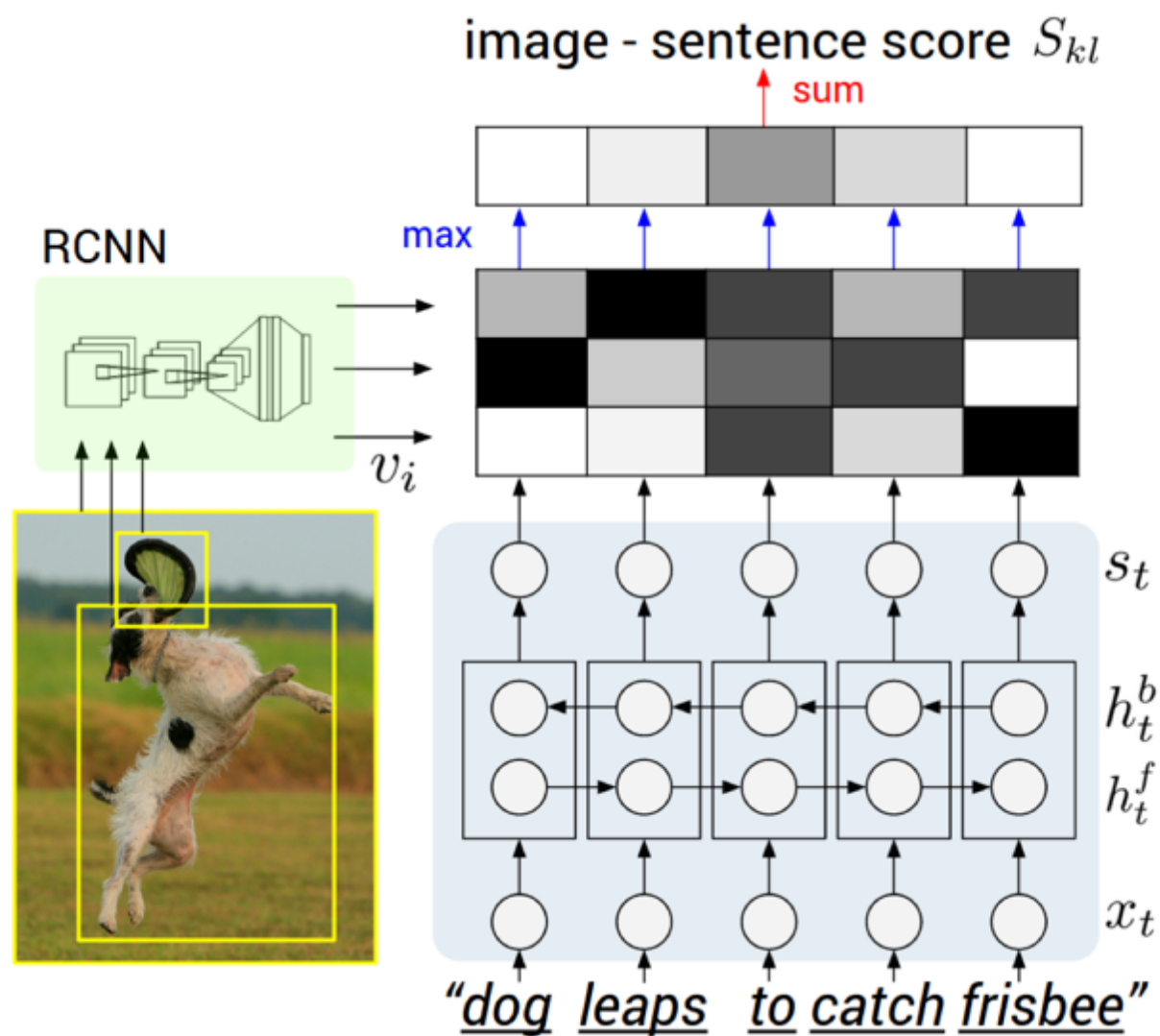
$$\begin{aligned} x_t &= W_w \mathbb{I}_t \\ e_t &= f(W_e x_t + b_e) \\ h_t^f &= f(e_t + W_f h_{t-1}^f + b_f) \\ h_t^b &= f(e_t + W_b h_{t+1}^b + b_b) \\ s_t &= f(W_d (h_t^f + h_t^b) + b_d). \end{aligned}$$

alignment
objective

$$\begin{aligned} \mathcal{C}(\theta) = \sum_k & \left[\underbrace{\sum_l \max(0, S_{kl} - S_{kk} + 1)}_{\text{rank images}} \right. \\ & \left. + \underbrace{\sum_l \max(0, S_{lk} - S_{kk} + 1)}_{\text{rank sentences}} \right]. \end{aligned}$$

A **ranking model** that makes similarity scores of **matching** pairs **higher** than those of **mis-matches**.

Algorithm



Encourage neighbour words to align to the same region.

image embedding

$$v = W_m [CNN_{\theta_c}(I_b)] + b_m$$

word embedding

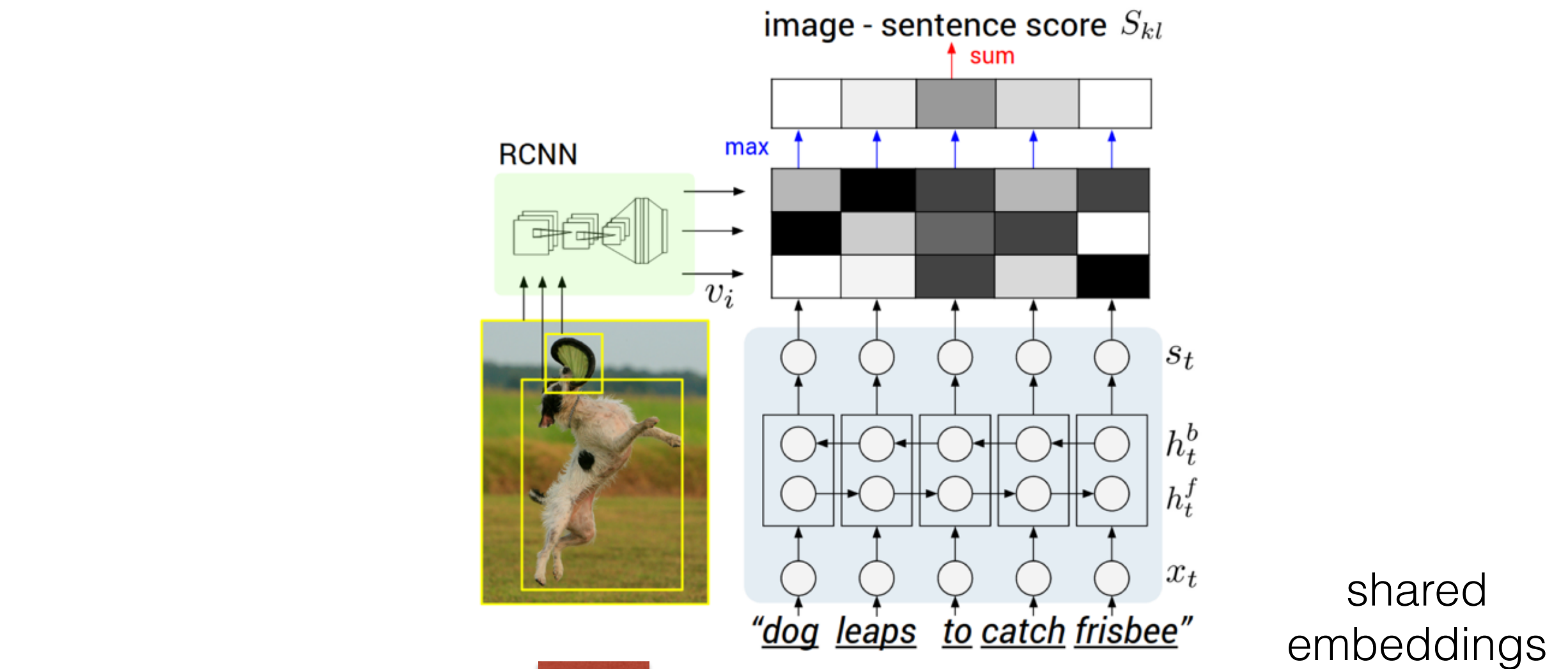
$$\begin{aligned} x_t &= W_w \mathbb{I}_t \\ e_t &= f(W_e x_t + b_e) \\ h_t^f &= f(e_t + W_f h_{t-1}^f + b_f) \\ h_t^b &= f(e_t + W_b h_{t+1}^b + b_b) \\ s_t &= f(W_d (h_t^f + h_t^b) + b_d). \end{aligned}$$

alignment objective

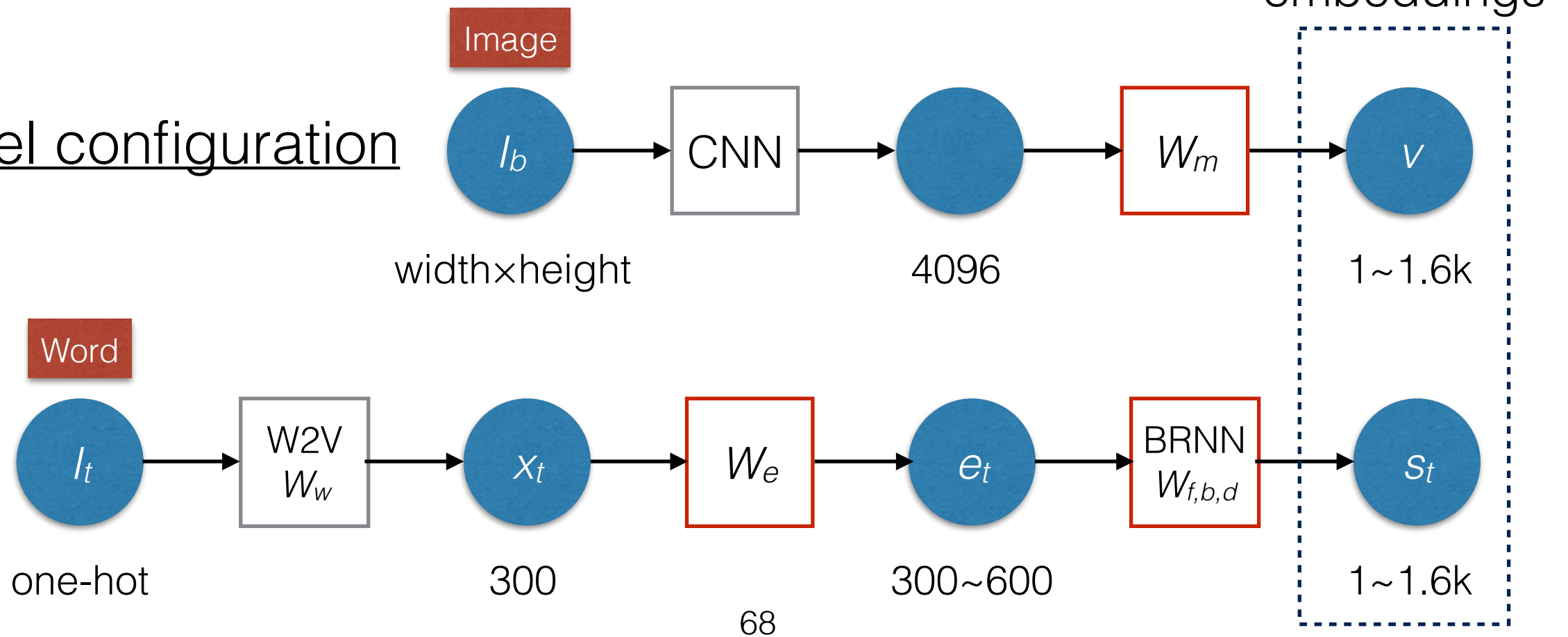
$$\begin{aligned} \mathcal{C}(\theta) = \sum_k & \left[\underbrace{\sum_l \max(0, S_{kl} - S_{kk} + 1)}_{\text{rank images}} \right. \\ & \left. + \underbrace{\sum_l \max(0, S_{lk} - S_{kk} + 1)}_{\text{rank sentences}} \right]. \end{aligned}$$

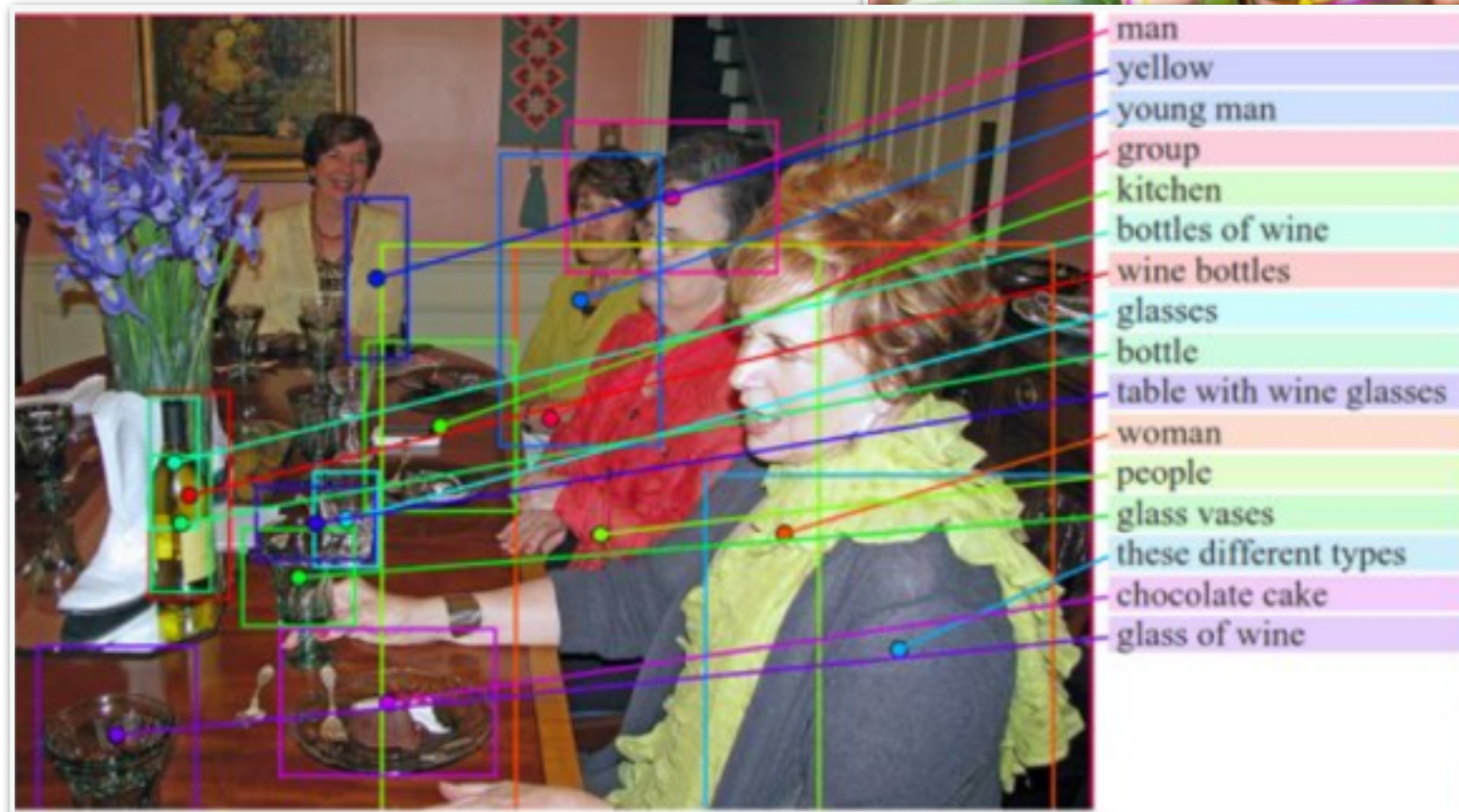
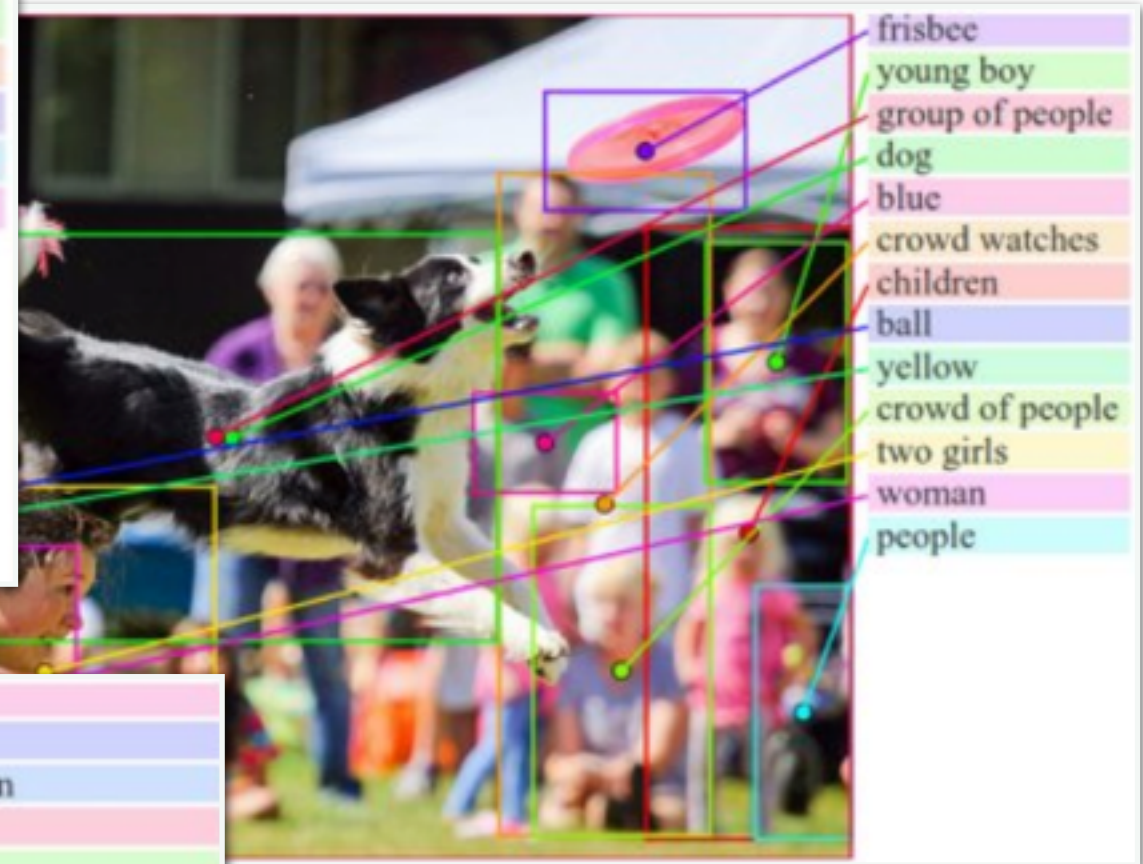
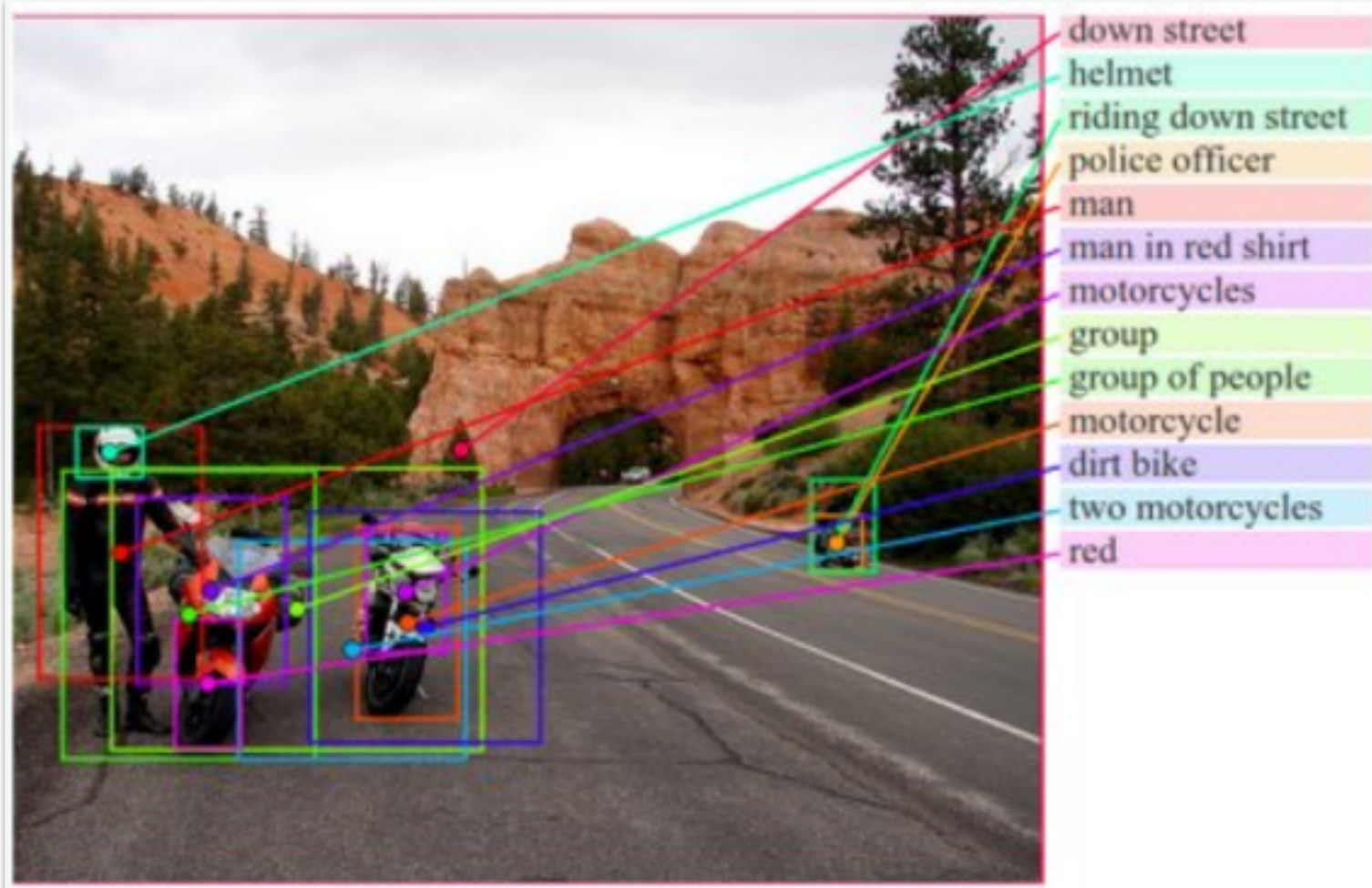
$$\begin{aligned} E(\mathbf{a}) &= \sum_{j=1 \dots N} \psi_j^U(a_j) + \sum_{j=1 \dots N-1} \psi_j^B(a_j, a_{j+1}) \\ \psi_j^U(a_j = t) &= v_i^T s_t \\ \psi_j^B(a_j, a_{j+1}) &= \beta \mathbb{1}[a_j = a_{j+1}]. \end{aligned}$$

MRF in decoding



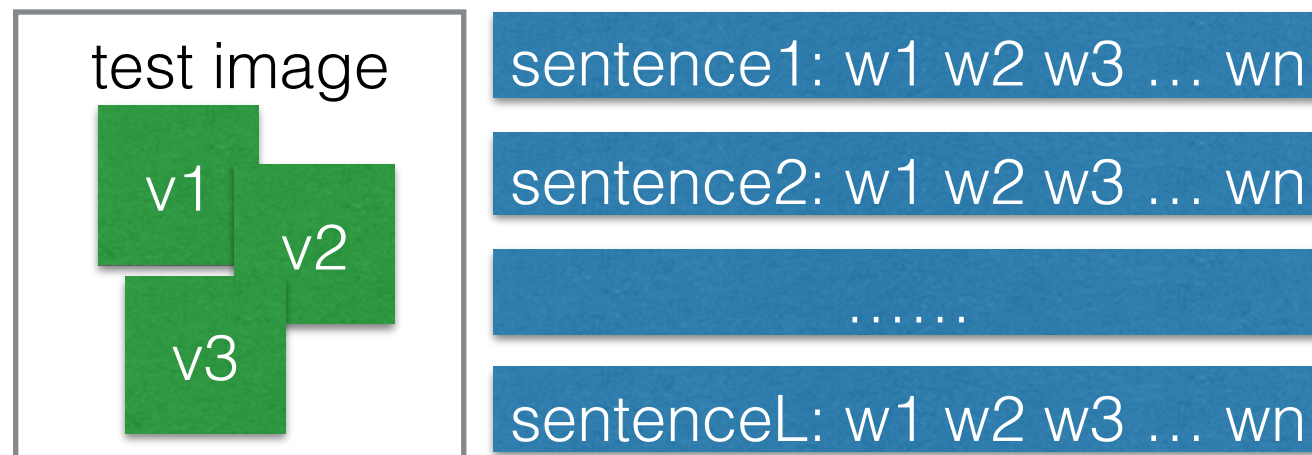
Model configuration



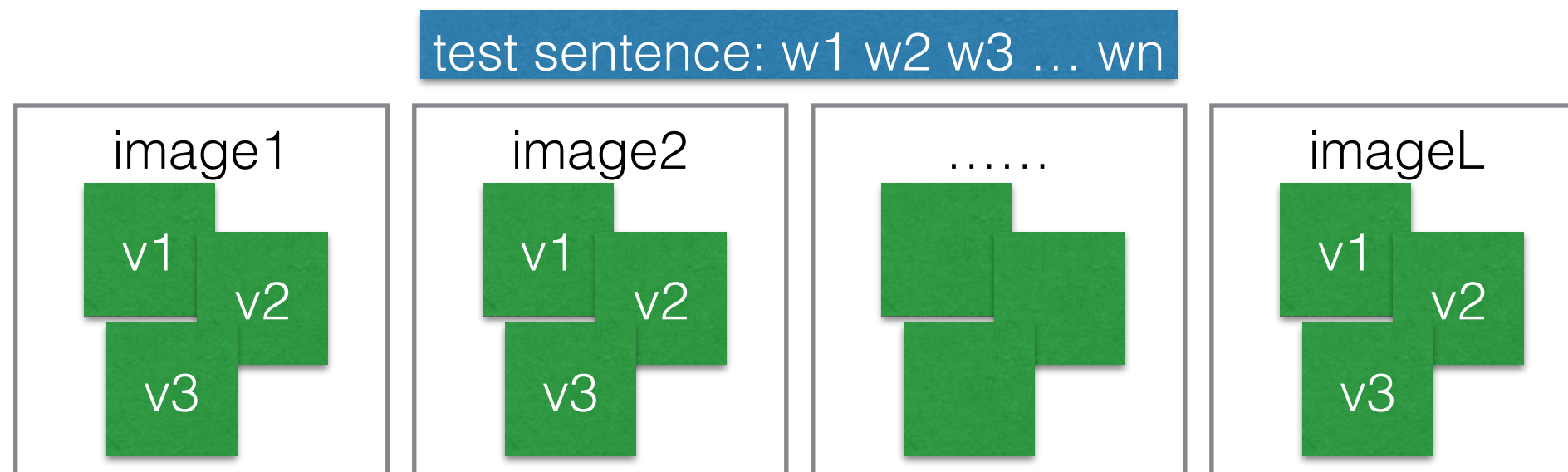


Evaluation - Alignment

- Image annotation



- Image search



Evaluation - Alignment

Model	Image Annotation				Image Search			
	R@1	R@5	R@10	Med r	R@1	R@5	R@10	Med r
Flickr8K								
DeViSE (Frome et al. [10])	4.5	18.1	29.2	26	6.7	21.9	32.7	25
SDT-RNN (Socher et al. [42])	9.6	29.8	41.1	16	8.9	29.8	41.1	16
Kiros et al. [19]	13.5	36.2	45.7	13	10.4	31.0	43.7	14
Mao et al. [31]	14.5	37.2	48.5	11	11.5	31.0	42.4	15
DeFrag (Karpathy et al. [18])	12.6	32.9	44.0	14	9.7	29.6	42.5	15
Our implementation of DeFrag [18]	13.8	35.8	48.2	10.4	9.5	28.2	40.3	15.6
Our model: DepTree edges	14.8	37.9	50.0	9.4	11.6	31.4	43.8	13.2
Our model: BRNN	16.5	40.6	54.2	7.6	11.8	32.1	44.7	12.4
Flickr30K								
DeViSE (Frome et al. [10])	4.5	18.1	29.2	26	6.7	21.9	32.7	25
SDT-RNN (Socher et al. [42])	9.6	29.8	41.1	16	8.9	29.8	41.1	16
Kiros et al. [19]	14.8	39.2	50.9	10	11.8	34.0	46.3	13
Mao et al. [31]	18.4	40.2	50.9	10	12.6	31.2	41.5	16
DeFrag (Karpathy et al. [18])	14.2	37.7	51.3	10	10.2	30.8	44.2	14
Our implementation of DeFrag [18]	19.2	44.5	58.0	6.0	12.9	35.4	47.5	10.8
Our model: DepTree edges	20.0	46.6	59.4	5.4	15.0	36.5	48.2	10.4
Our model: BRNN	22.2	48.2	61.4	4.8	15.2	37.7	50.5	9.2
MSCOCO								
Our model: 1K test images	29.4	62.0	75.9	2.5	20.9	52.8	69.2	4.0
Our model: 5K test images	11.8	32.5	45.4	12.2	8.9	24.9	36.3	19.5

Evaluation - Translation

	Flickr8K				Flickr30K				MSCOCO			
Method of generating text	\mathcal{PPL}	B-1	B-2	B-3	\mathcal{PPL}	B-1	B-2	B-3	\mathcal{PPL}	B-1	B-2	B-3
4 sentence references												
Human agreement	-	0.63	0.40	0.21	-	0.69	0.45	0.23	-	0.63	0.41	0.22
Ranking: Nearest Neighbor	-	0.29	0.11	0.03	-	0.27	0.08	0.02	-	0.32	0.11	0.03
Generating: RNN	-	0.42	0.19	0.06	-	0.45	0.20	0.06	-	0.50	0.25	0.12
Generating: RNN (OxfordNet CNN [40])	-	0.49	0.28	0.11	-	0.49	0.28	0.12	-	0.54	0.34	0.16
5 sentence references												
Generating: RNN	-	0.45	0.21	0.09	-	0.47	0.21	0.09	-	0.53	0.28	0.15
Mao et al. [31]	24.39	0.58	0.28	0.23	35.11	0.55	0.24	0.20	-	-	-	-
Generating: RNN (OxfordNet CNN [40])	22.66	0.51	0.31	0.12	21.20	0.50	0.30	0.15	19.64	0.57	0.37	0.19

	Flickr8K				Flickr30K				MSCOCO			
Method of generating text	\mathcal{PPL}	B-1	B-2	B-3	\mathcal{PPL}	B-1	B-2	B-3	\mathcal{PPL}	B-1	B-2	B-3
Vanilla RNN	22.66	0.51	0.31	0.12	21.20	0.50	0.30	0.15	19.64	0.57	0.37	0.19
LSTM	15.47	0.53	0.34	0.17	18.92	0.52	0.32	0.15	13.96	0.60	0.40	0.21

Method of generating text	B-1	B-2	B-3
Human agreement	0.54	0.33	0.16
Ranking: Nearest Neighbor	0.14	0.03	0.07
Generating: Full frame model	0.12	0.03	0.01
Generating: Region level model	0.17	0.05	0.01

Reference

- Karpathy, A. & Fei-Fei, L., 2014. Deep Visual-Semantic Alignments for Generating Image Descriptions. arXiv.org, cs.CV.
- Vinyals, O. et al., 2014. Show and Tell: A Neural Image Caption Generator. arXiv.org, cs.CV.